

# Fast and Flexible Program Optimization with E-Graphs

Anjali Pal

```
x = input()
y = abs(x) * 2
if x > 0:
    y = y + abs(x) - x
    z = foo(x, y)
else:
    y = y + abs(x) + x
    z = bar(x, y)
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x = input()
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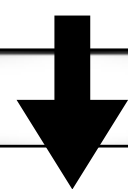
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x = input()
y = abs(x) * 2
y = y + abs(x)
if x > 0:
    z = foo(x, y)
else:
    z = bar(x, y)
```

```
x = input()
y = abs(x) * 3
if x > 0:
    z = foo(x, y)
else:
    z = bar(x, y)
```

```
x = input()
y = abs(x) * 2
if x > 0:
    y = y + abs(x) - x
    z = foo(x, y)
else:
    y = y + abs(x) + x
    z = bar(x, y)
```



```
x = input()
y = abs(x) * 2
if x > 0:
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```

**Most compilers  
can't do both!**

```
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x = input()
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**(I) Term Rewriting**

**(II) Non-destructive term rewriting using e-graphs**

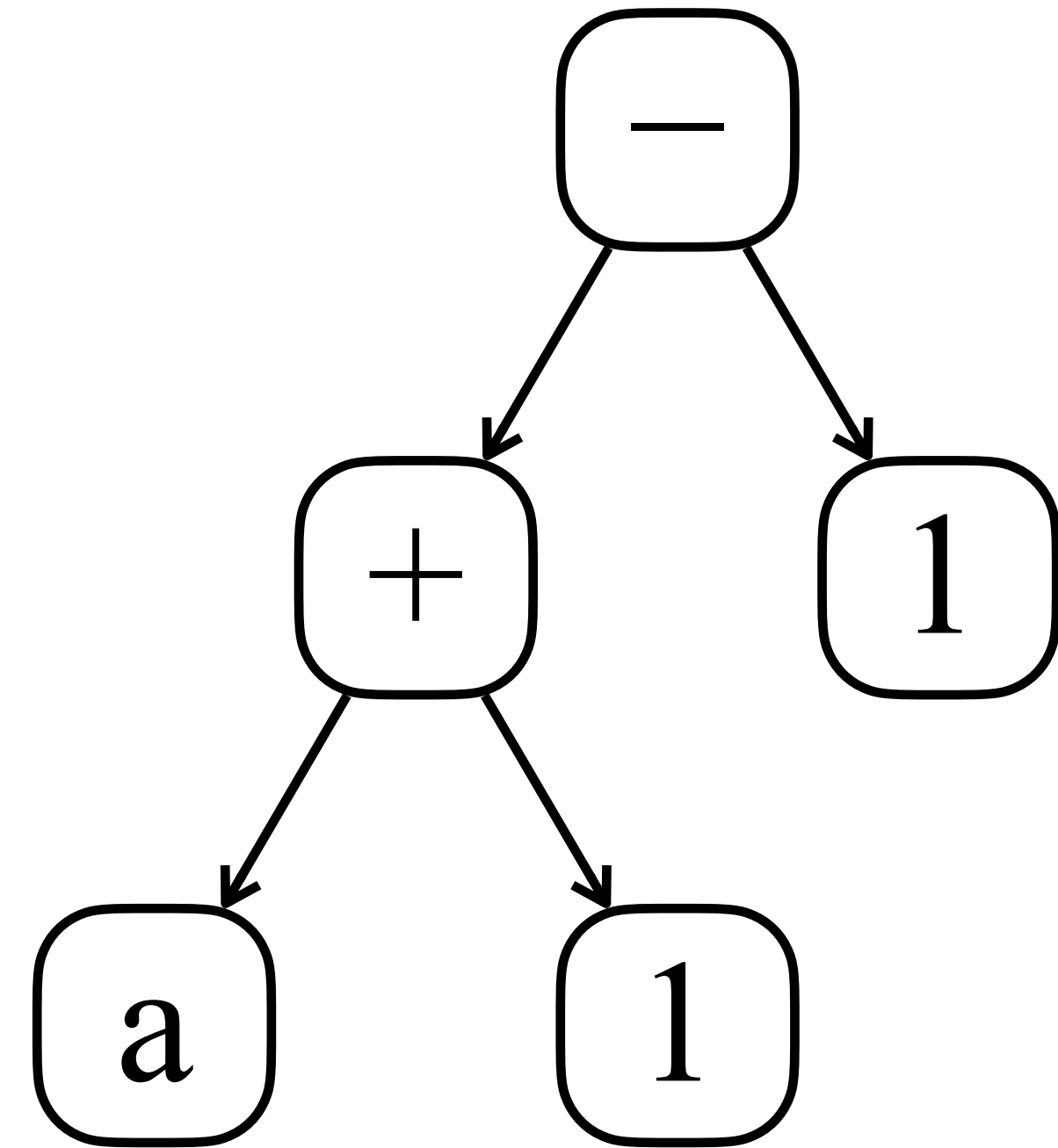
**(III) Extracting optimized terms from e-graphs**

**(IV) Effectful program optimization using e-graphs**

**(V) Effect-safe extraction**

# Program Optimization via Term Rewriting

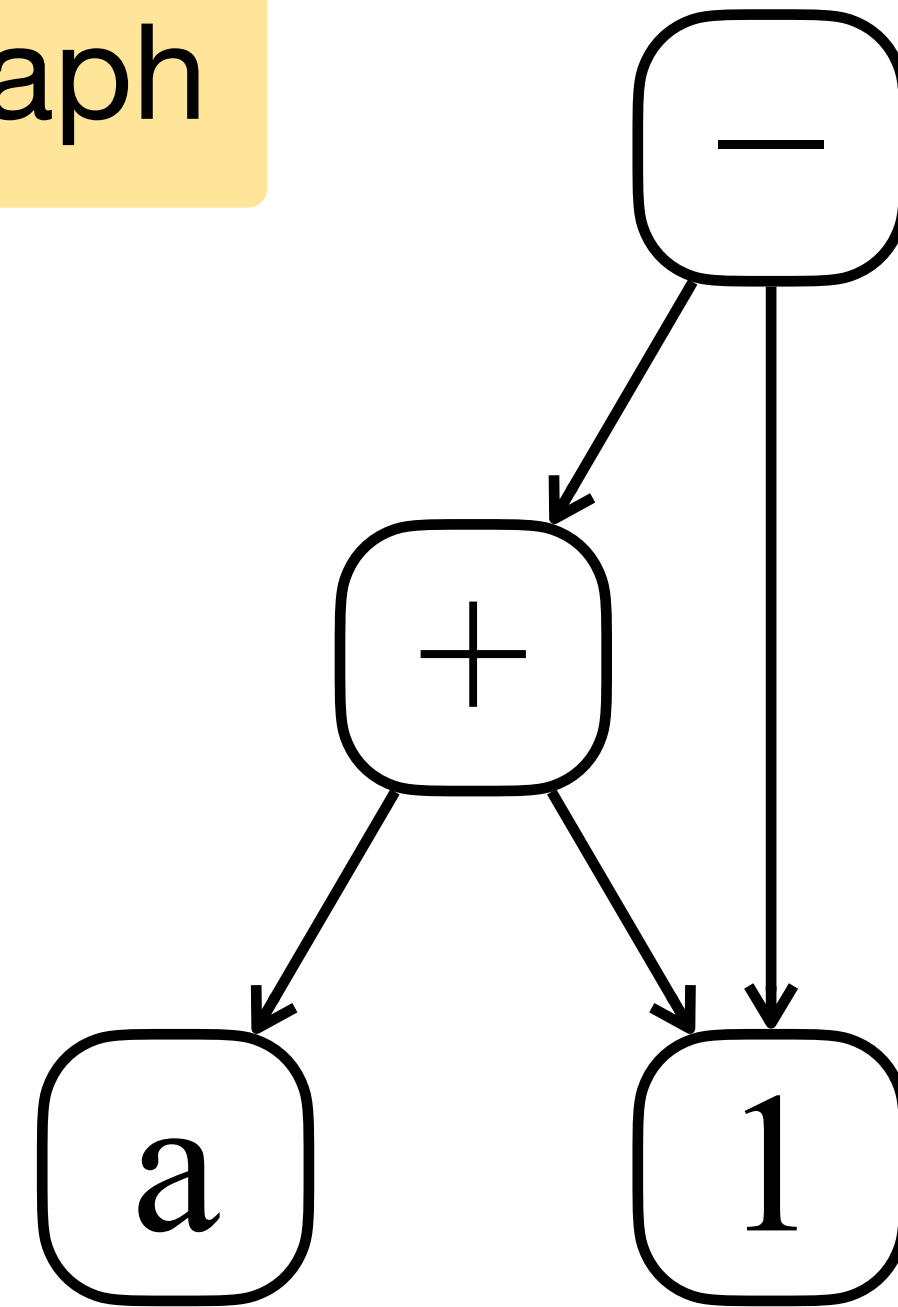
# Programs are trees



$(a + 1) - 1$

# Programs are ~~trees~~ DAGs

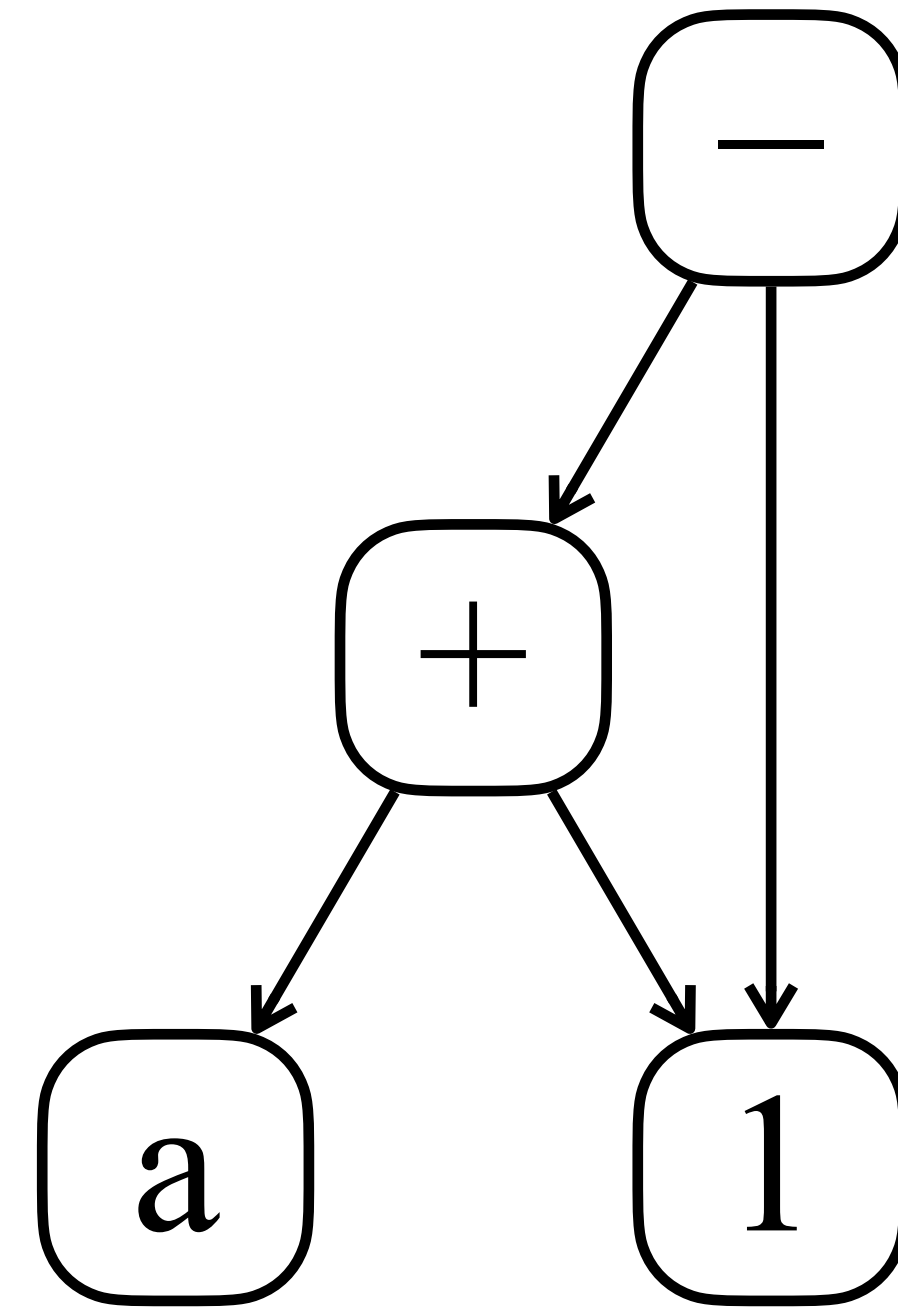
Directed Acyclic Graph



$(a + 1) - 1$

# Syntactic Rewrite Rules

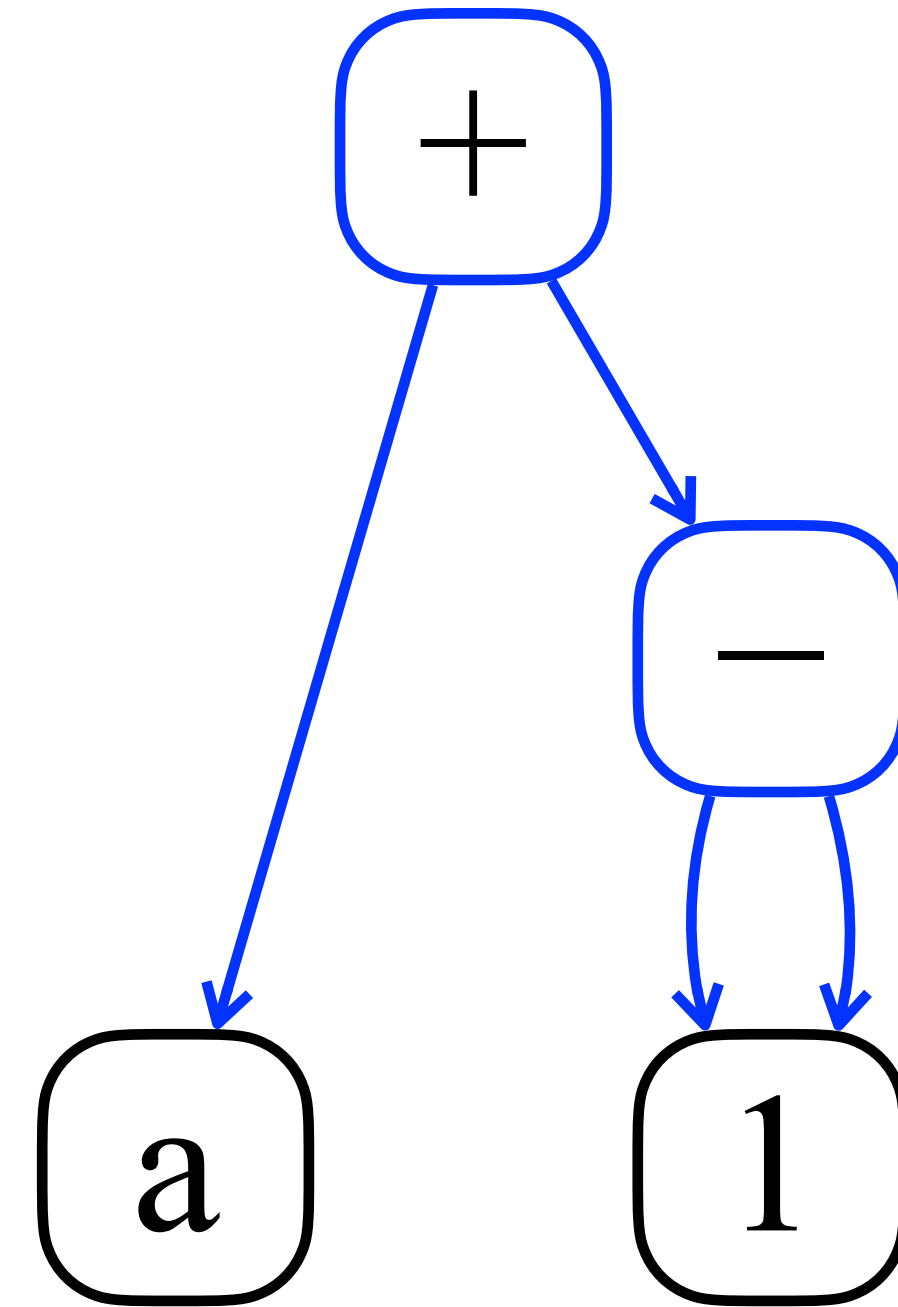
$$(\alpha + \beta) - \gamma \rightsquigarrow \alpha + (\beta - \gamma)$$



$$(a + 1) - 1$$

# Syntactic Rewrite Rules

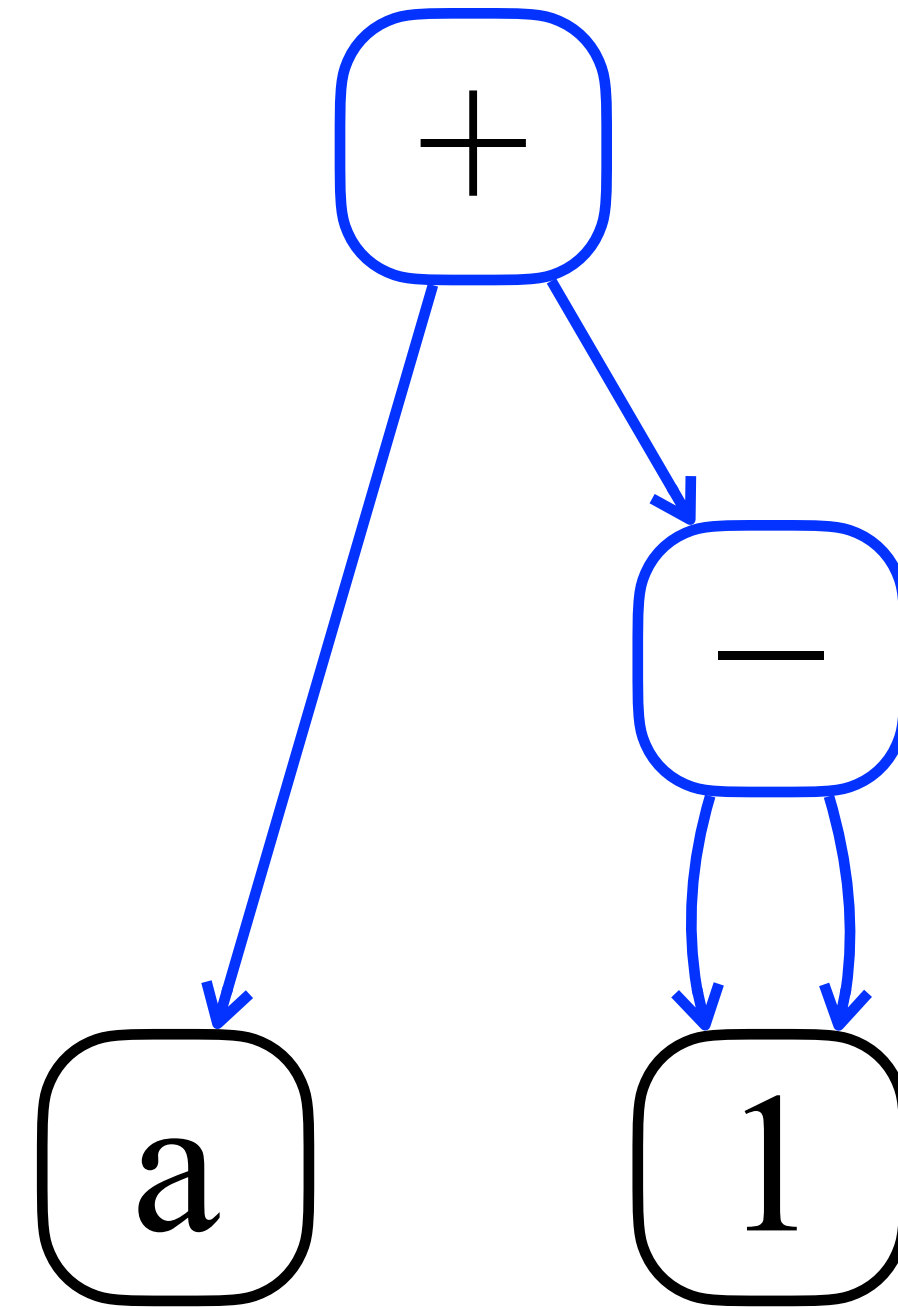
$$(\alpha + \beta) - \gamma \rightsquigarrow \alpha + (\beta - \gamma)$$



$$a + (1 - 1)$$

# Syntactic Rewrite Rules

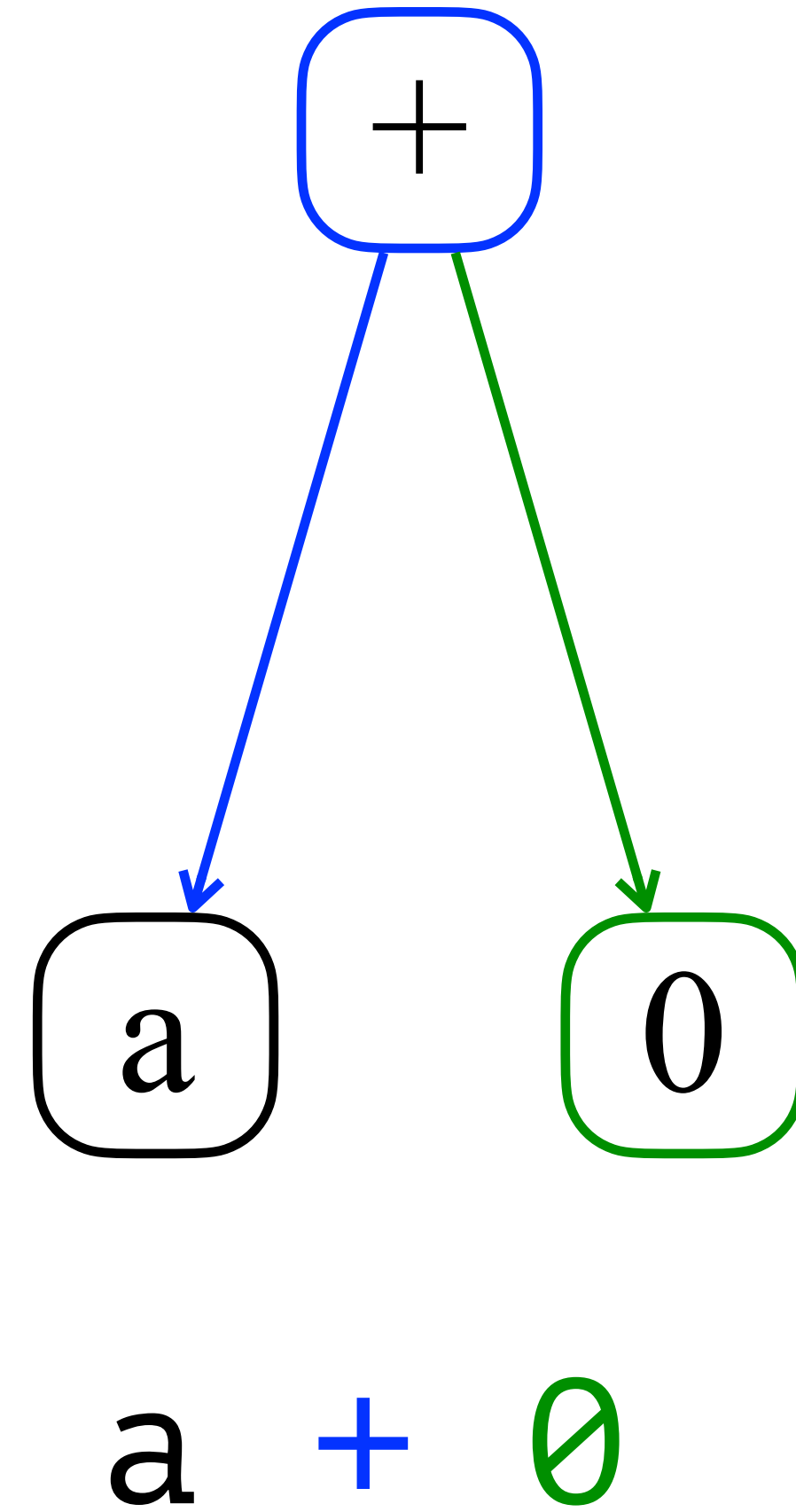
$$a - a \rightsquigarrow 0$$



$a + (1 - 1)$

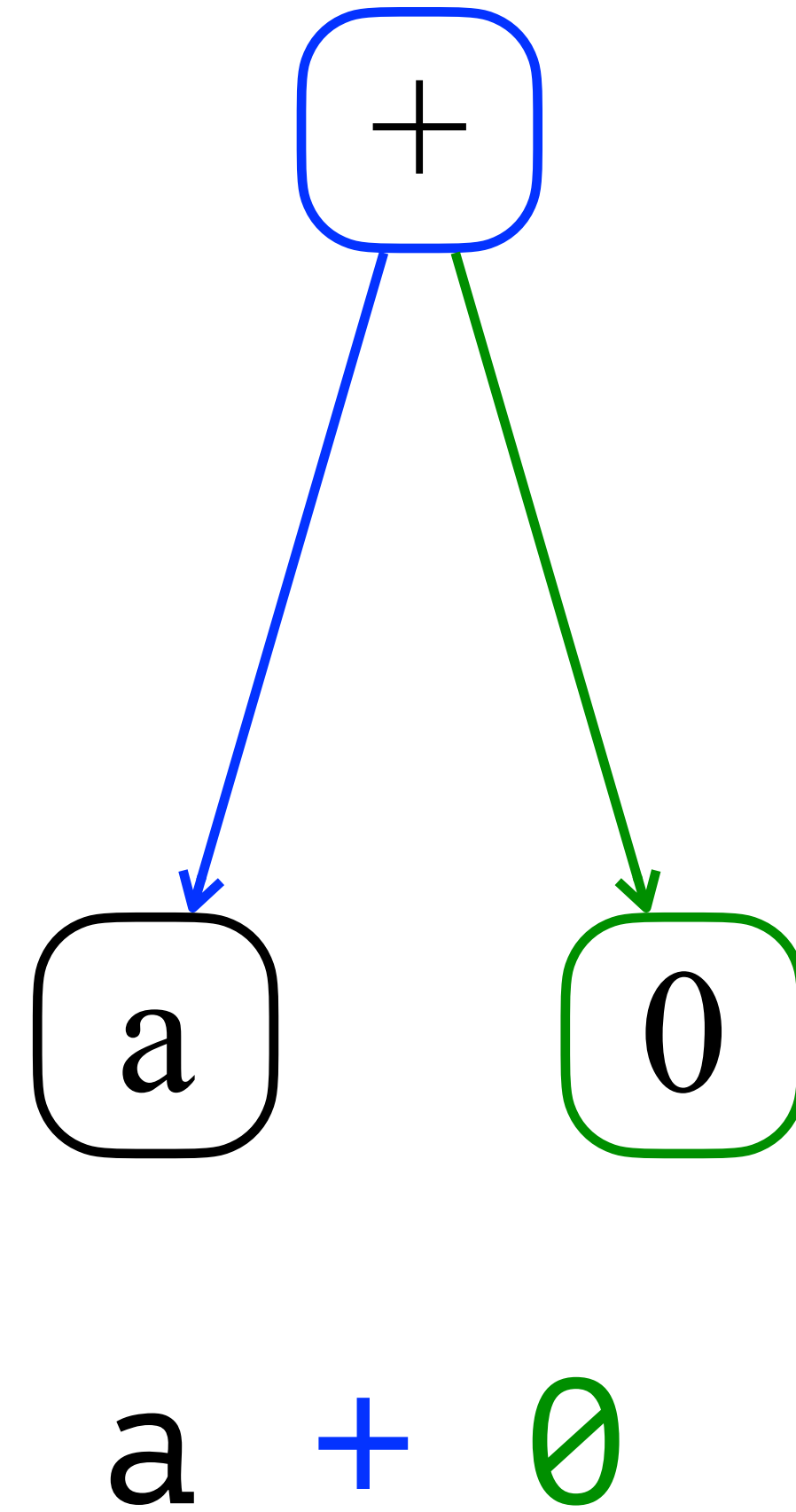
# Syntactic Rewrite Rules

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# Syntactic Rewrite Rules

$$\alpha + 0 \rightsquigarrow \alpha$$



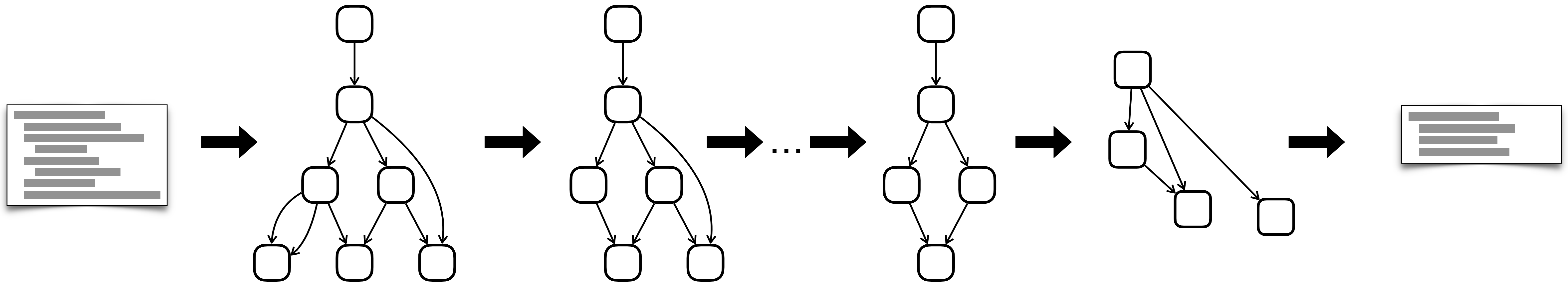
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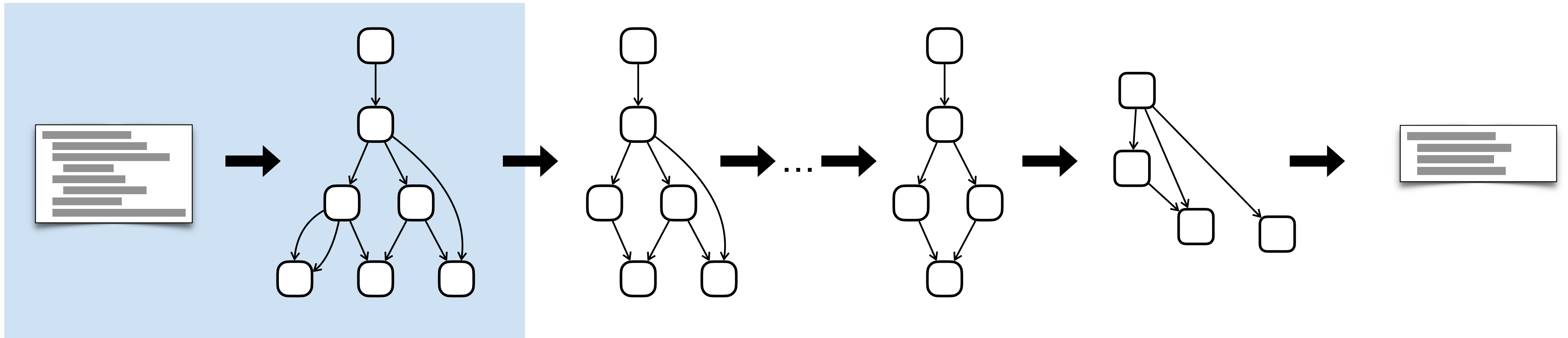
a

a

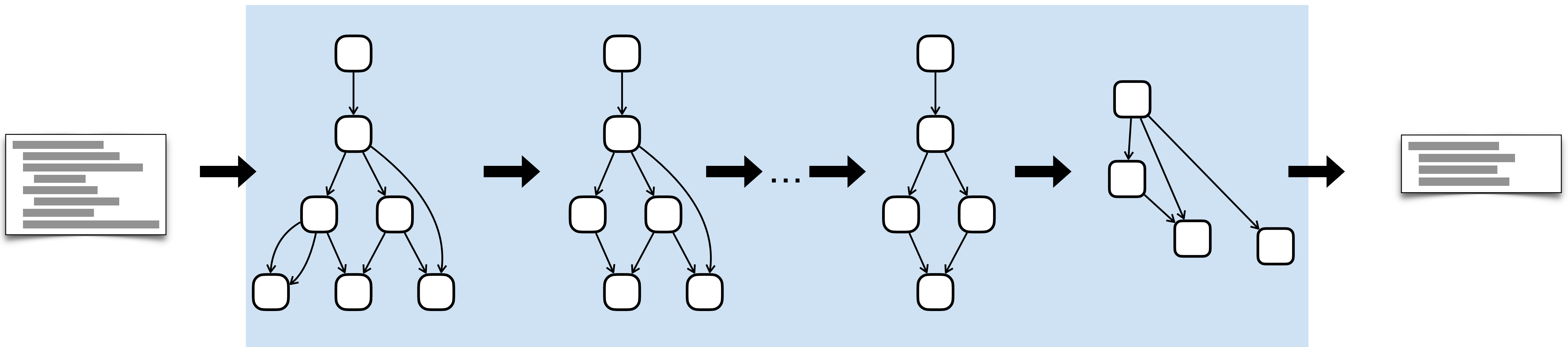
# Program Optimization with Term Rewriting



# Program Optimization with Term Rewriting

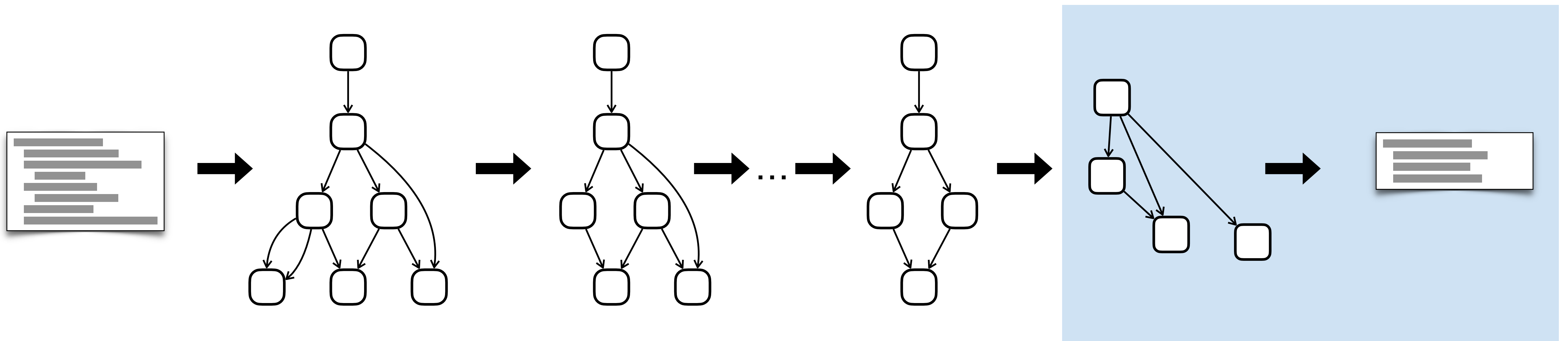


# Program Optimization with Term Rewriting



**Fixed Rule Order**

# Program Optimization with Term Rewriting

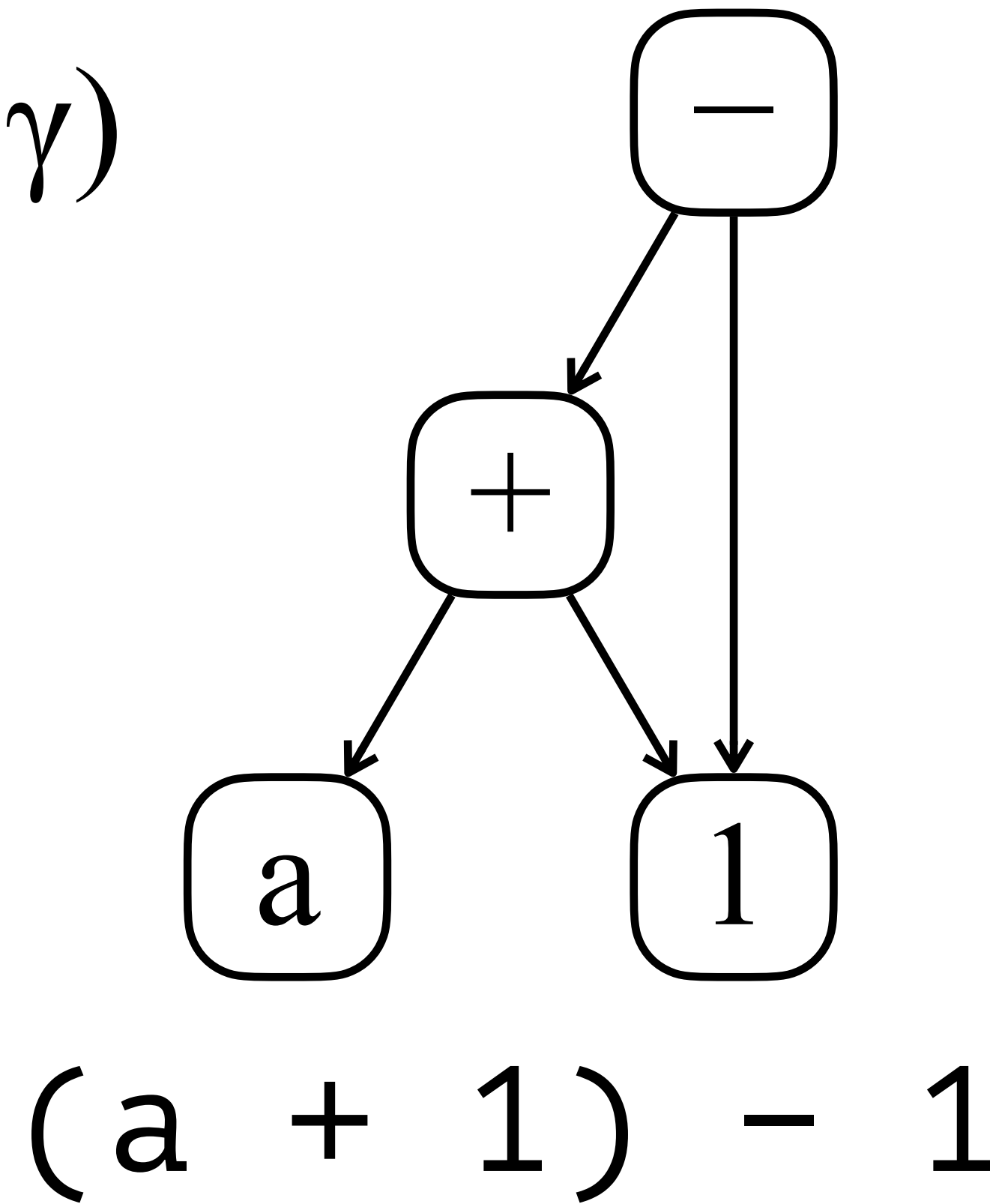


# Phase Ordering Problem

$$1. (\alpha + \beta) - \gamma \rightsquigarrow \alpha + (\beta - \gamma)$$

$$2. \alpha - \alpha \rightsquigarrow 0$$

$$3. \alpha + 0 \rightsquigarrow \alpha$$

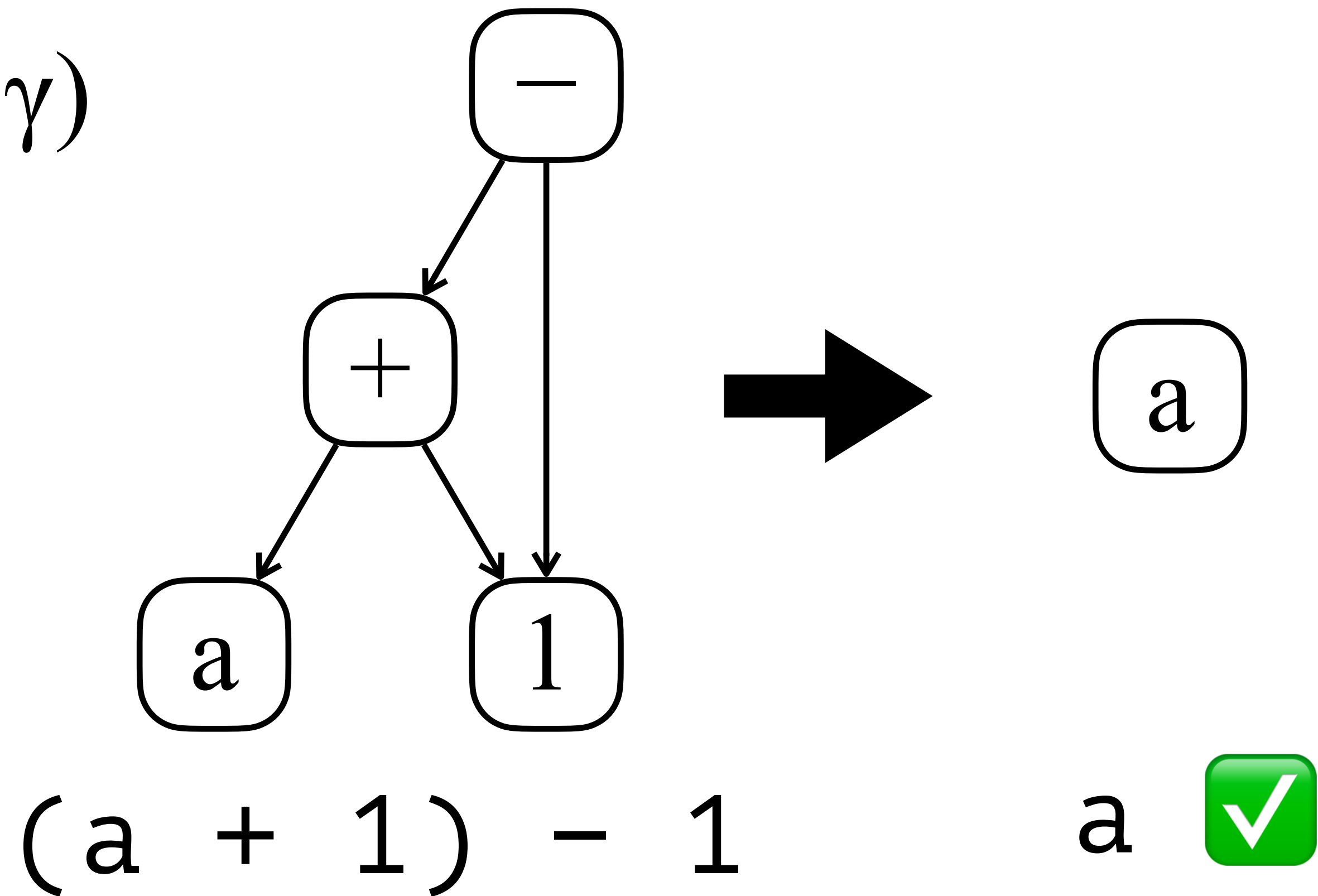


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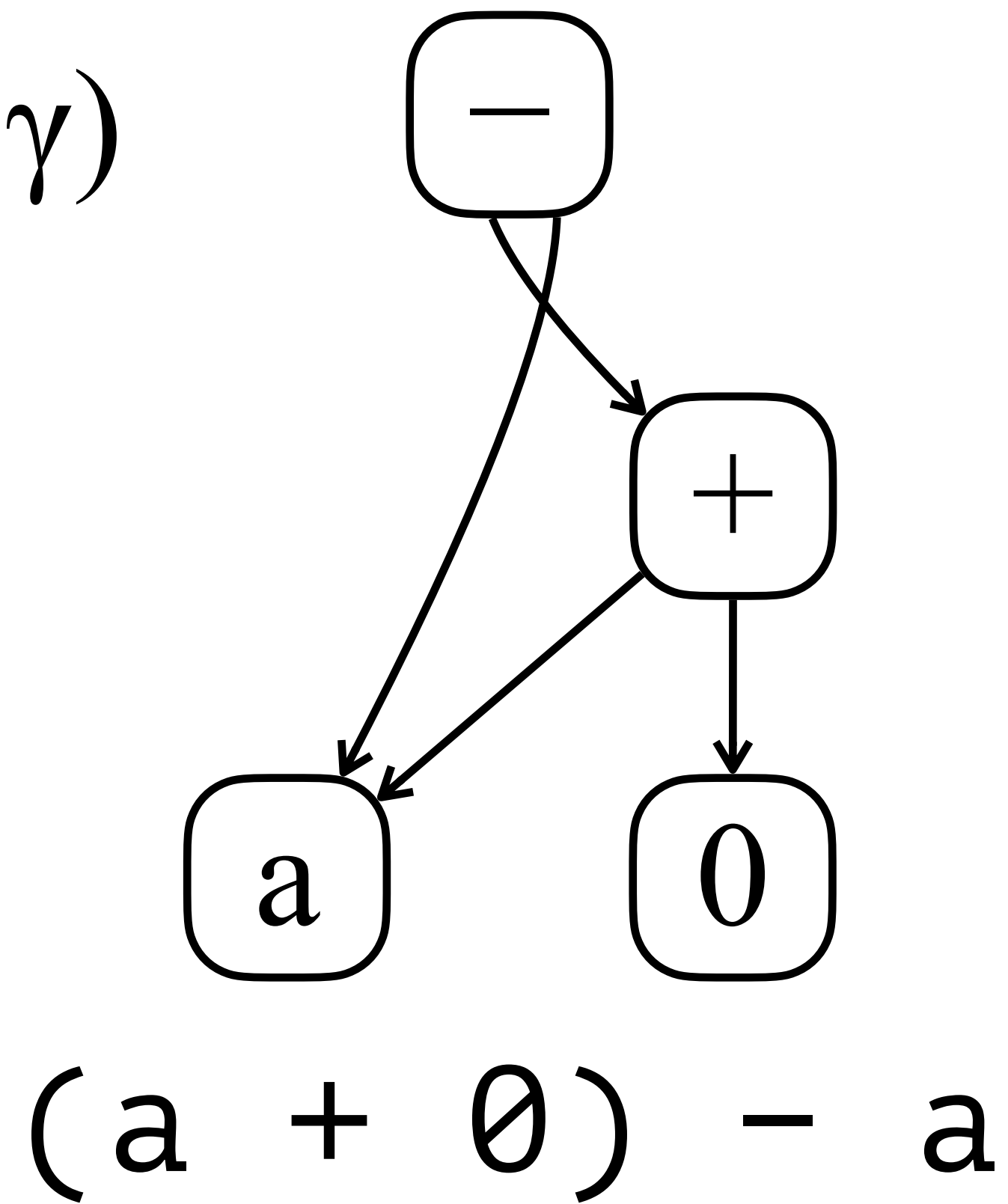


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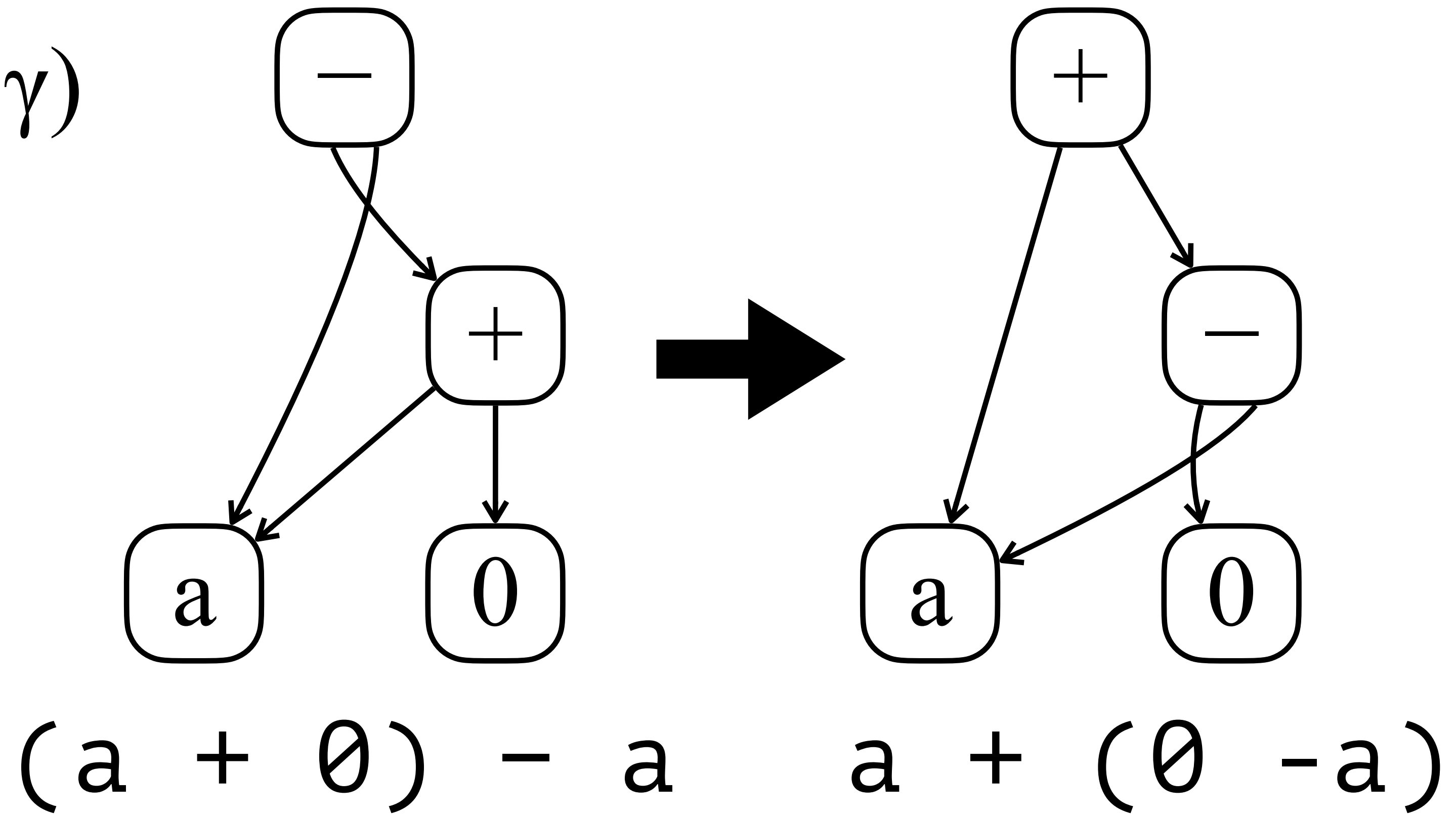


# Phase Ordering Problem

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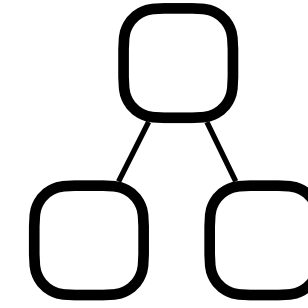
$$3. \alpha + 0 \rightsquigarrow \alpha$$



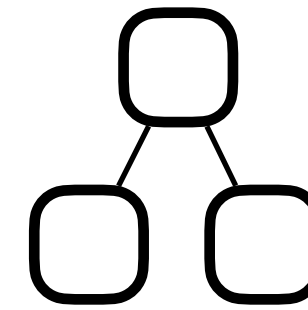
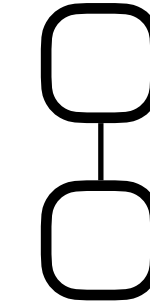
X

**No rule ordering works for all inputs**

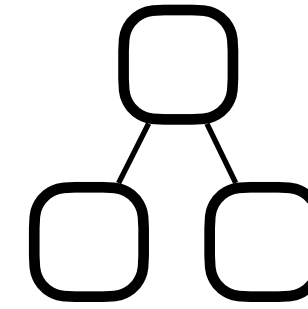
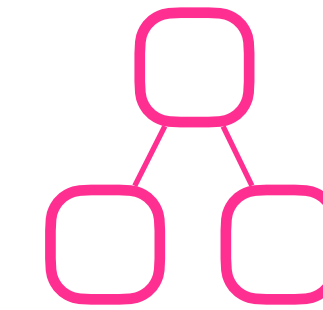
# Try Every Order?



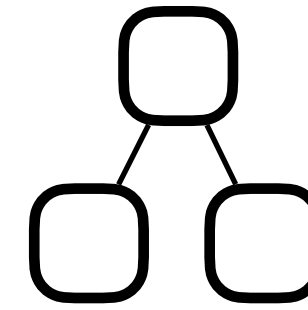
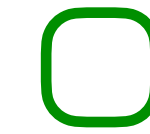
1.  $(\alpha + \beta) - \gamma \rightsquigarrow \alpha + (\beta - \gamma)$
2.  $\alpha - \alpha \rightsquigarrow 0$
3.  $\alpha + 0 \rightsquigarrow \alpha$



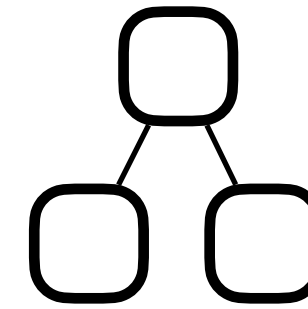
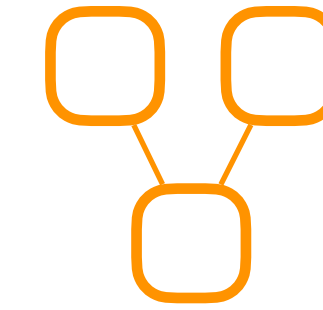
1.  $\alpha - \alpha \rightsquigarrow 0$
2.  $\alpha + 0 \rightsquigarrow \alpha$
3.  $(\alpha + \beta) - \gamma \rightsquigarrow \alpha + (\beta - \gamma)$



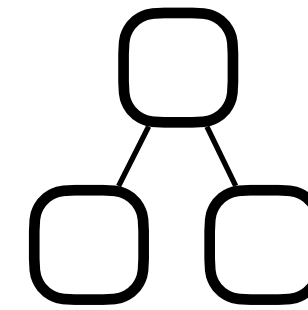
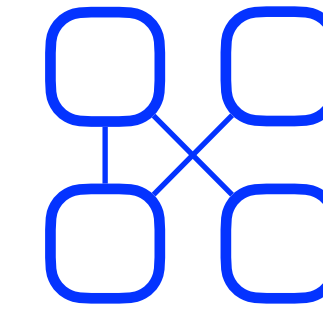
1.  $\alpha + 0 \rightsquigarrow \alpha$
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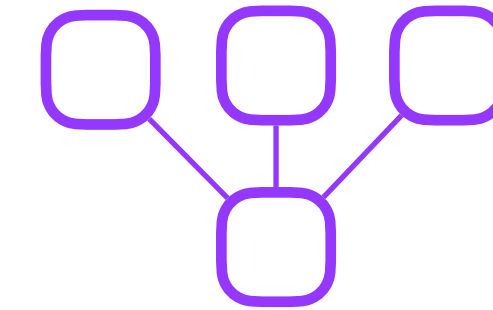
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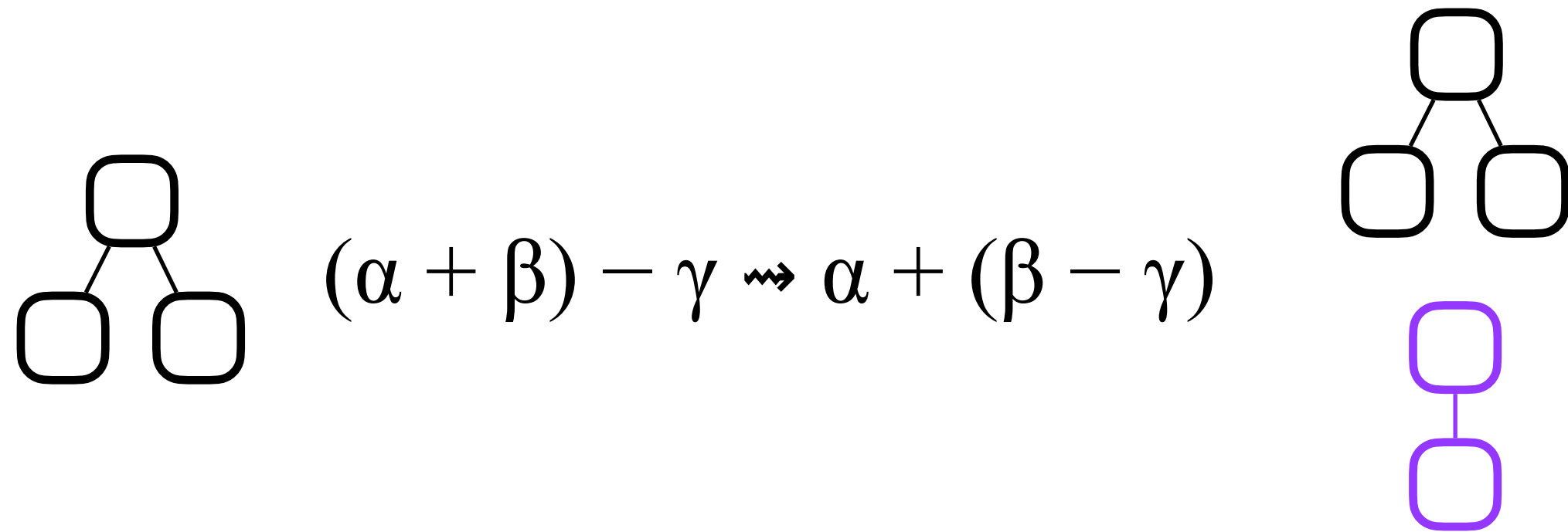


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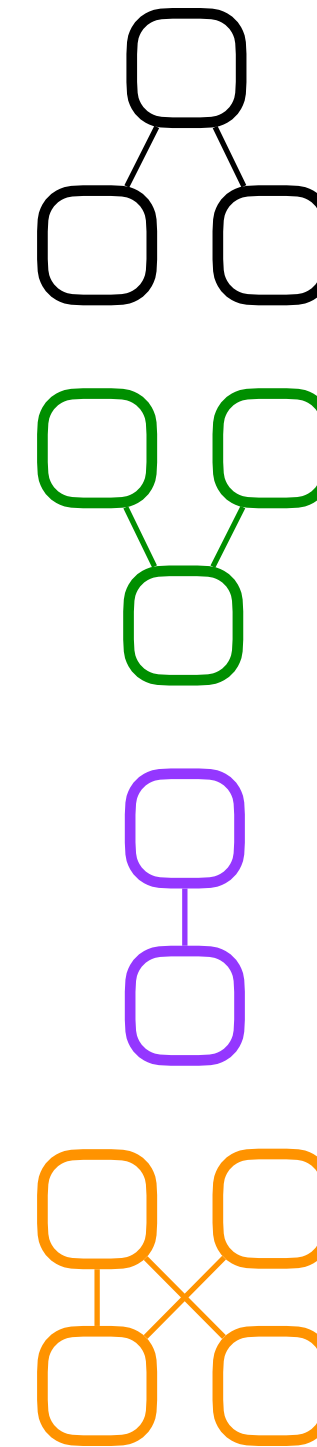


Too much time **X**

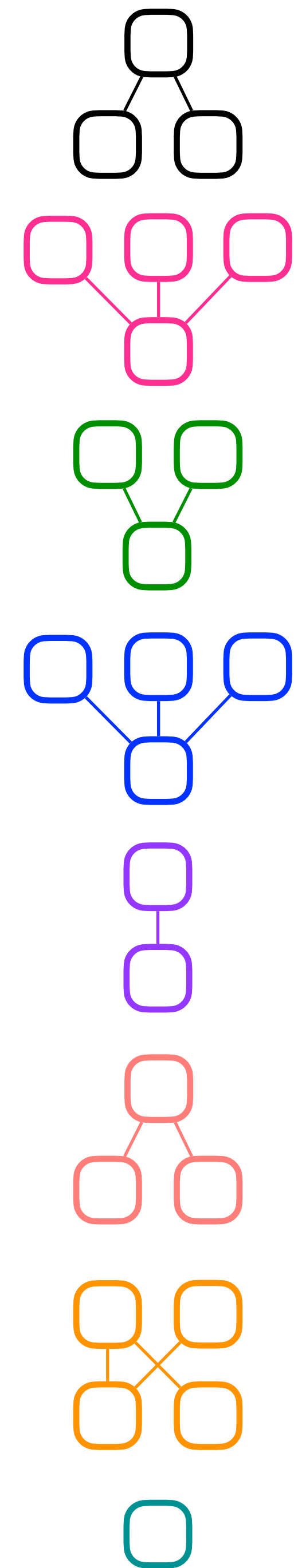
# Keep Every Term?



$\alpha + 0 \rightsquigarrow \alpha$

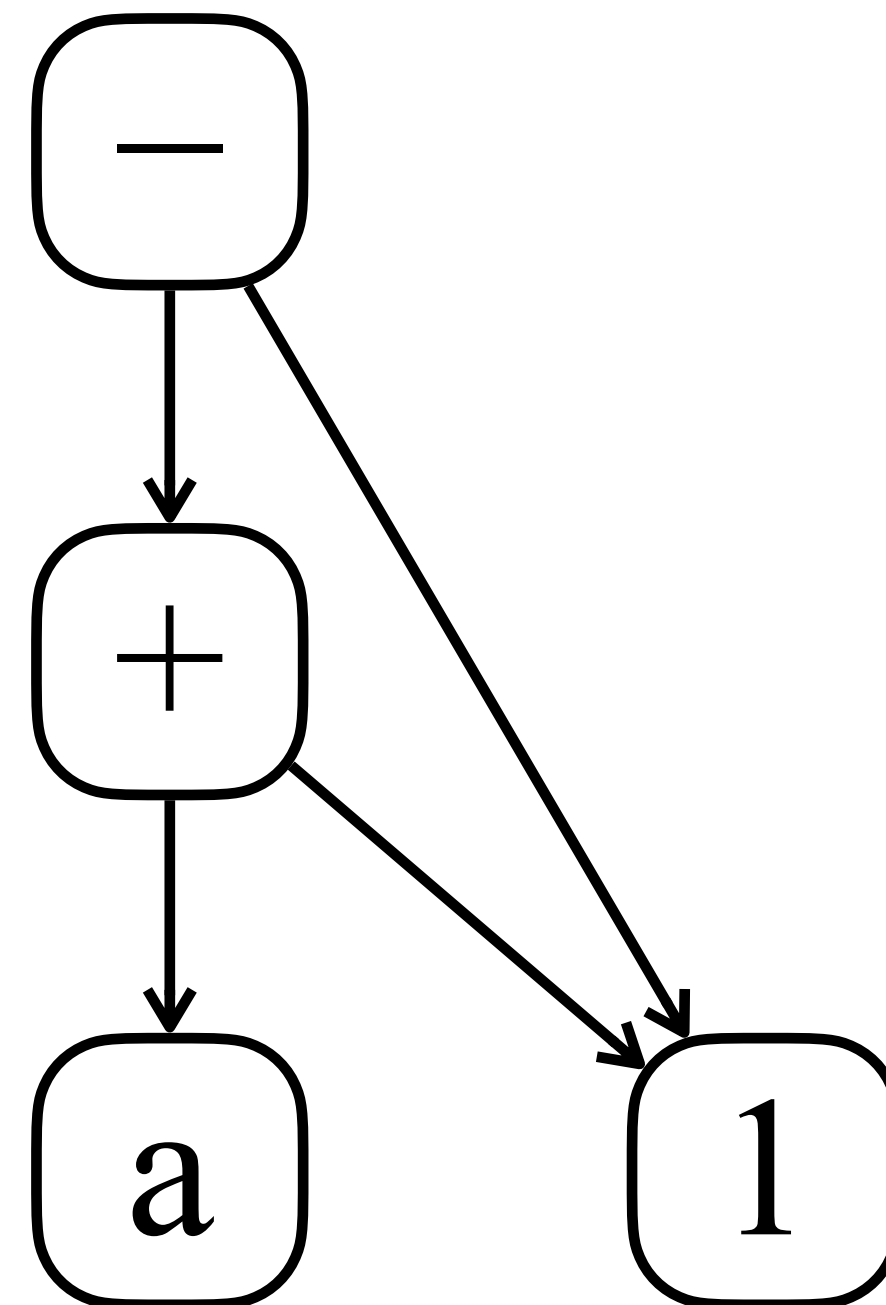


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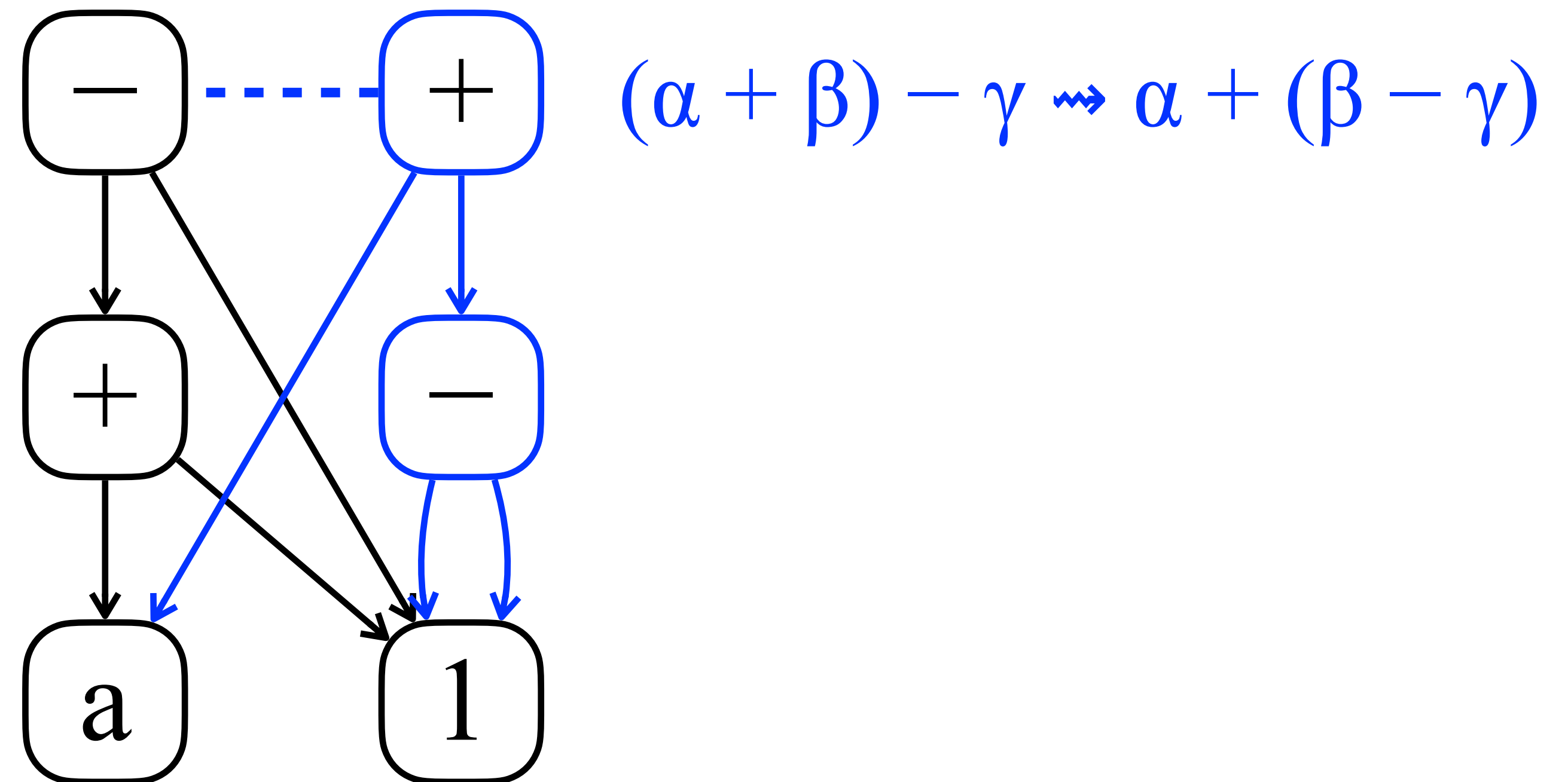


**Too much space?**

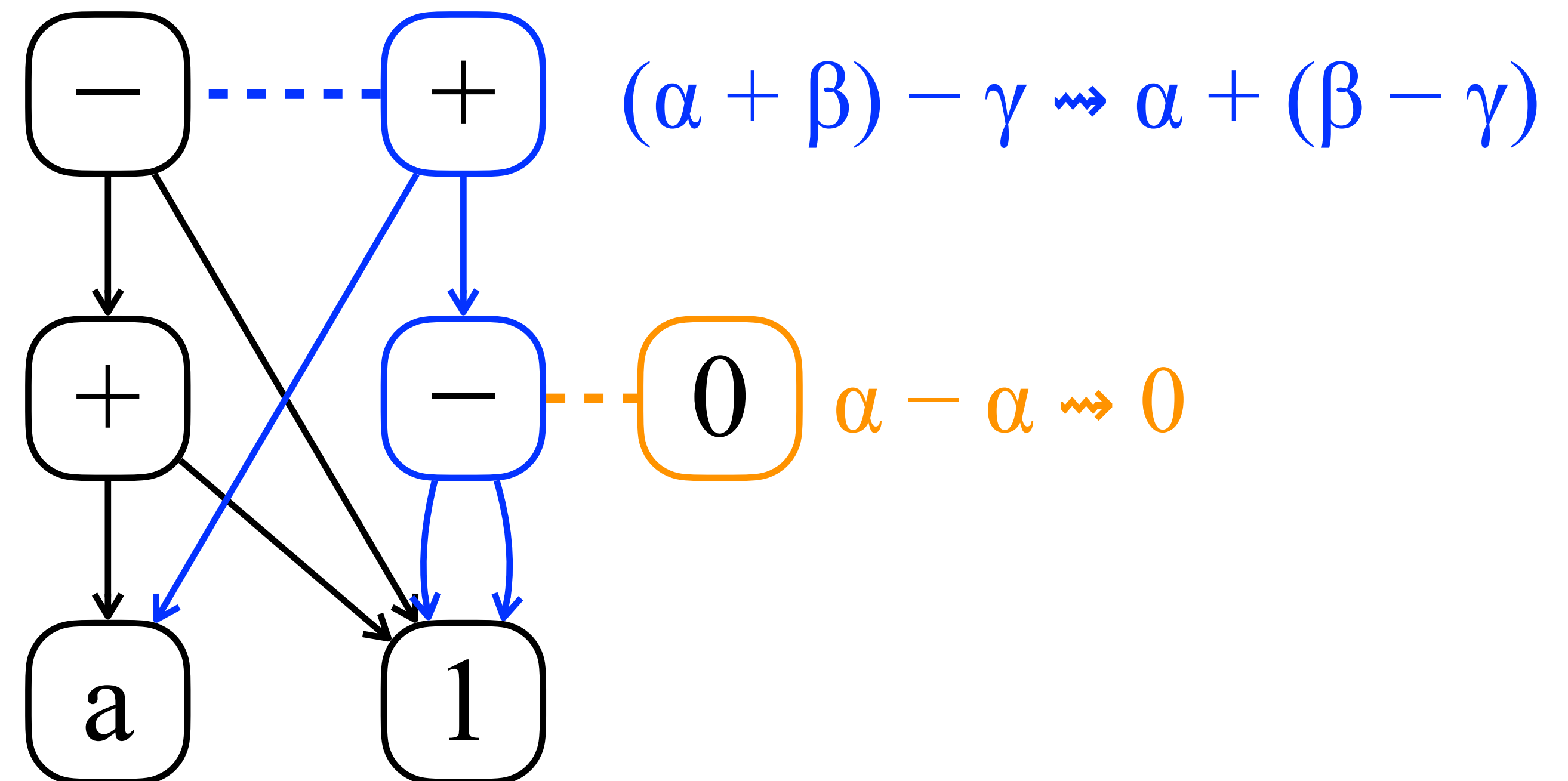
# Equivalence Graph (E-Graph)



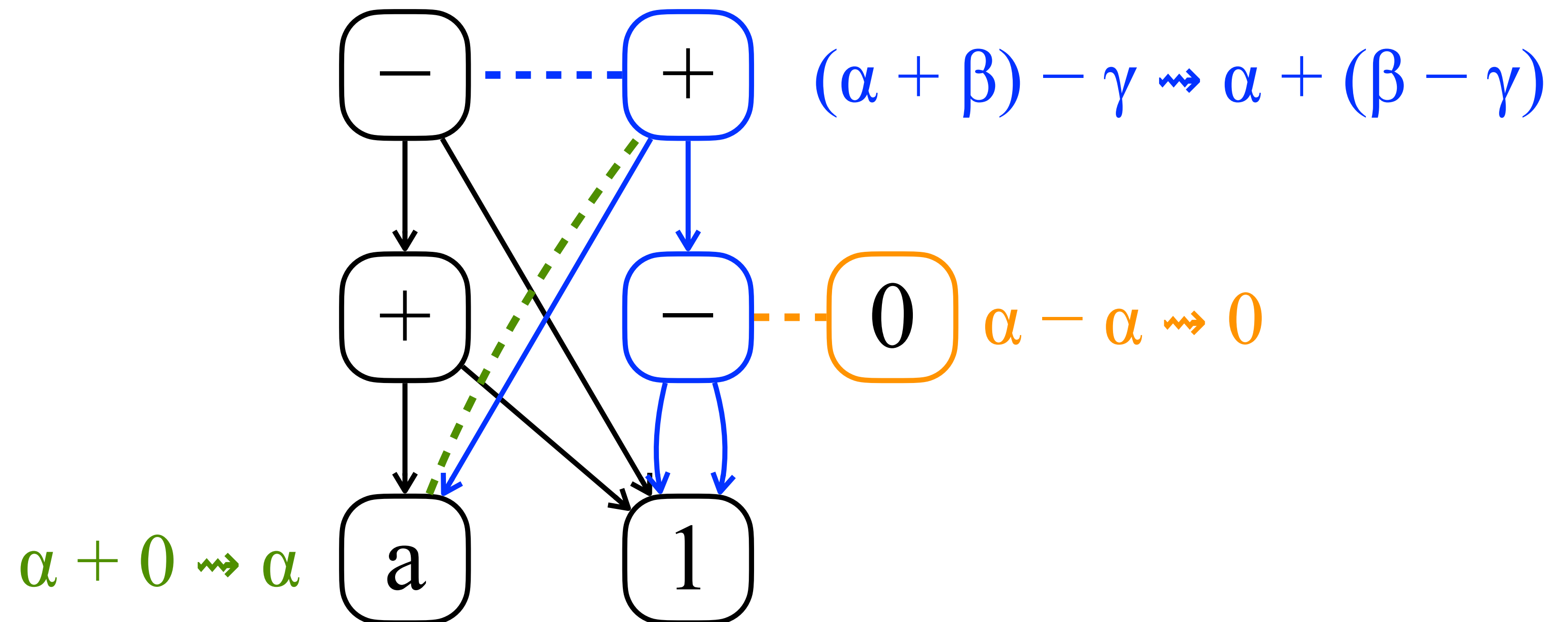
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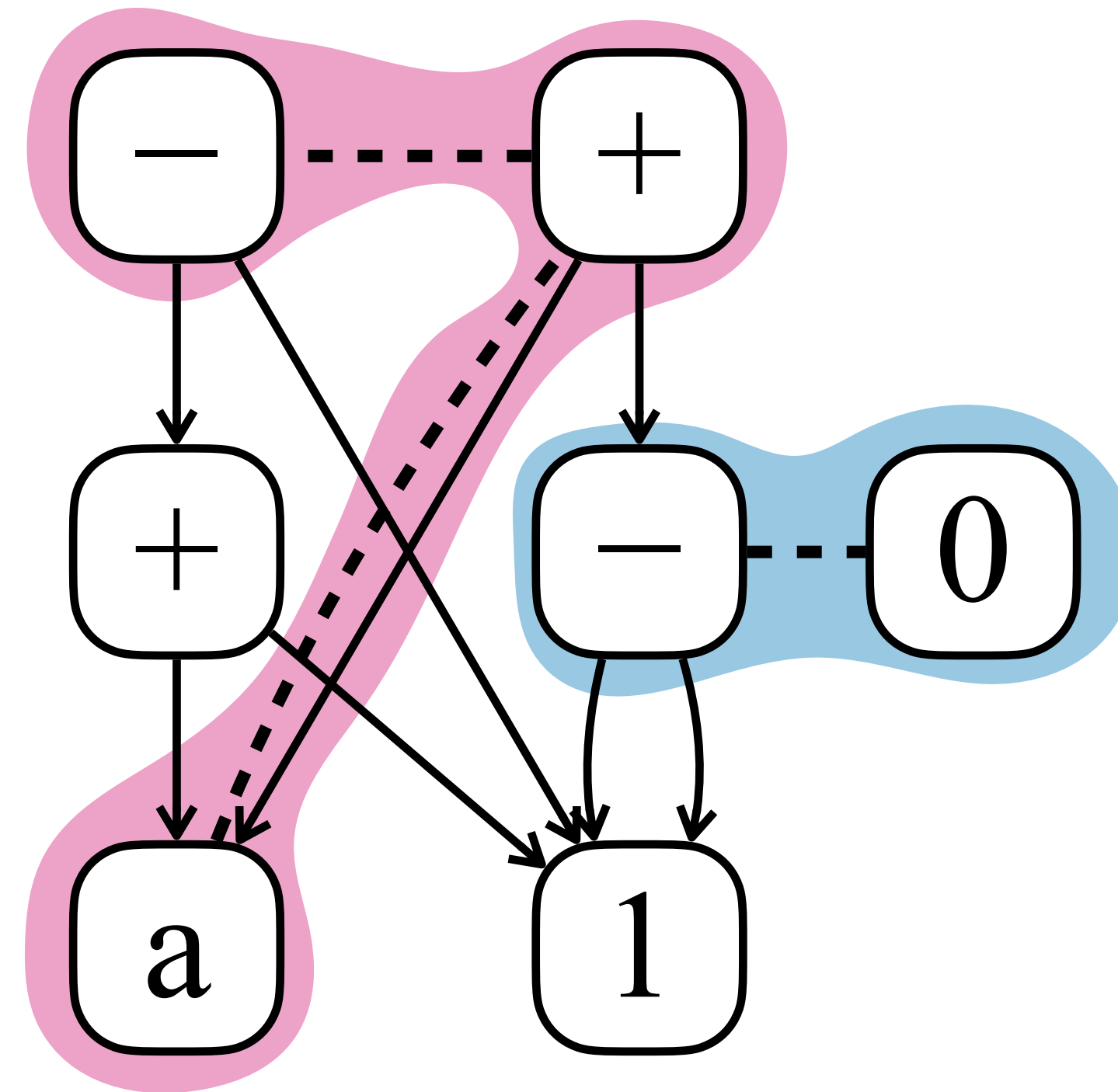
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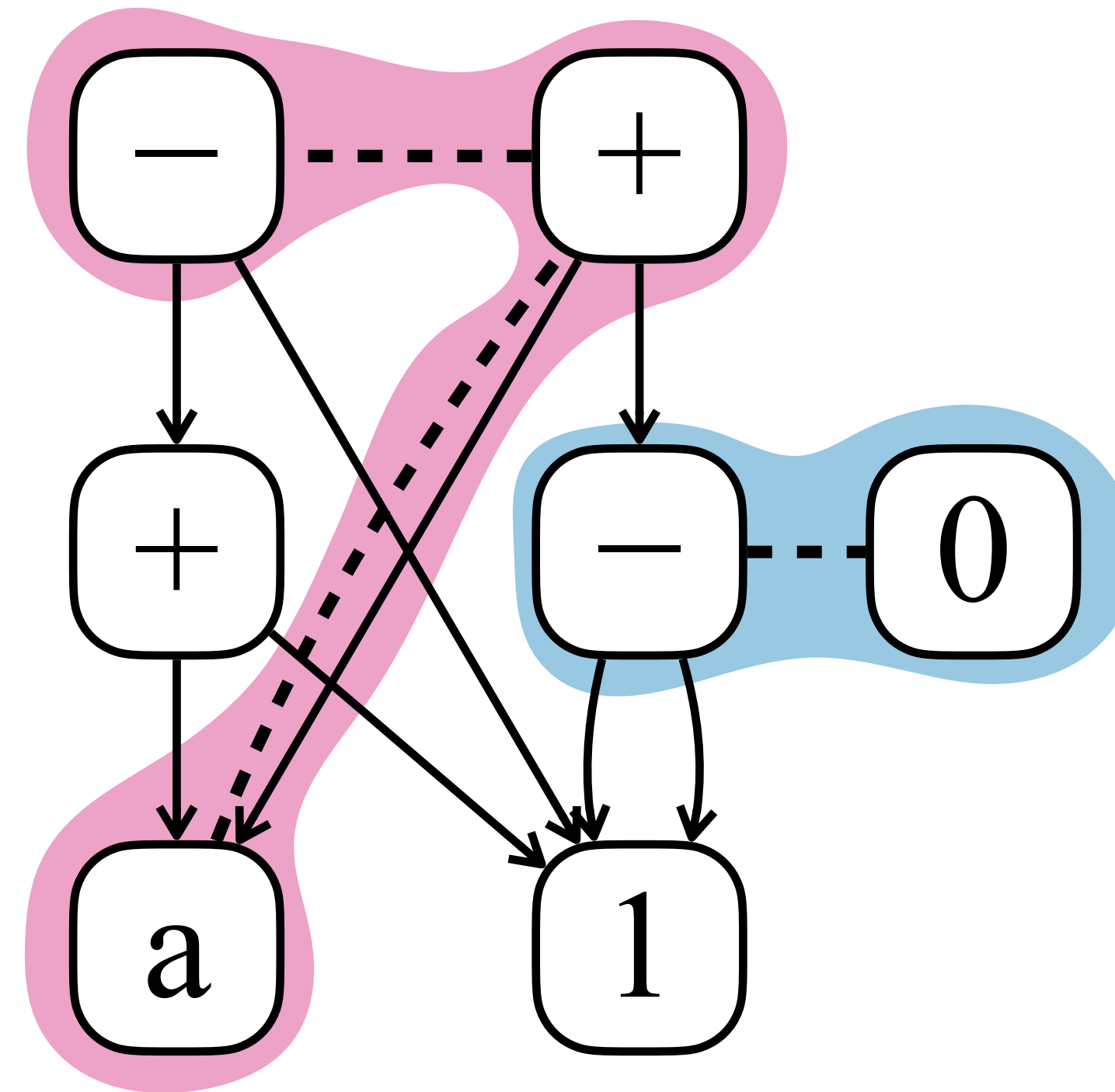


# Equivalence Graph (E-Graph)



# Equivalence Graph (E-Graph)

$$\begin{aligned}
 &(a + 1) - 1 \\
 &\equiv a + (1 - 1) \\
 &\equiv a
 \end{aligned}$$

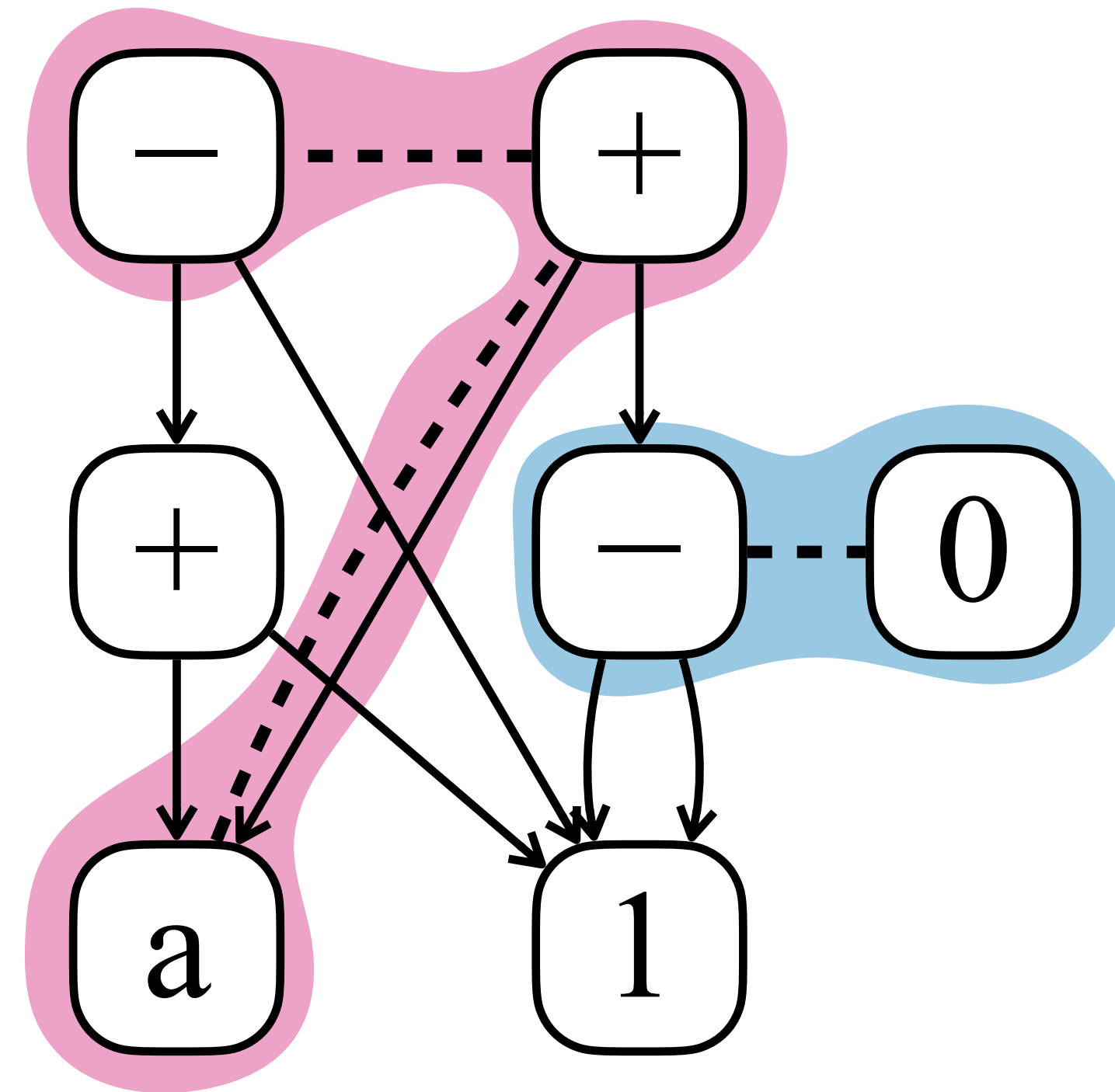


$$1 - 1 \equiv 0$$

# Equivalence Graph (E-Graph)

$$\alpha \equiv \beta \Rightarrow f(\alpha) \equiv f(\beta)$$

$$\begin{aligned} &(a + 1) - 1 \\ &\equiv a + (1 - 1) \\ &\equiv a \end{aligned}$$

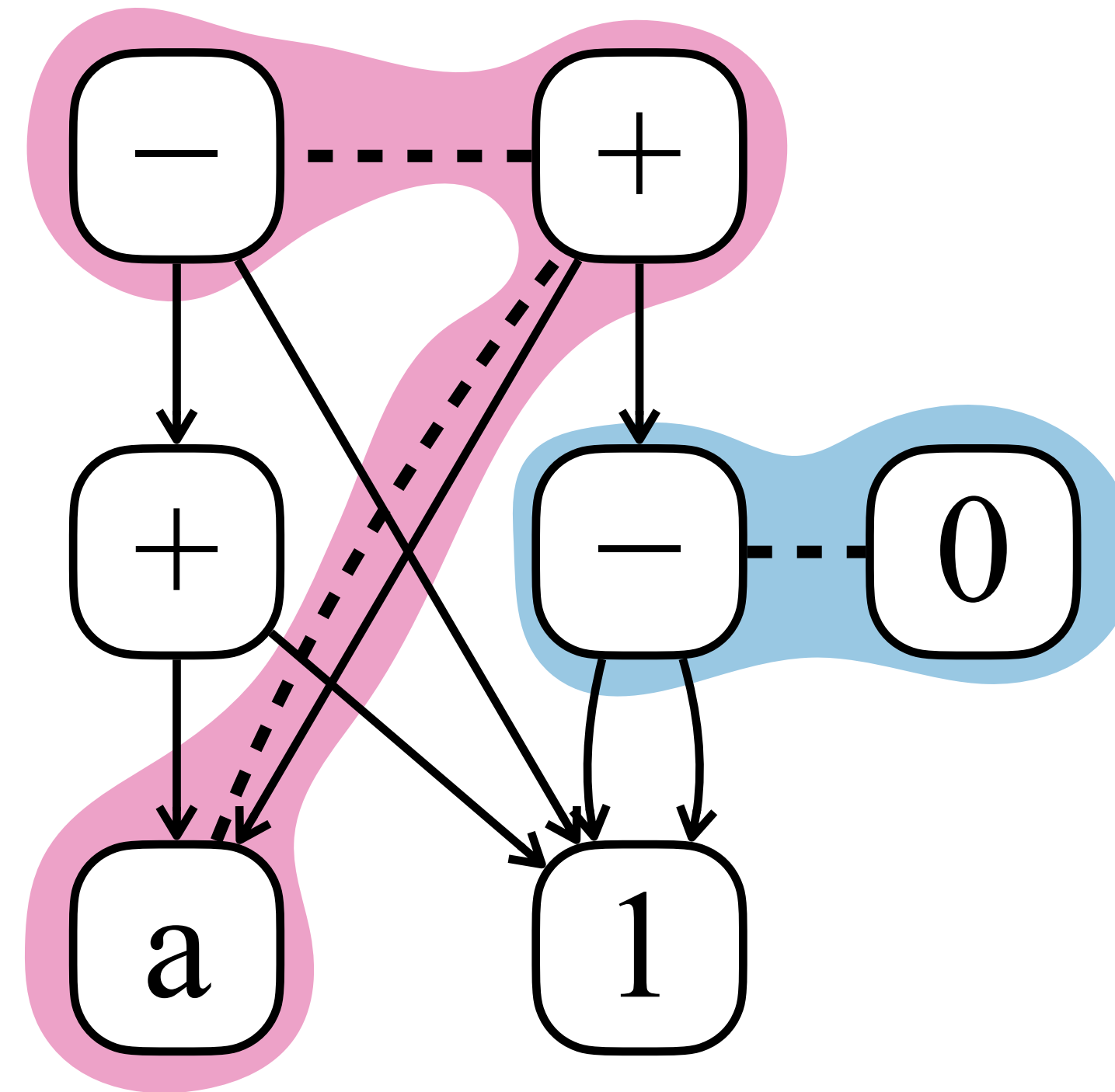


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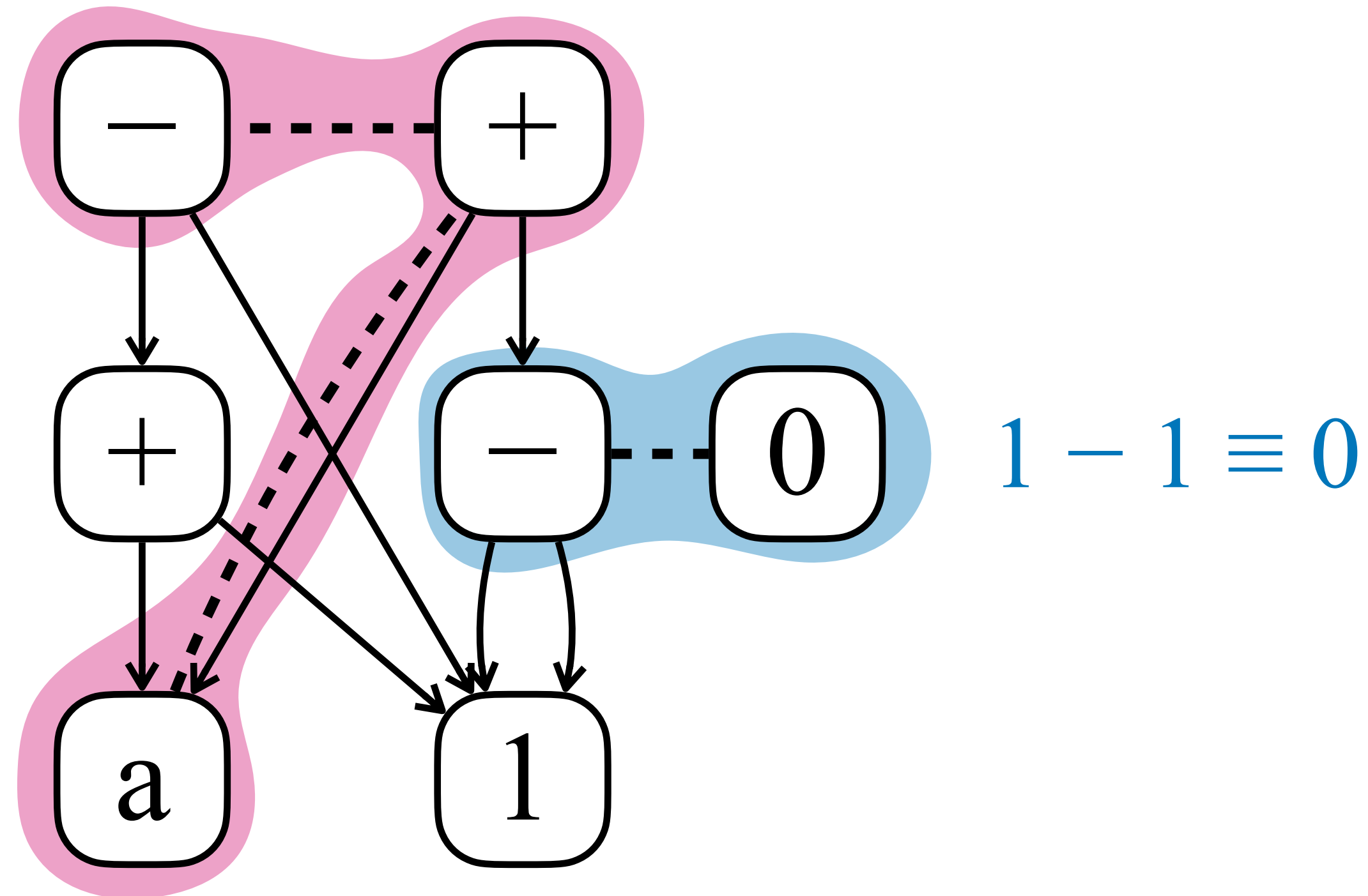


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$$\alpha \equiv \beta \Rightarrow f(\alpha) \equiv f(\beta)$$

$$\begin{aligned} & (a + 1) - 1 \\ & \equiv a + (1 - 1) \\ & \equiv a \\ & \equiv a + 0 \\ & \equiv (a + 0) + 0 \\ & \equiv ((a + 0) + 0) + 0 \\ & \dots \end{aligned}$$

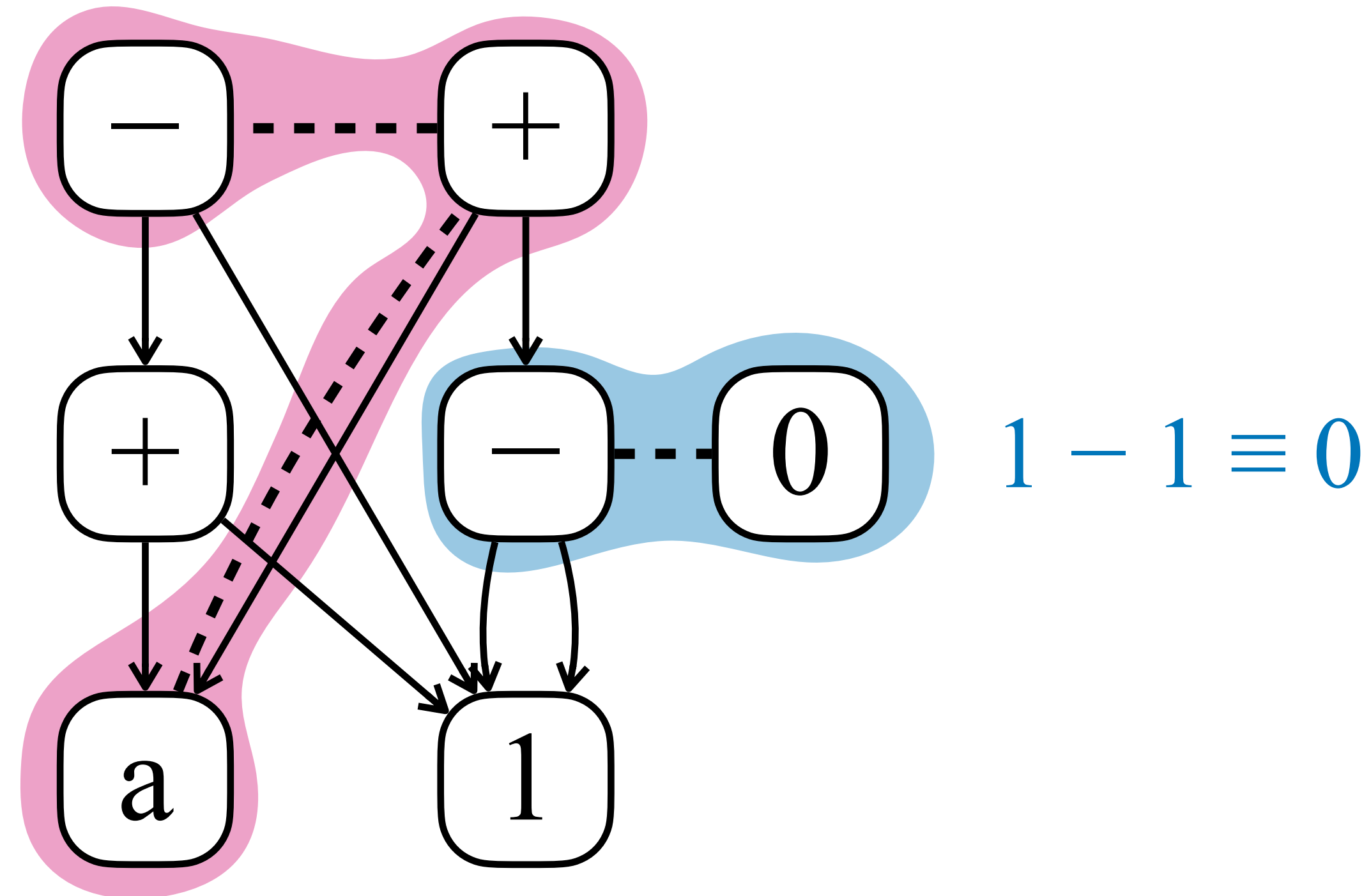


# Equivalence Graph (E-Graph)

$$\alpha \equiv \beta \Rightarrow f(\alpha) \equiv f(\beta)$$

Equivalent terms are interchangeable

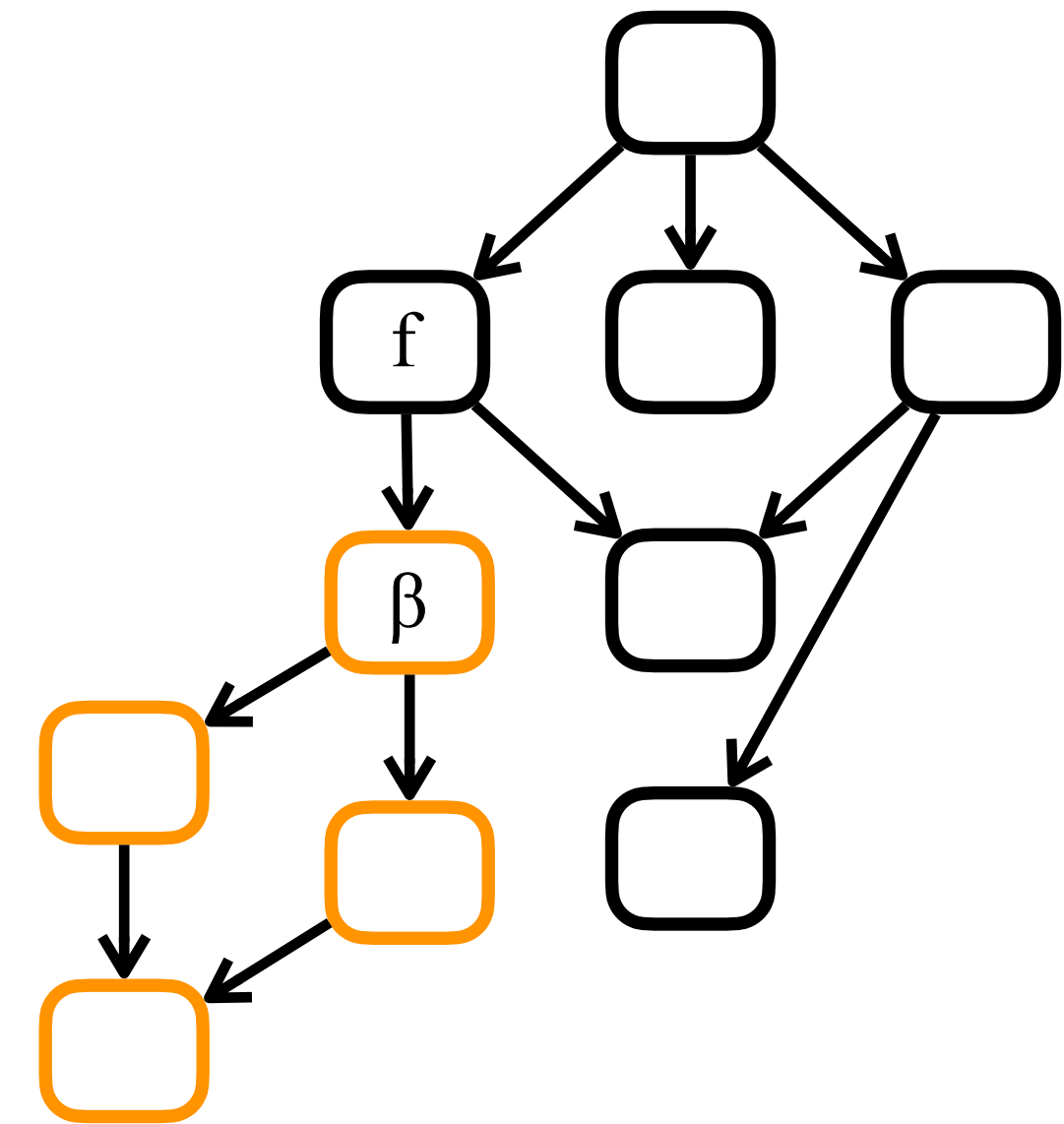
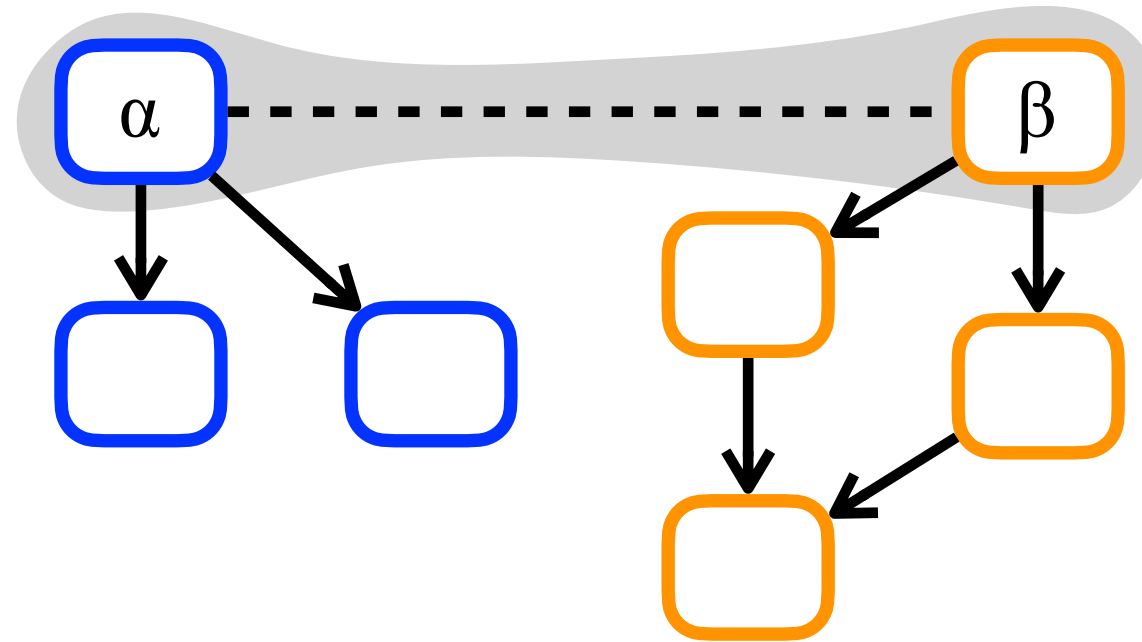
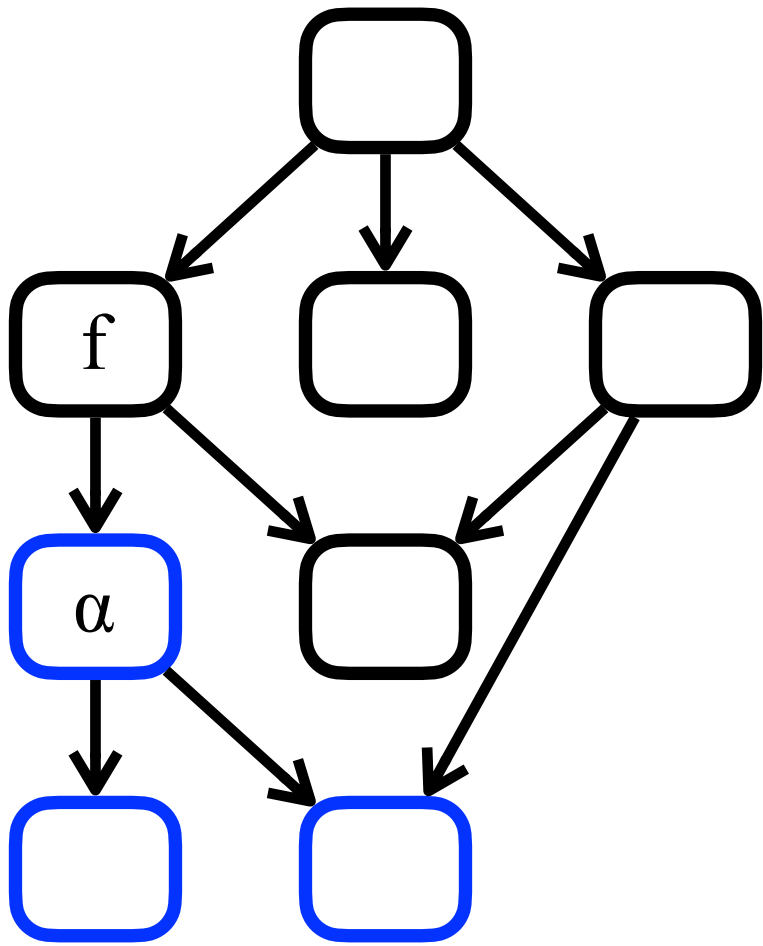
$$\begin{aligned} &(a + 1) - 1 \\ &\equiv a + (1 - 1) \\ &\equiv a \\ &\equiv a + 0 \\ &\equiv (a + 0) + 0 \\ &\equiv ((a + 0) + 0) + 0 \\ &\dots \end{aligned}$$



# Equivalence Graph (E-Graph)

$$\alpha \equiv \beta \Rightarrow f(\alpha) \equiv f(\beta)$$

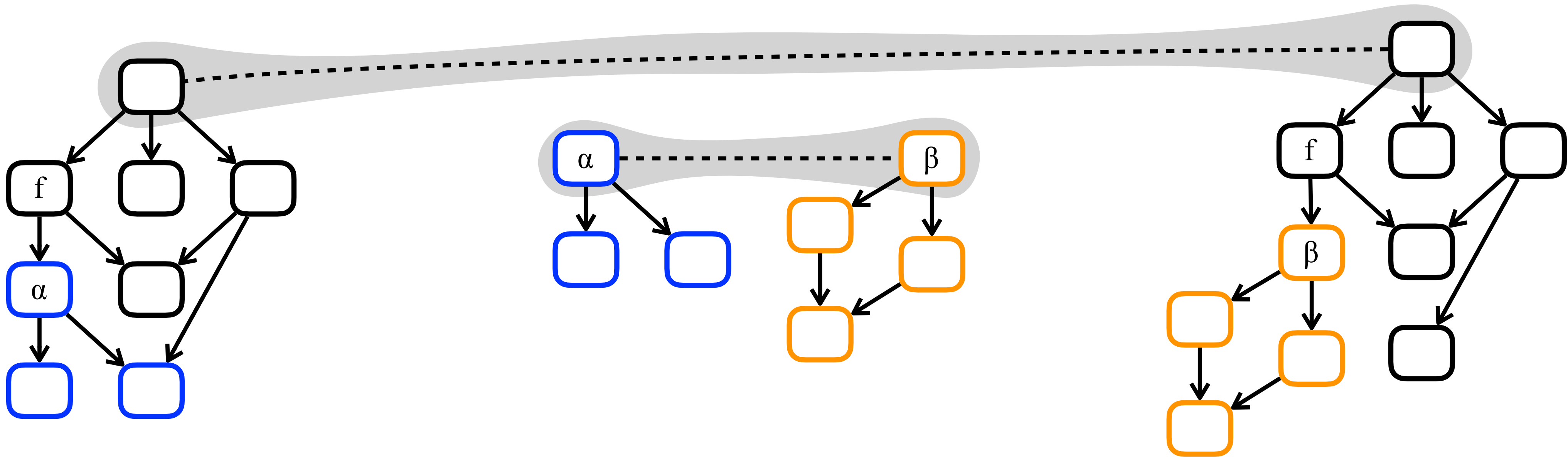
Equivalent terms are interchangeable



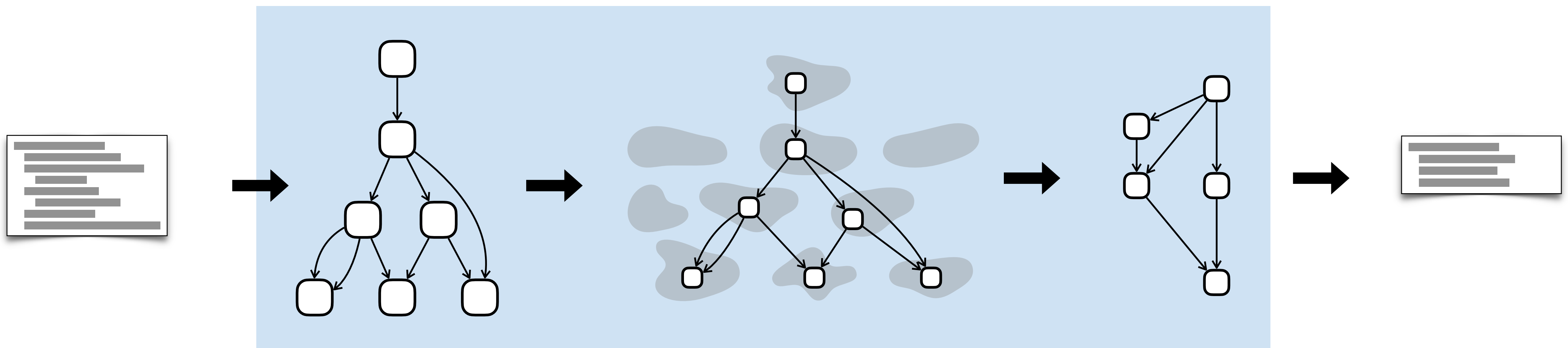
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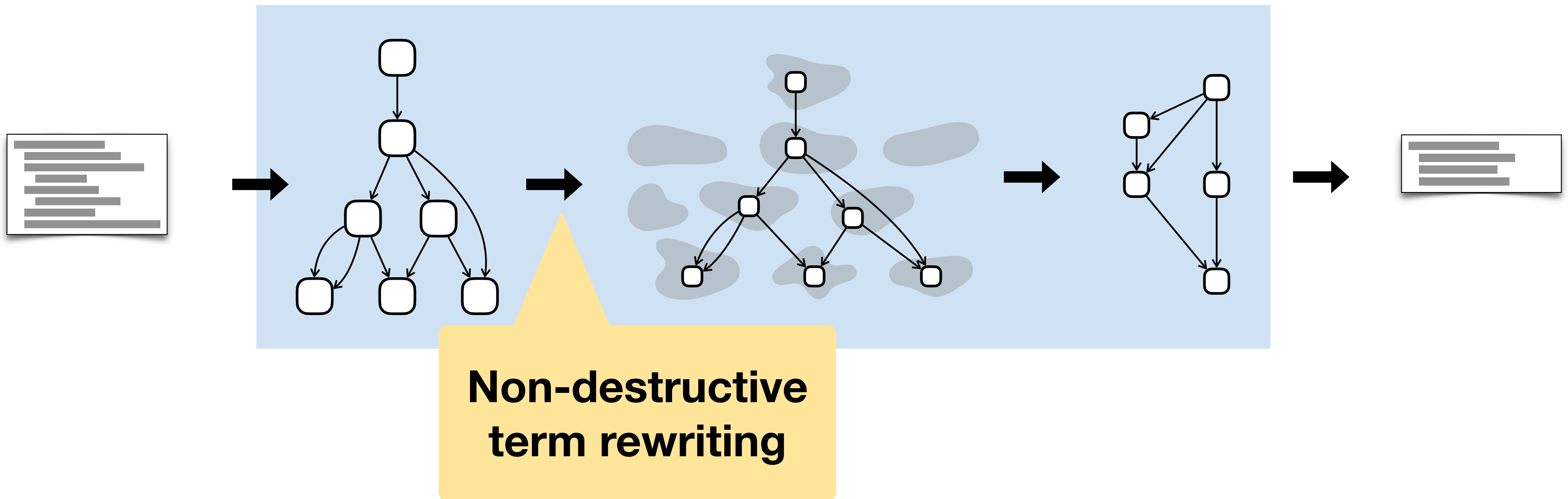
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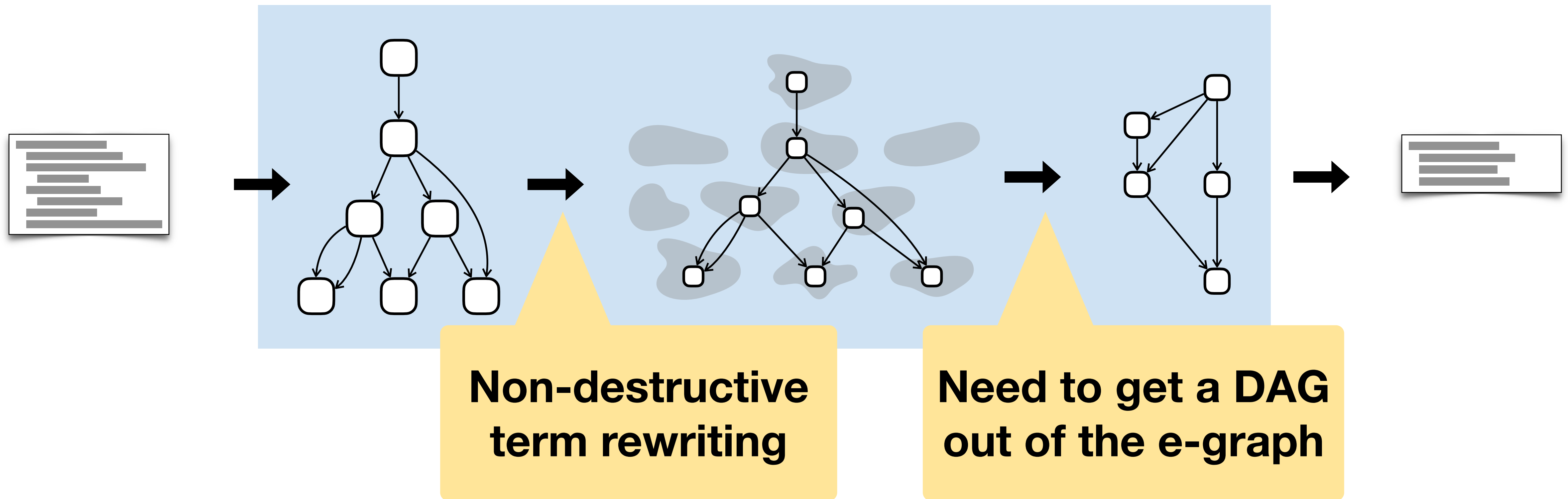
# Program Optimization with E-Graphs



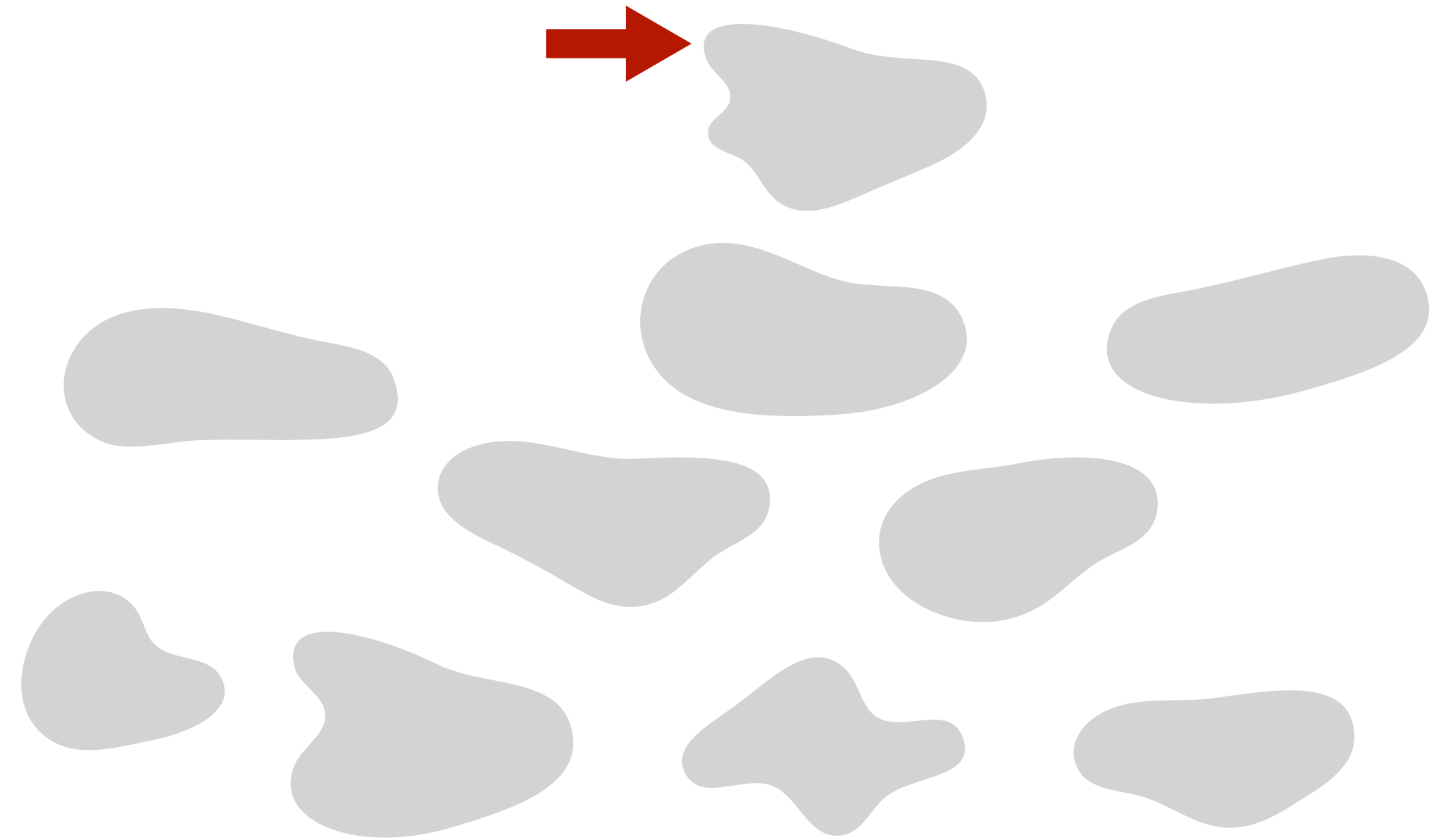
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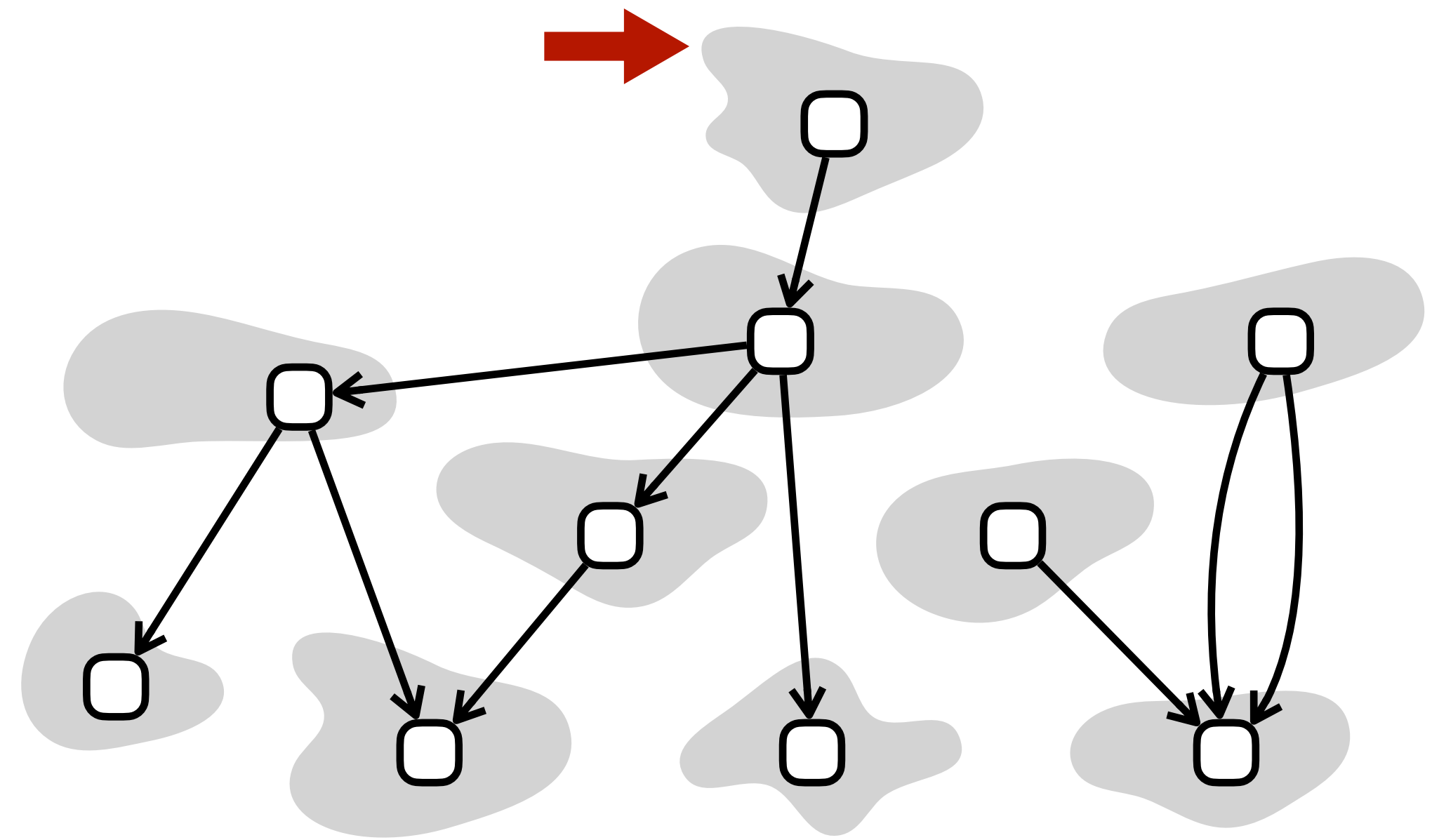


# Extraction



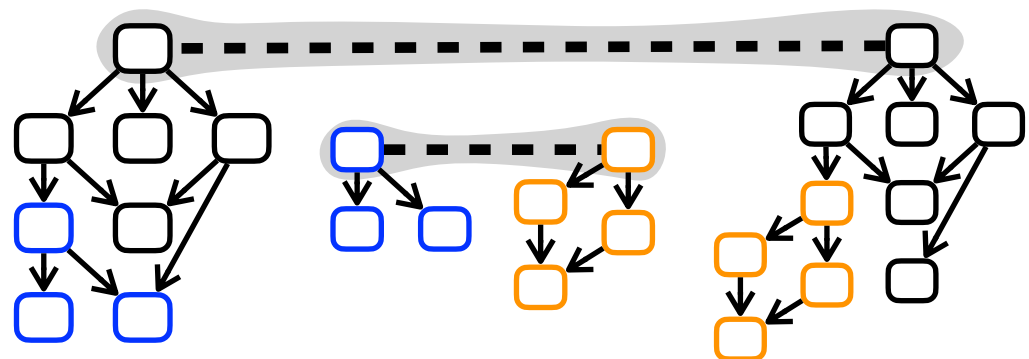
# Extraction

1. Pick a representative term from each e-class
2. Re-use that term everywhere you need an equivalent term

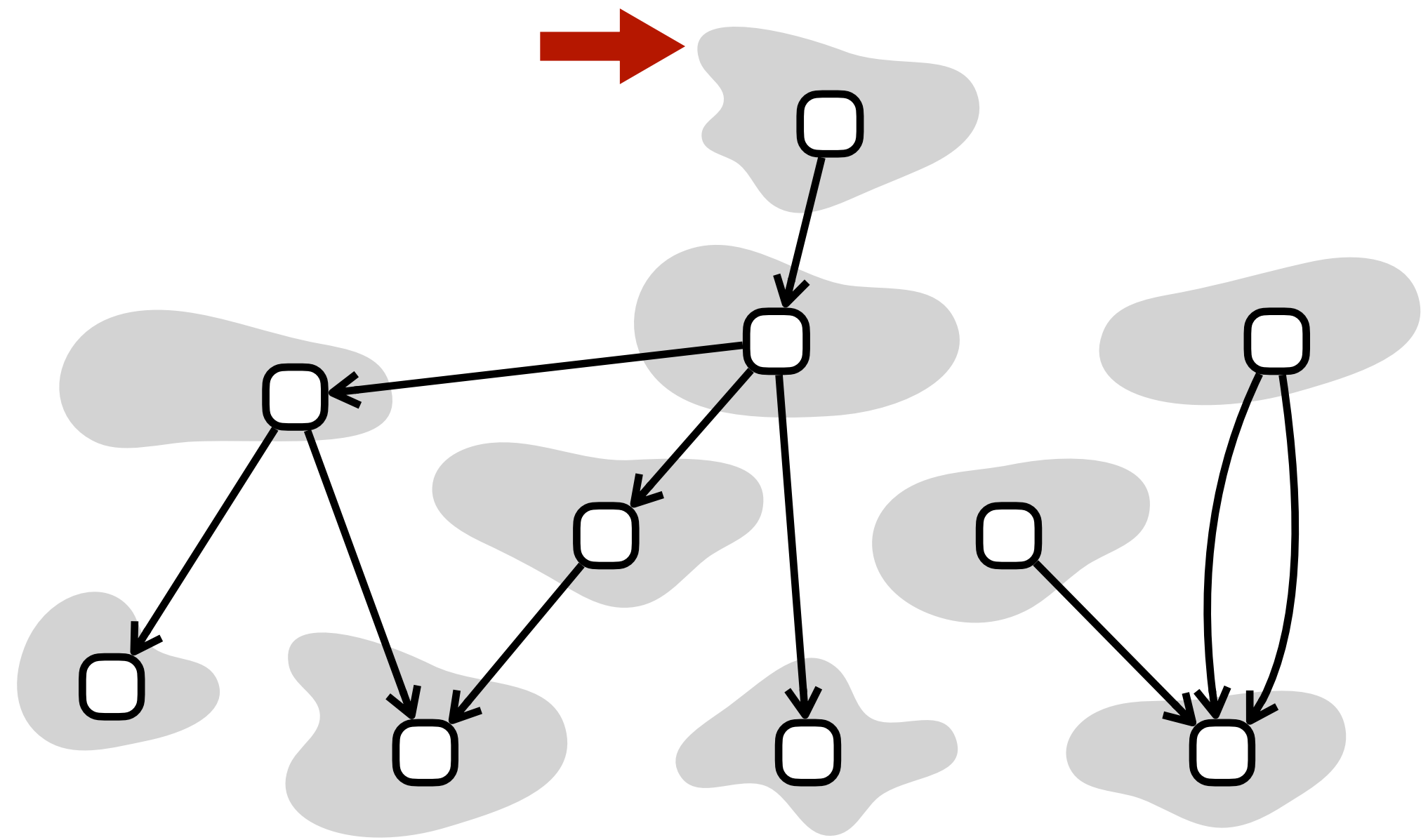


# Extraction

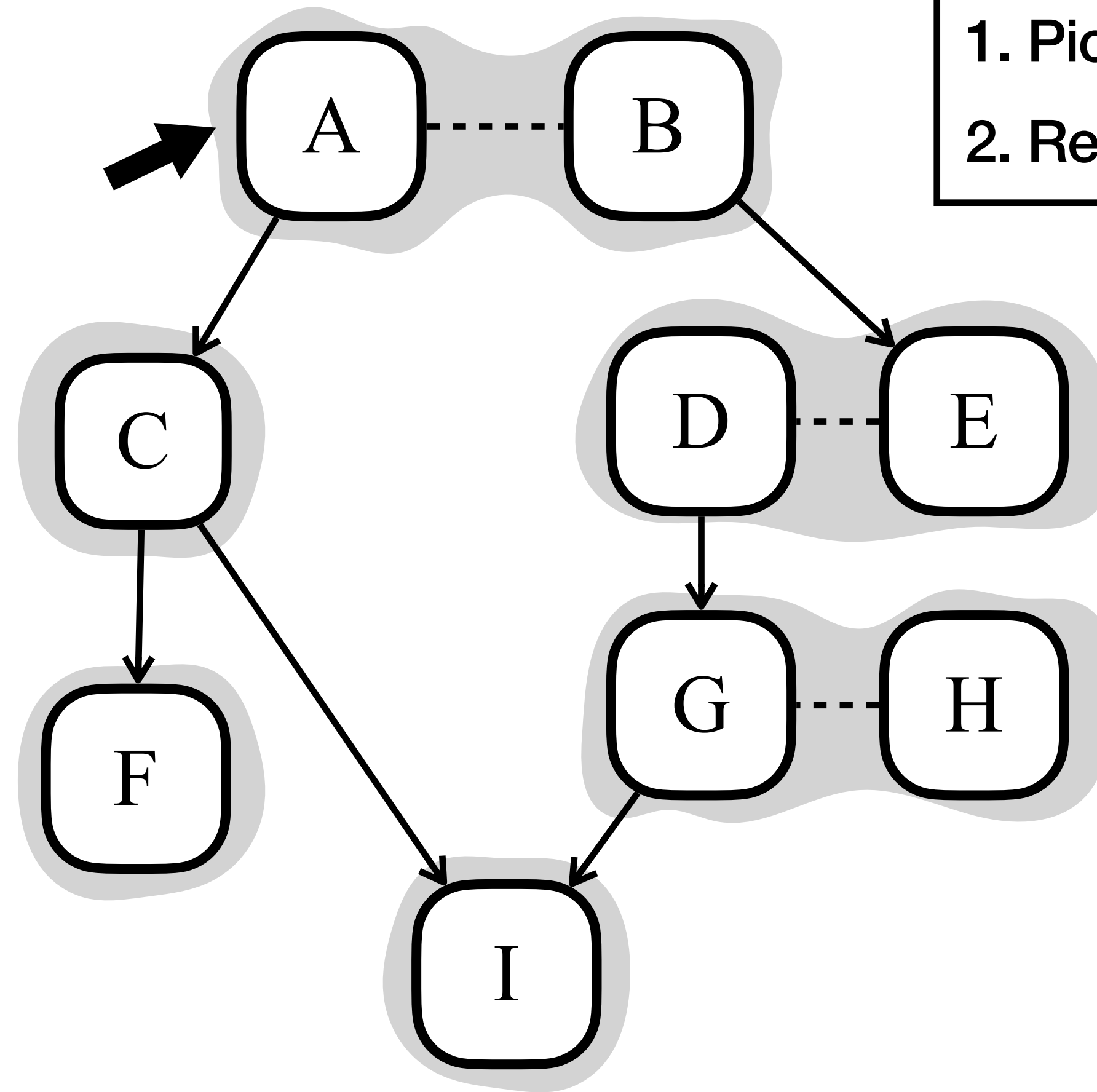
1. Pick a representative term from each e-class
2. **Re-use that term** everywhere you need an equivalent term



**Equivalent terms are interchangeable**



# Greedy Extraction with Cost Model



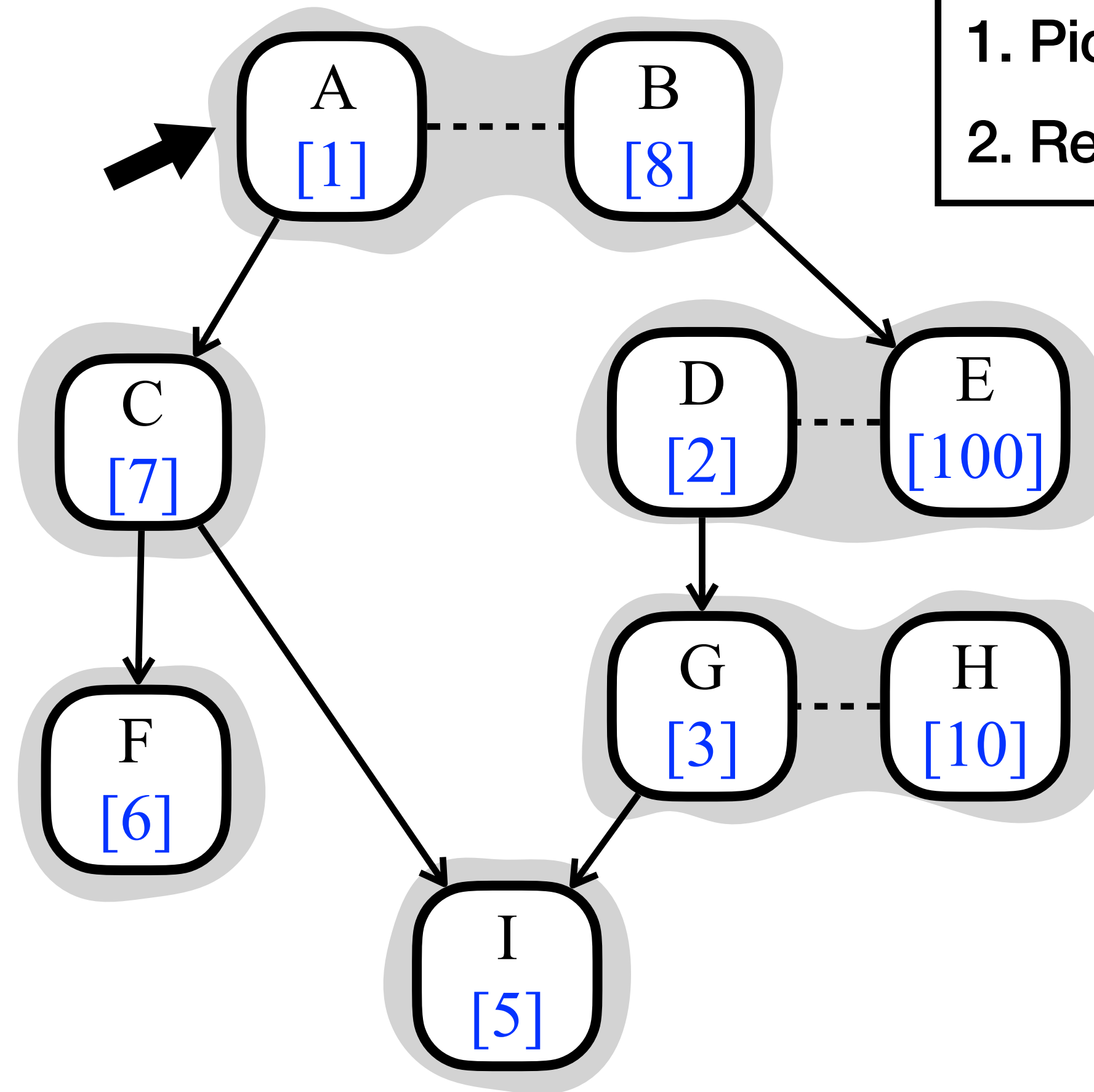
## Extraction

1. Pick a term from each e-class
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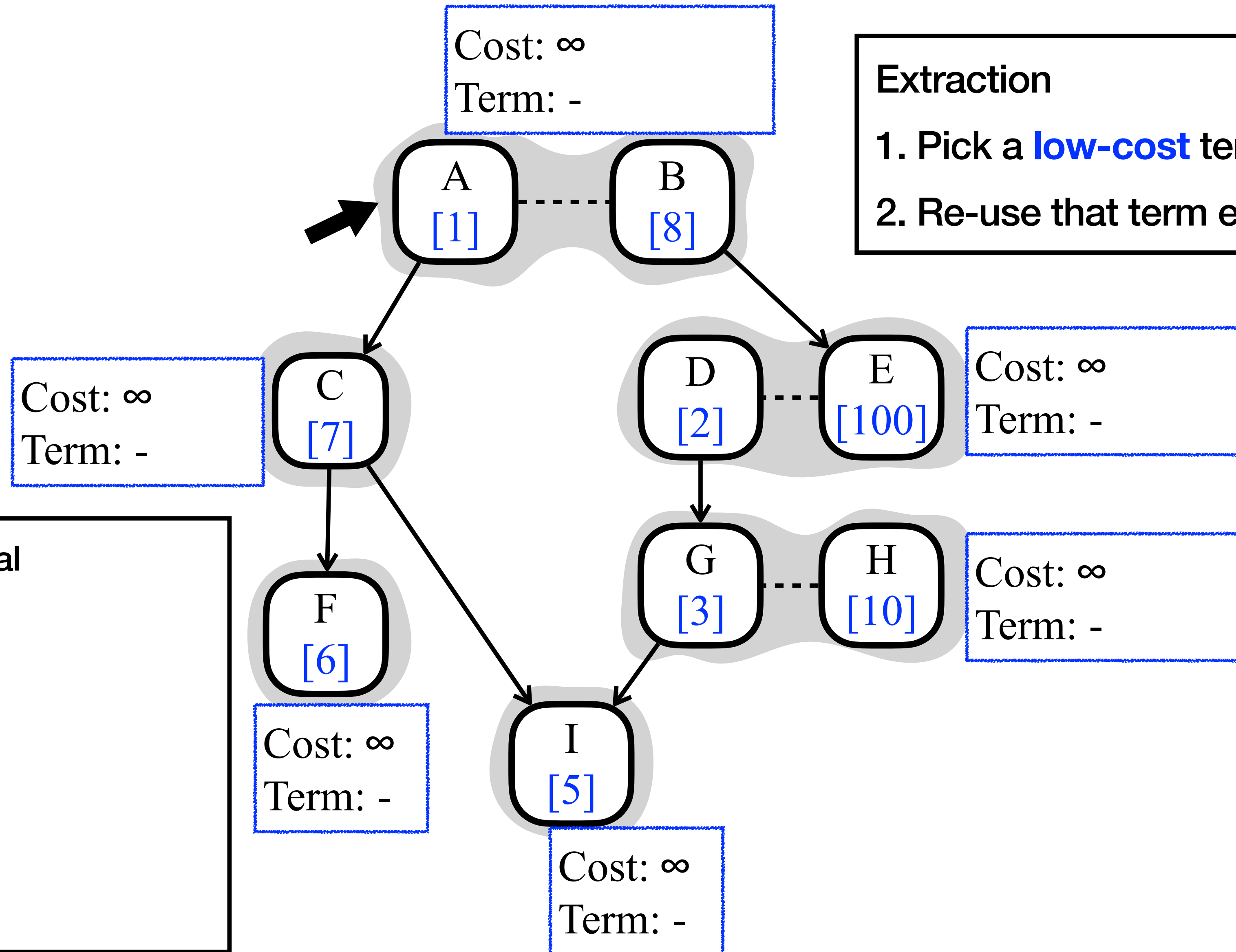
# Greedy Extraction with Cost Model

## Extraction

1. Pick a **low-cost** term from each e-class
2. Re-use that term everywhere



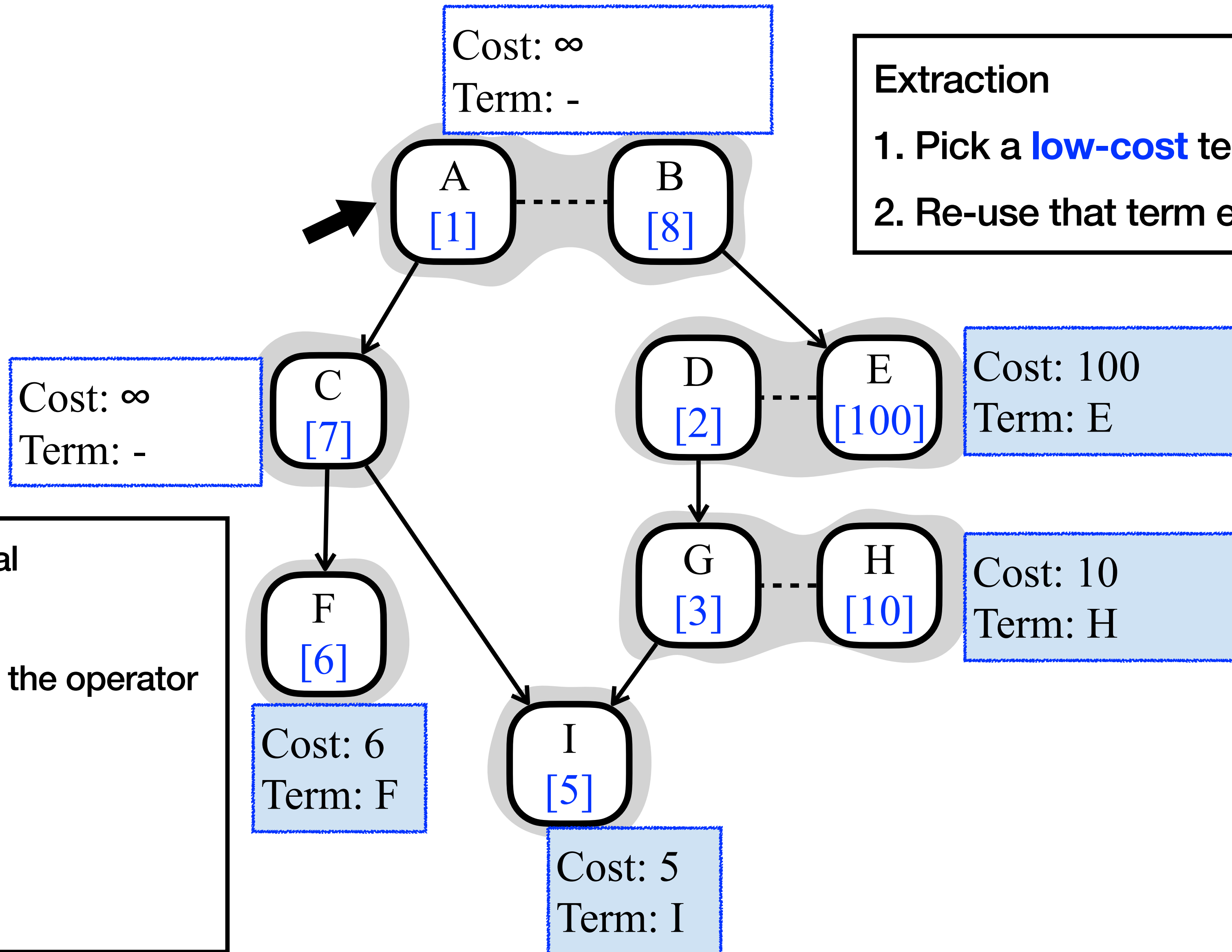
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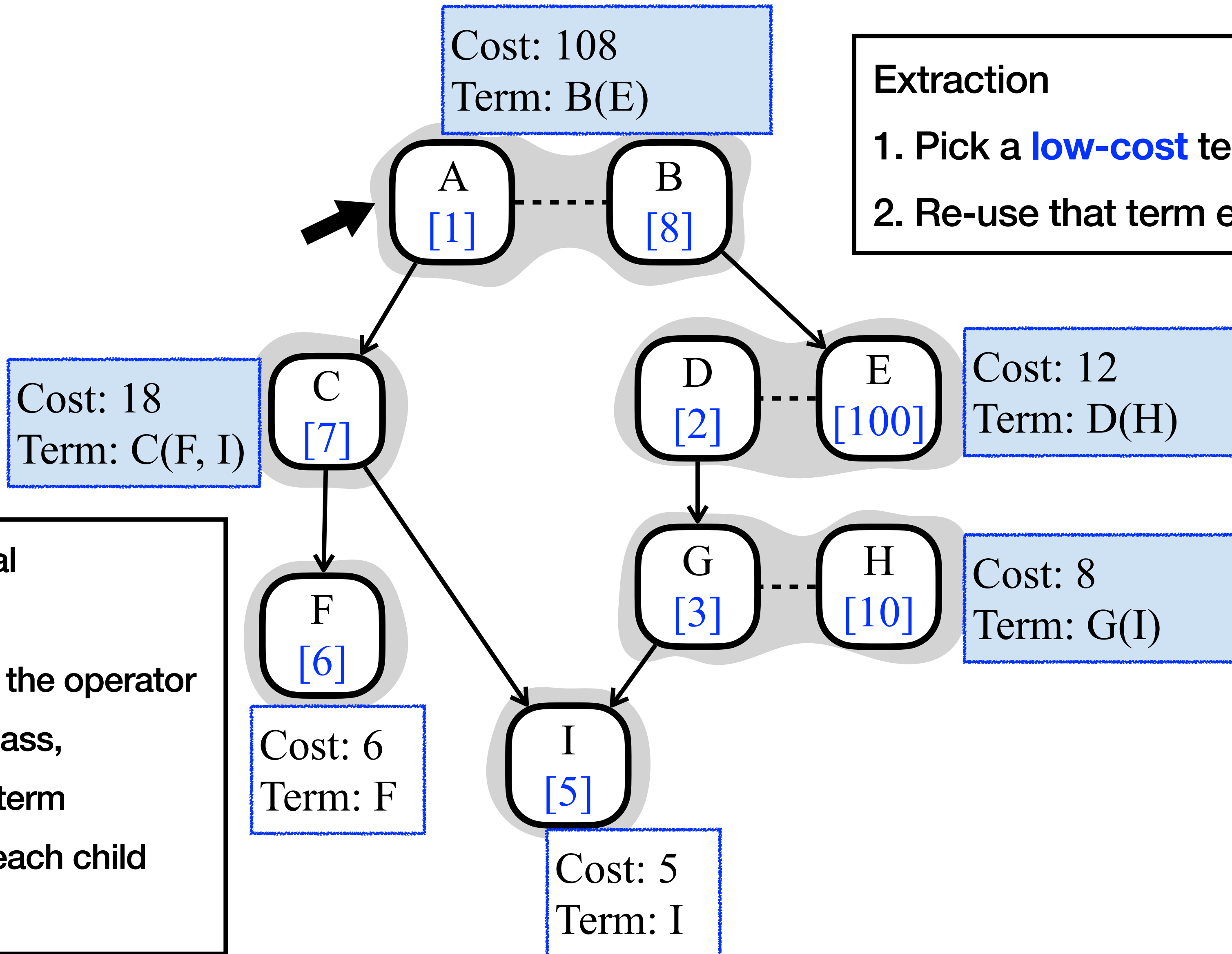
## Bottom Up Graph Traversal

1. Initialize all costs to  $\infty$
2. Leaf terms have cost of the operator

# Greedy Extraction with Cost Model

## Extraction

1. Pick a **low-cost** term from each e-class
2. Re-use that term everywhere



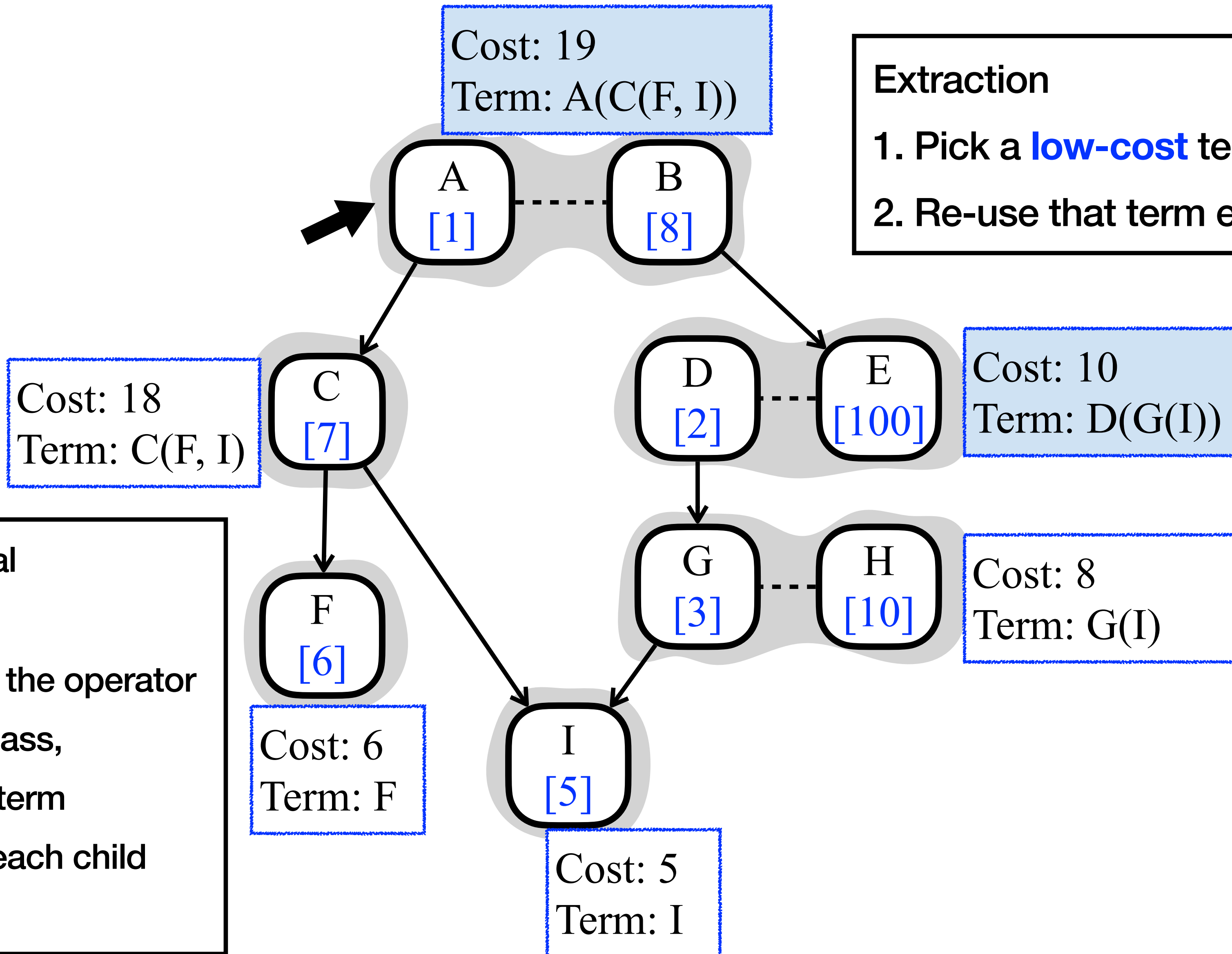
## Bottom Up Graph Traversal

1. Initialize all costs to  $\infty$
2. Leaf terms have cost of the operator
3. For each equivalence class, search for a lower cost term using the best cost for each child
4. Repeat until fixed point

# Greedy Extraction with Cost Model

## Extraction

1. Pick a **low-cost** term from each e-class
2. Re-use that term everywhere



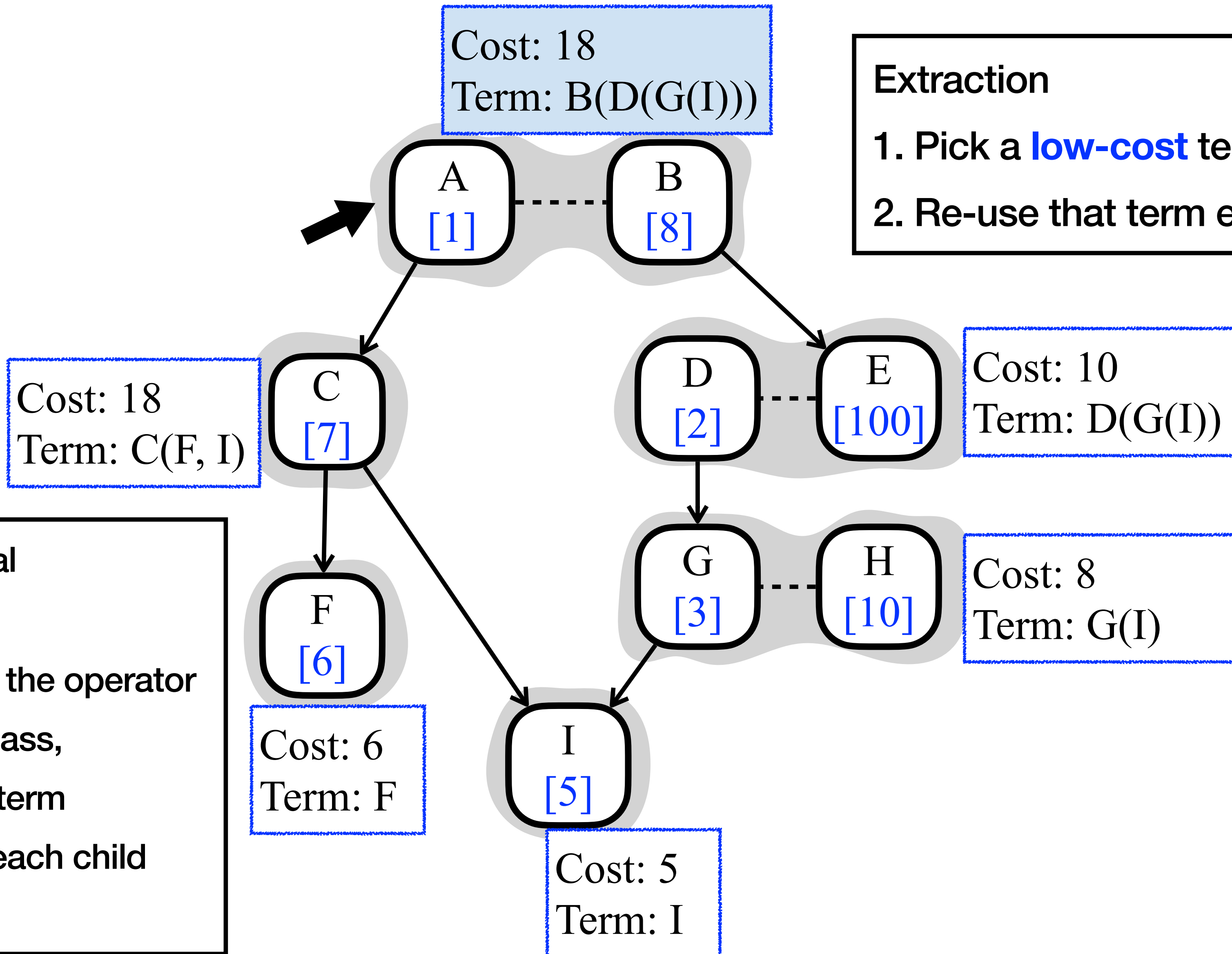
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# Greedy Extraction with Cost Model

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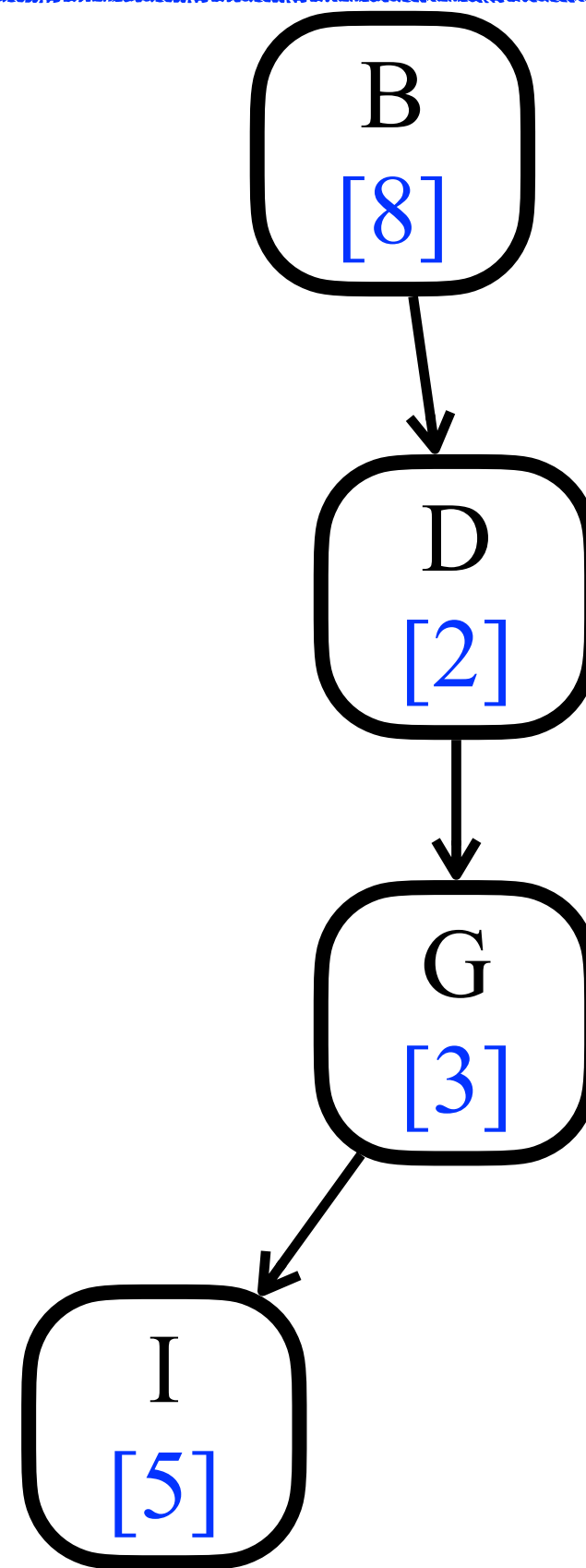


## Bottom Up Graph Traversal

1. Initialize all costs to  $\infty$
2. Leaf terms have cost of the operator
3. For each equivalence class, search for a lower cost term using the best cost for each child
4. Repeat until fixed point

# Greedy Extraction with Cost Model

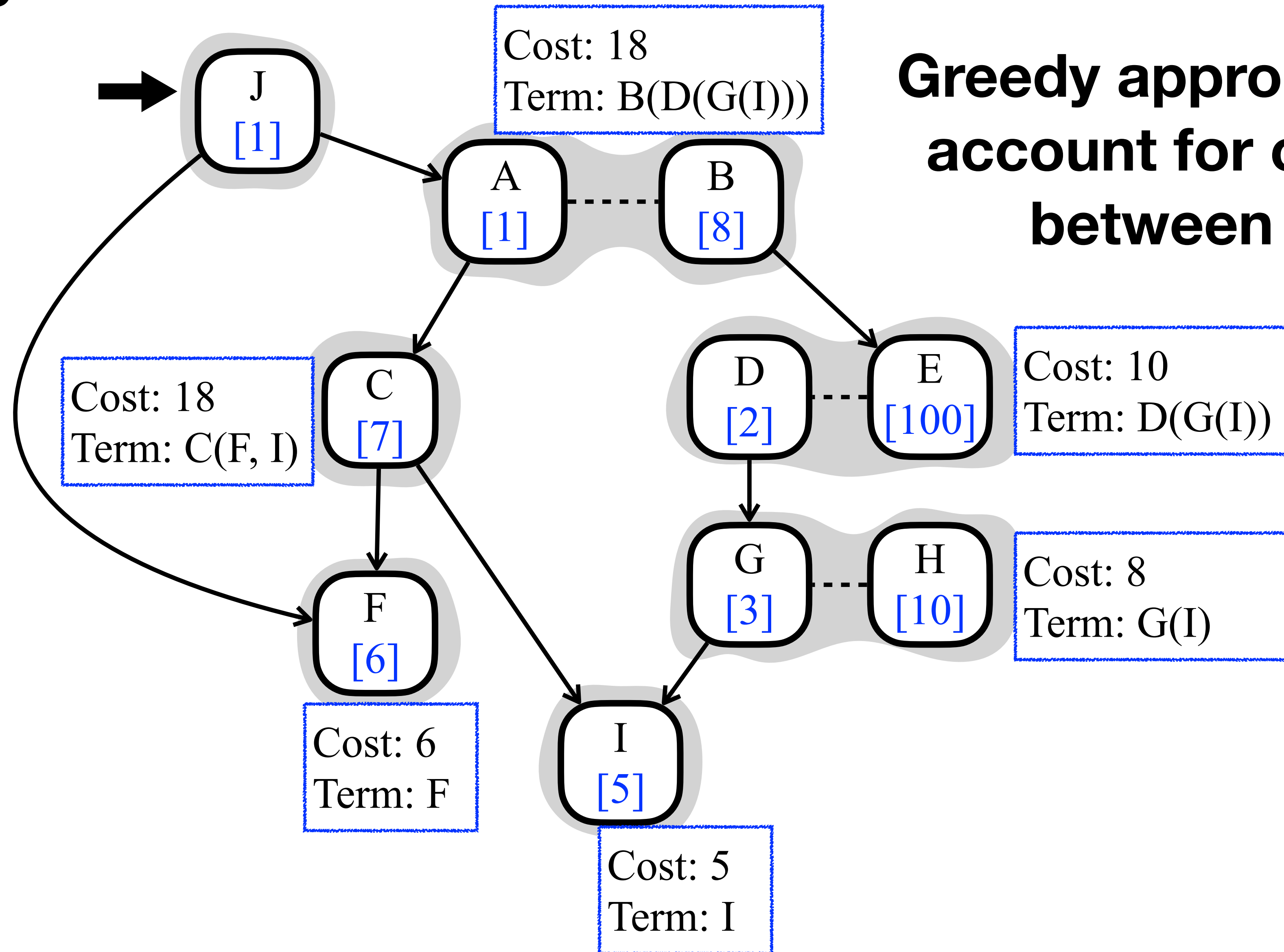
Cost: 18  
Term:  $B(D(G(I)))$



# Greedy Extraction with Cost Model

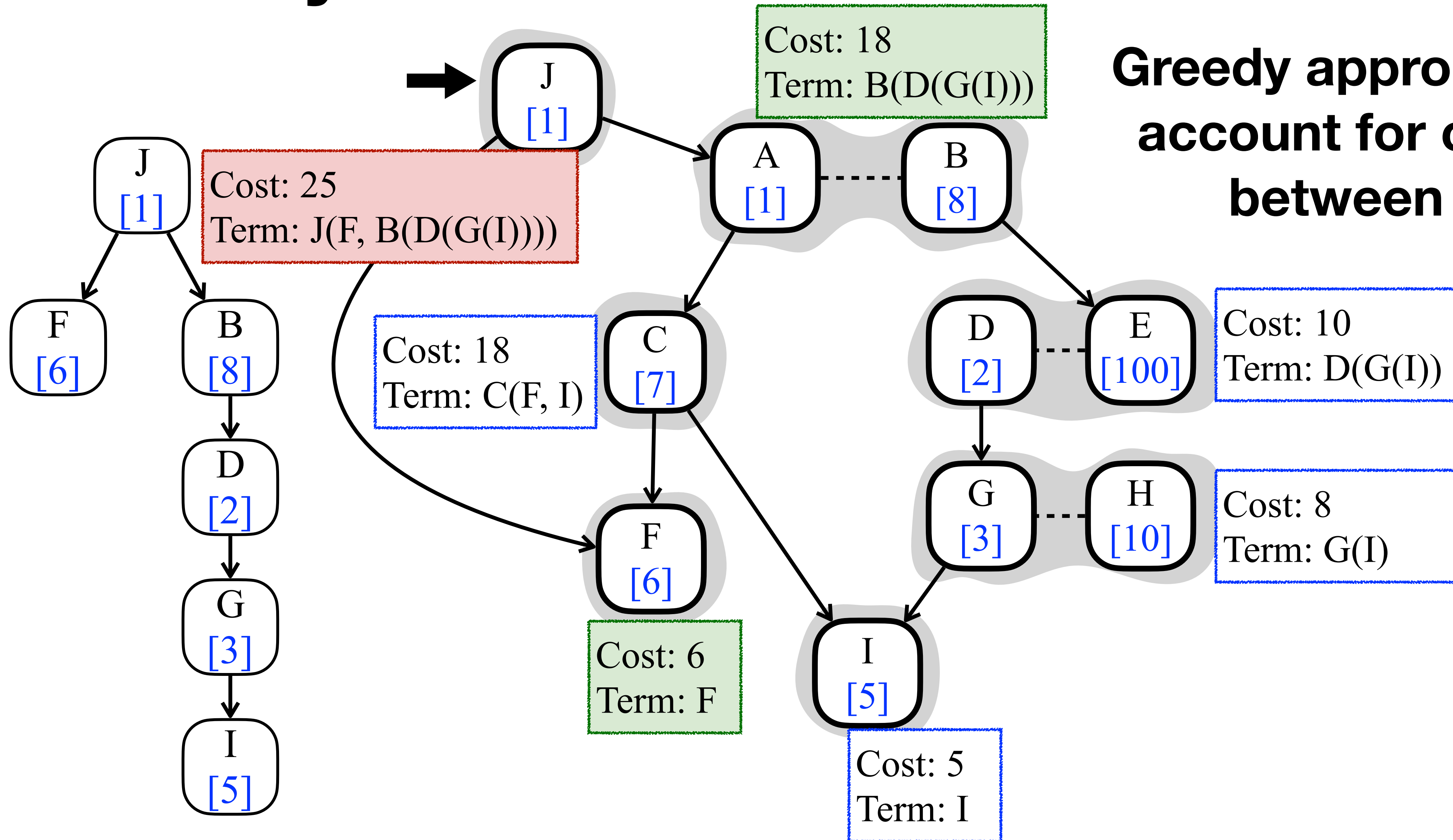
**Greedy approach does not  
account for cost sharing  
between children**

# Greedy Extraction with Cost Model

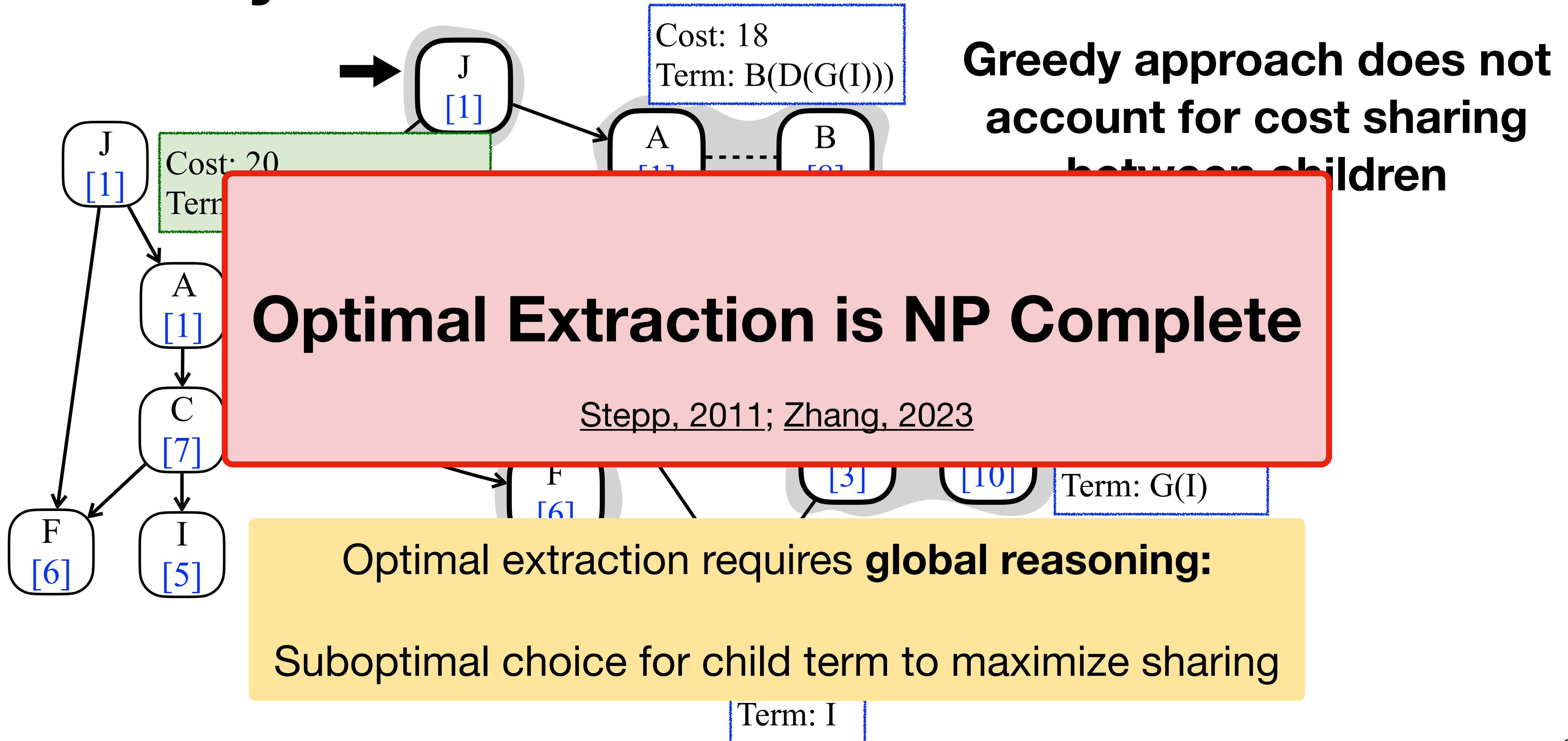


**Greedy approach does not account for cost sharing between children**

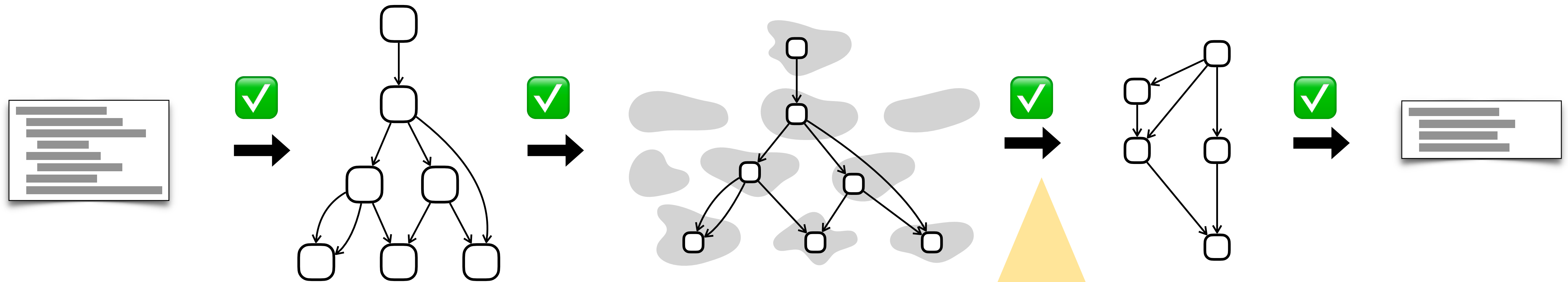
# Greedy Extraction with Cost Model



# Greedy Extraction with Cost Model

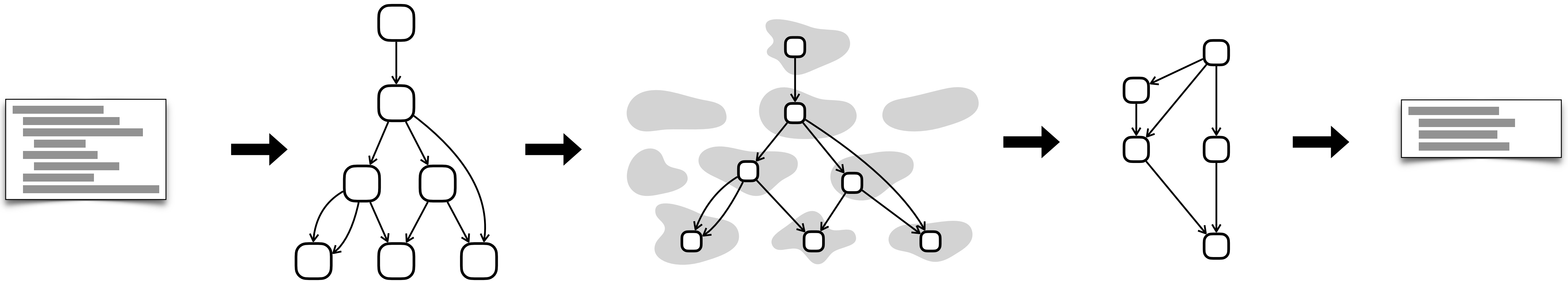


# Program Optimization with E-Graphs



**Optimal: NP Complete**  
**Greedy: Empirically Good**

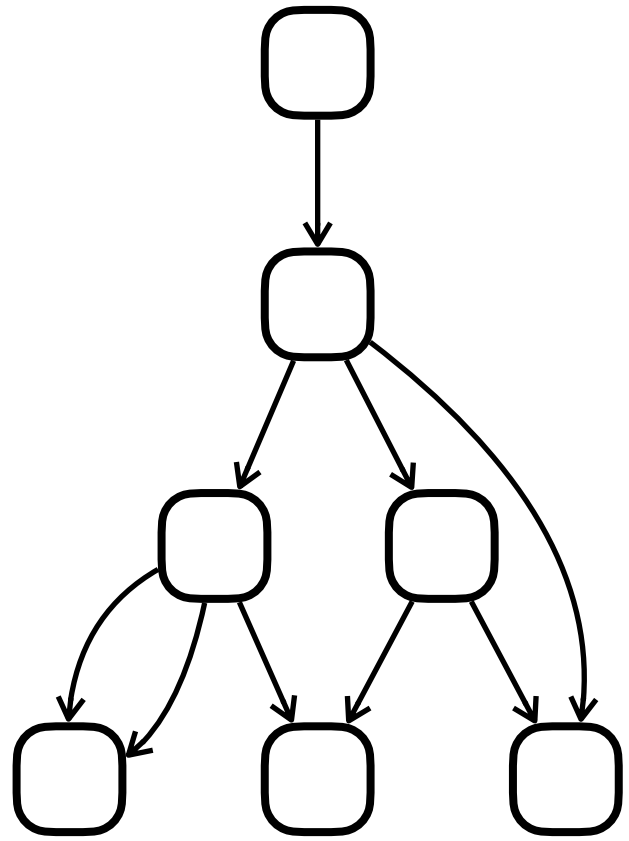
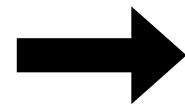
# Program Optimization with E-Graphs

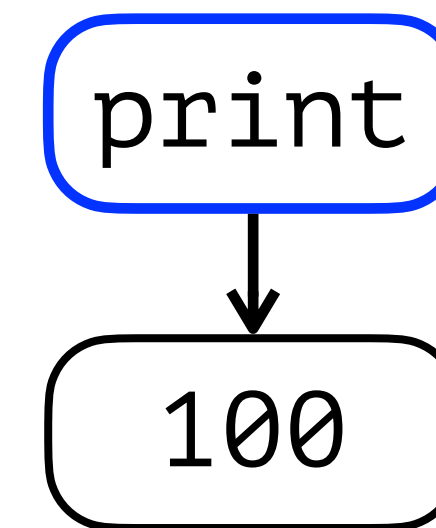
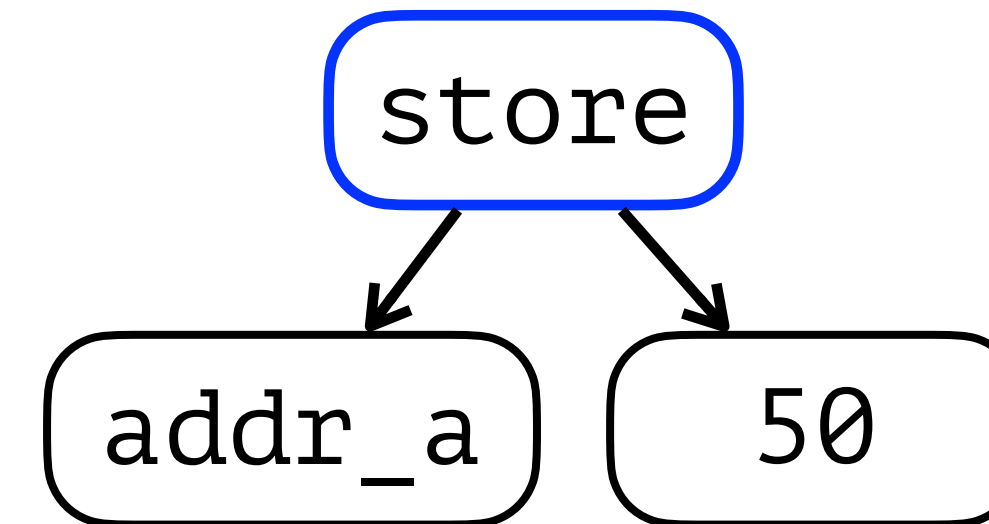
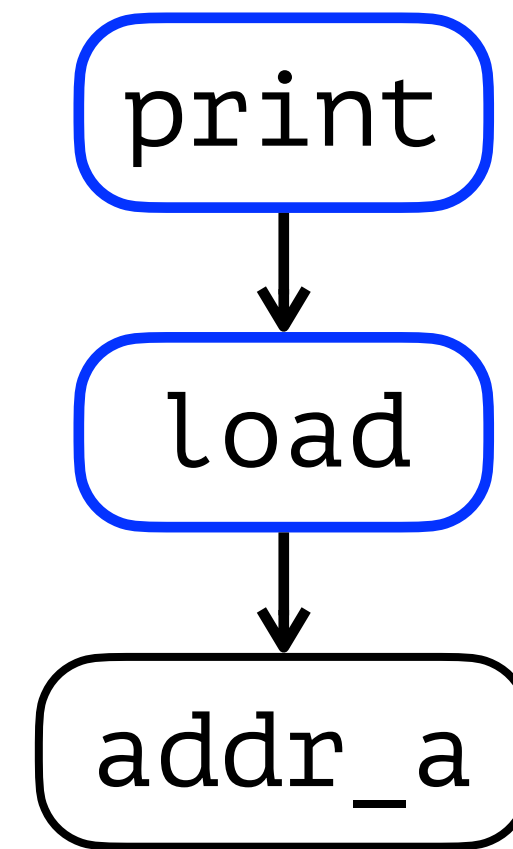
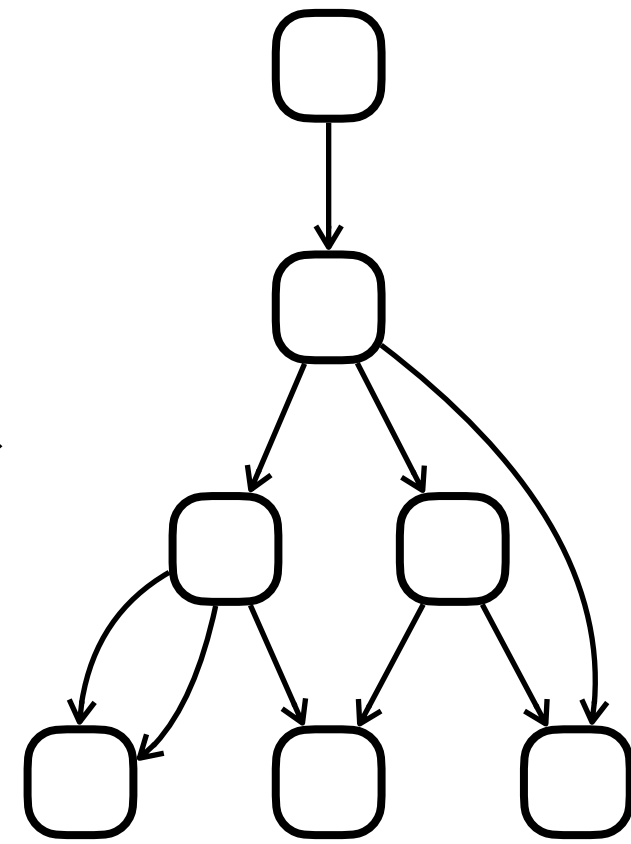
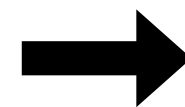
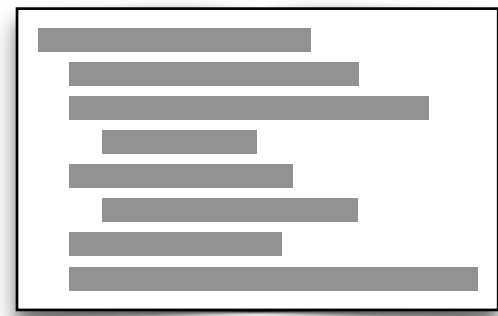


**Can we use this approach for programs with side effects?**

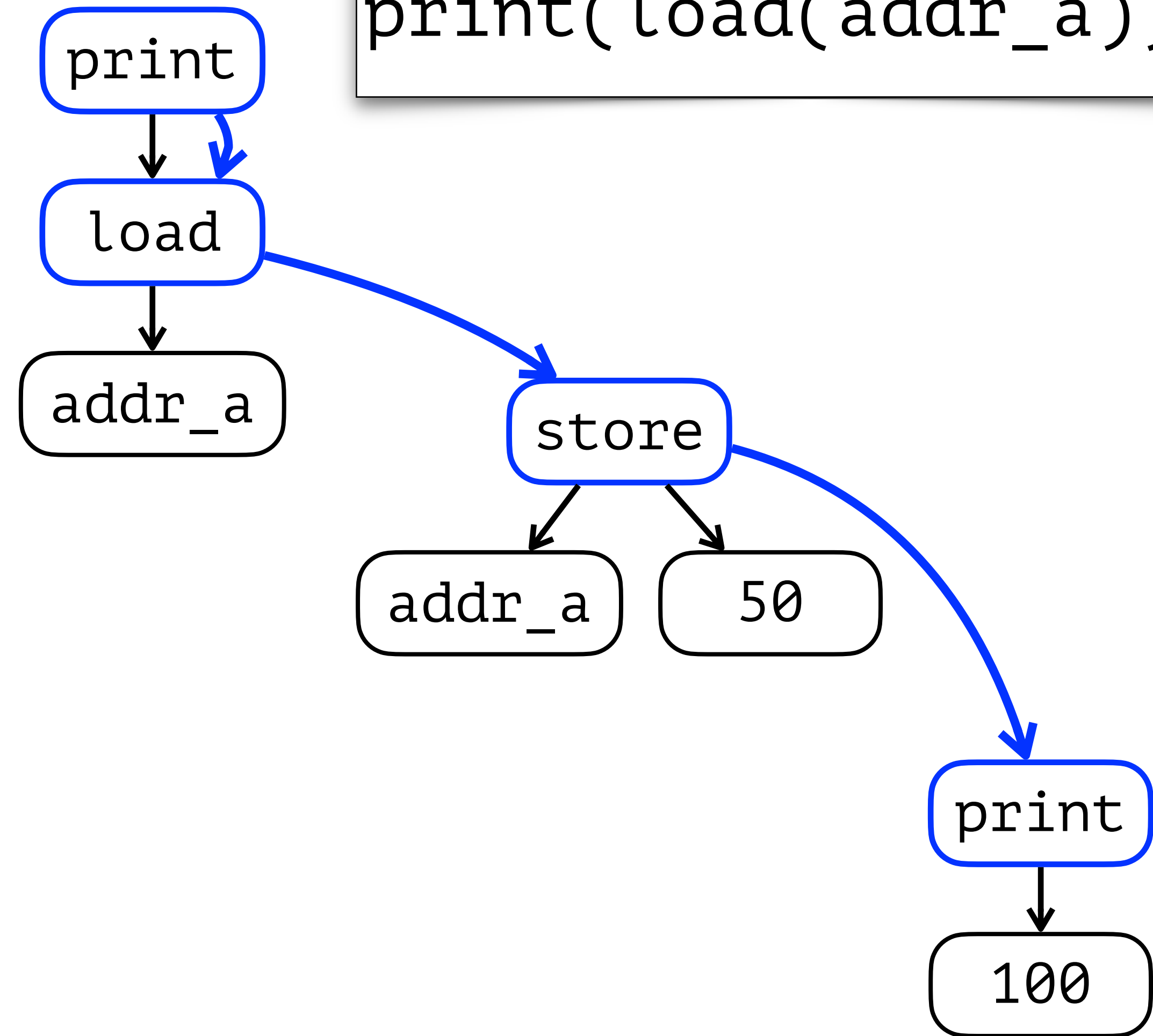
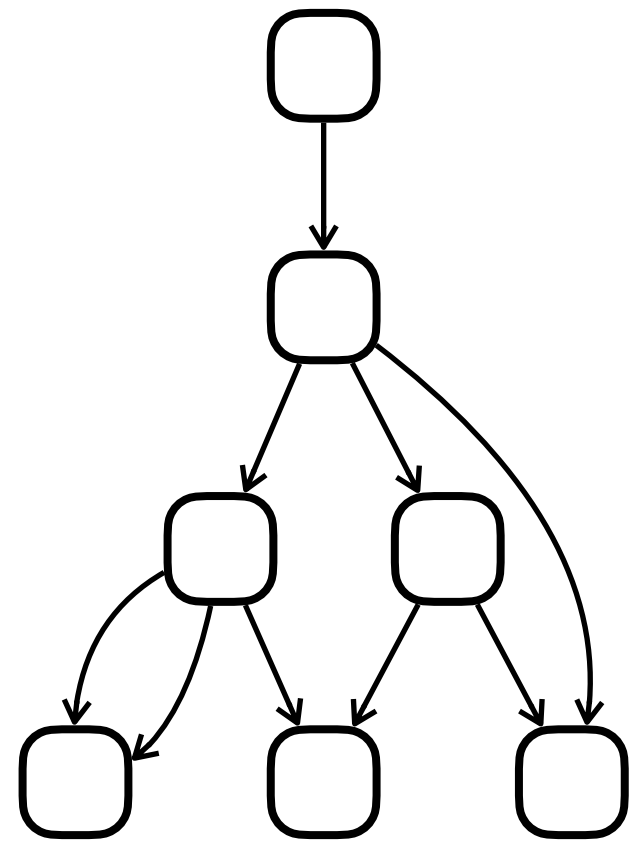
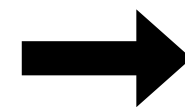
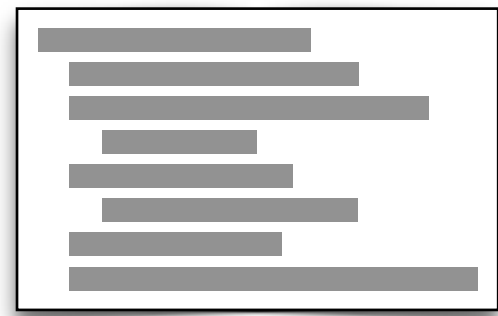
Memory operations, input/output, mutating state, and more

```
print(100)
store(addr_a, 50)
print(load(addr_a))
```





```
print(100)
store(addr_a, 50)
print(load(addr_a))
```

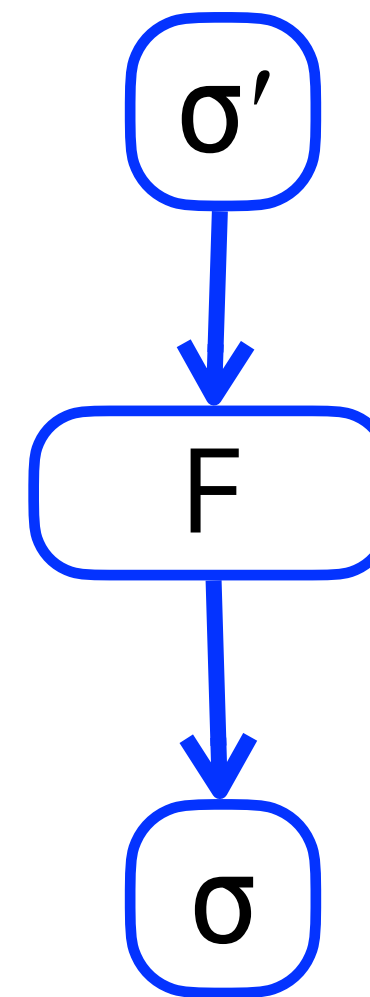


```
print(100)
```

```
store(addr_a, 50)
```

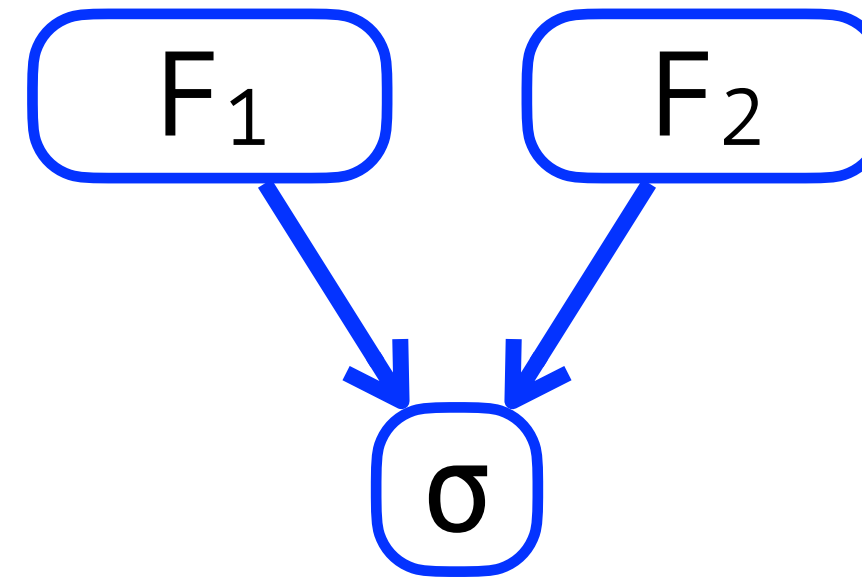
```
print(load(addr_a))
```

# State Values



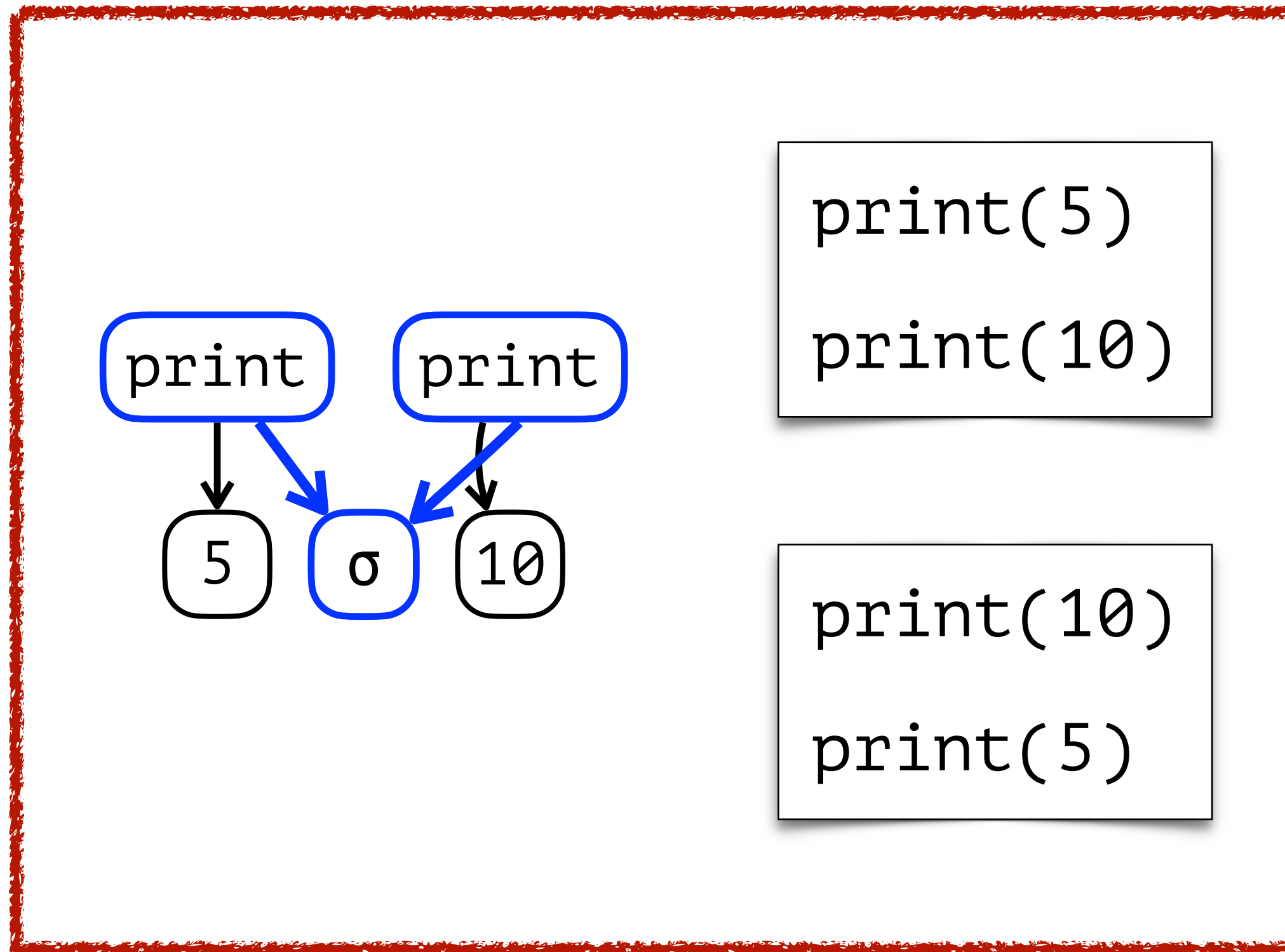
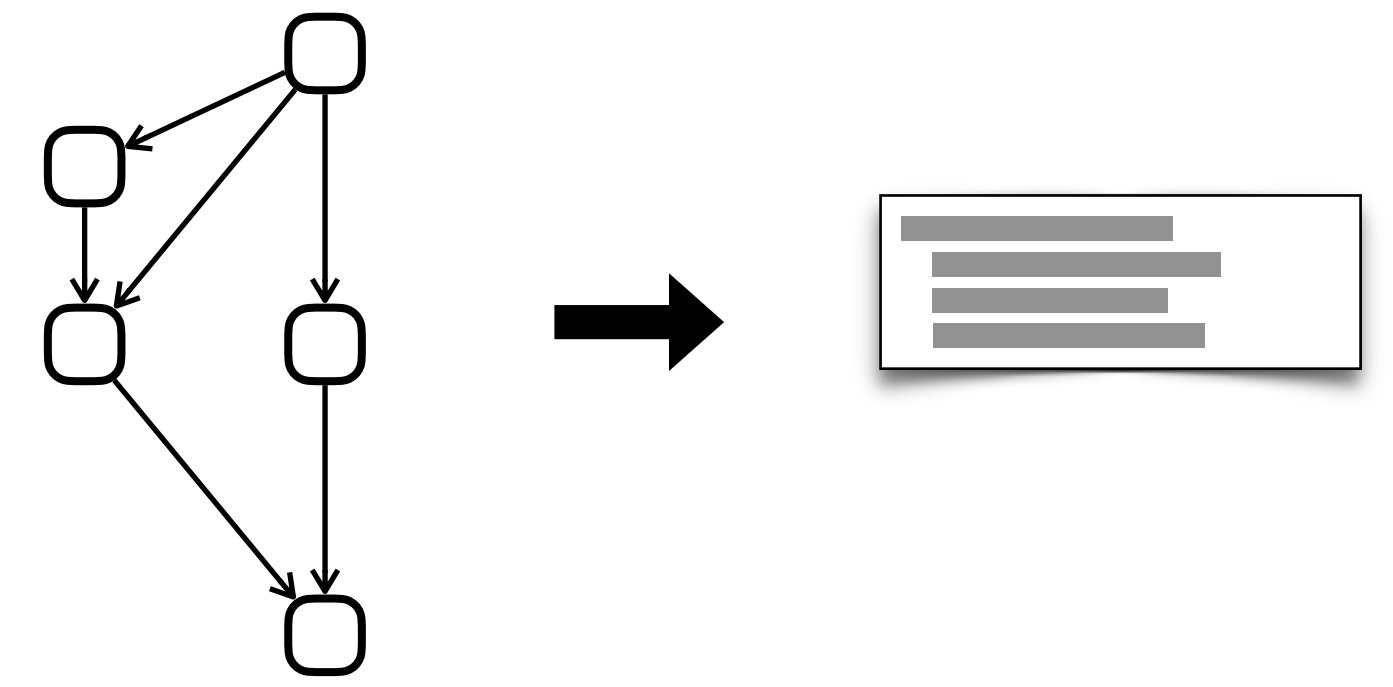
**Any operator that takes a state value as input must produce a new state value as output**

# State Values



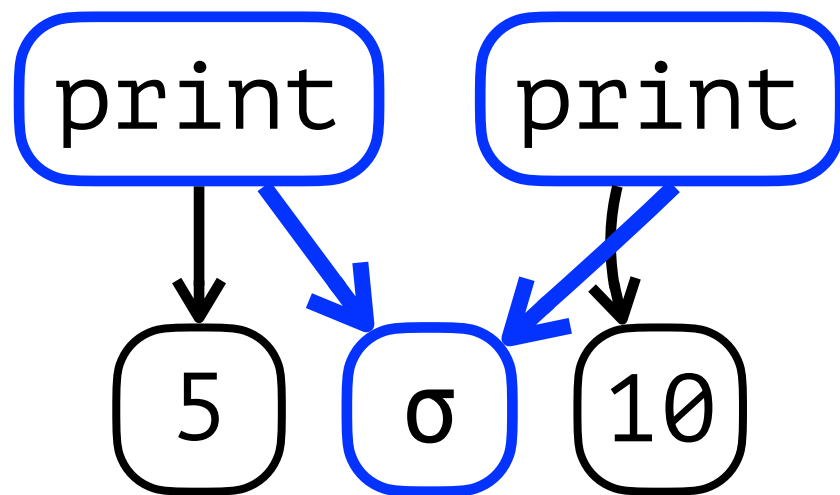
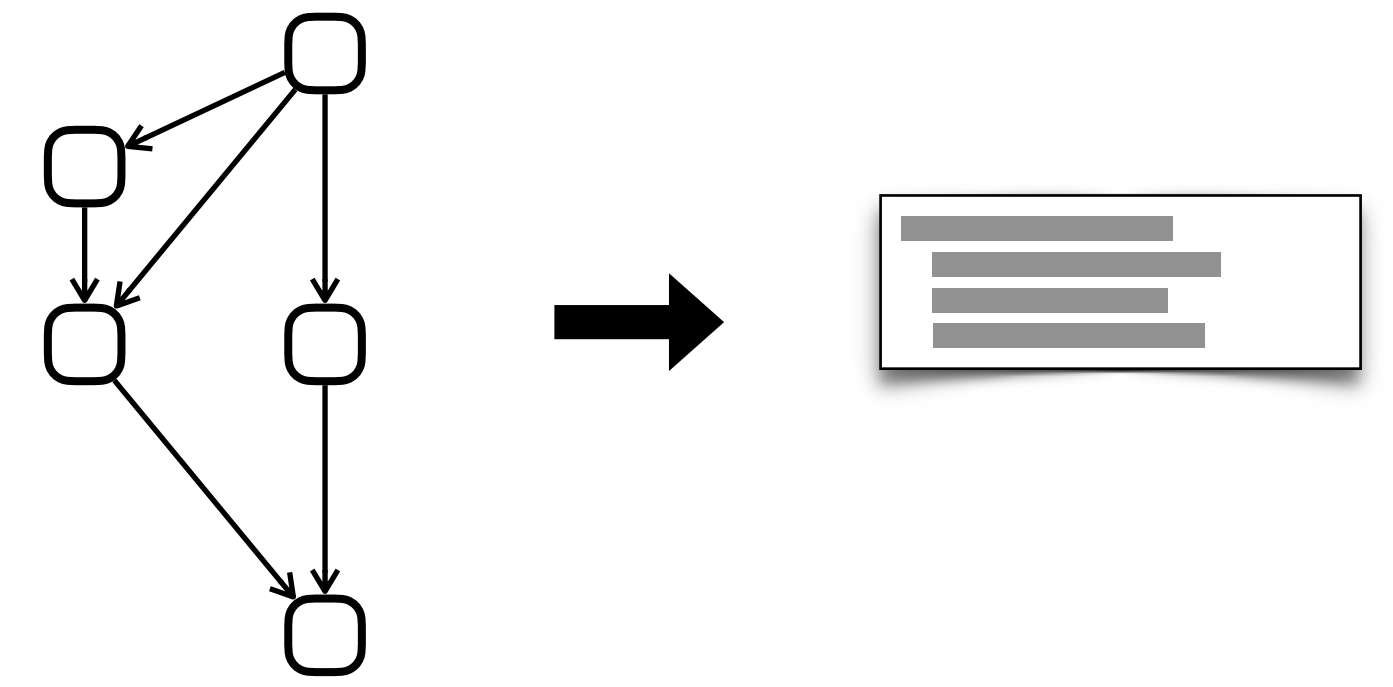
**“Forking” the state value is not allowed**

# State Values



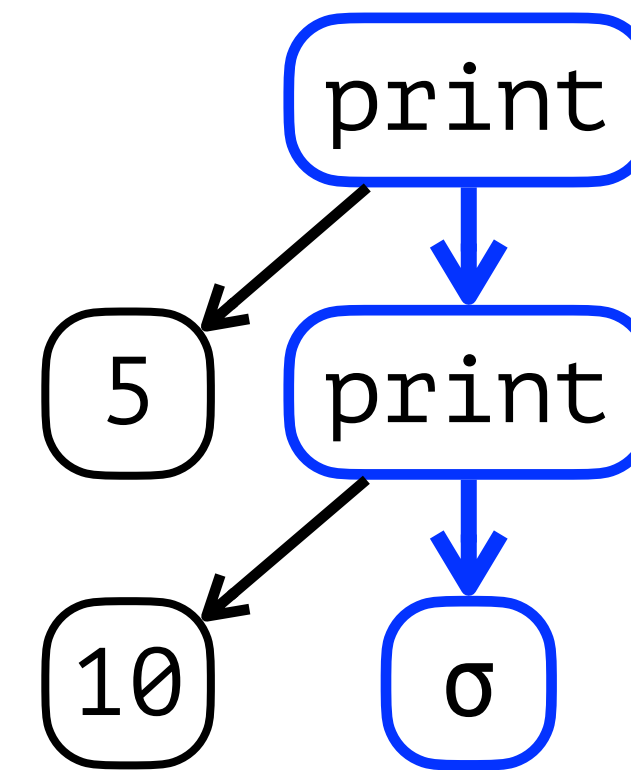
**“Forking” the state value is not allowed**

# State Values

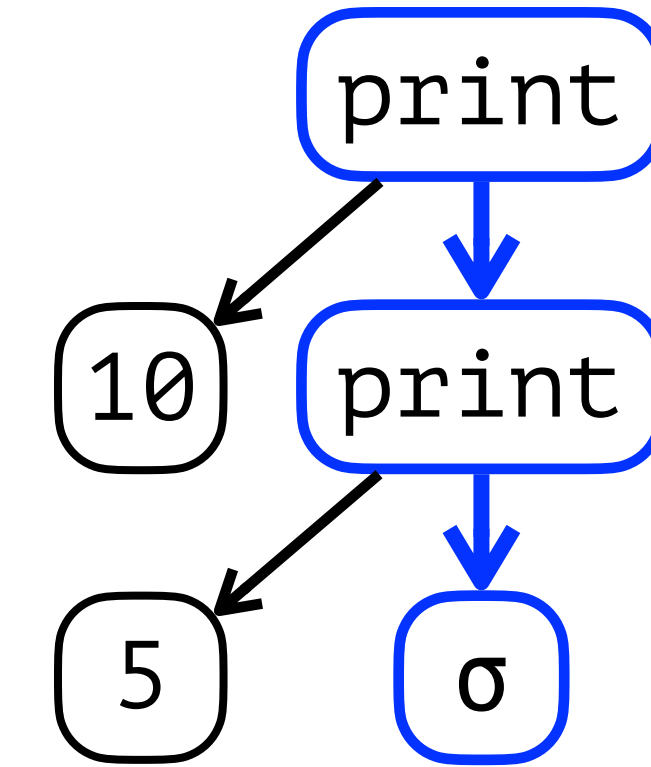


```
print(5)
print(10)
```

```
print(10)
print(5)
```



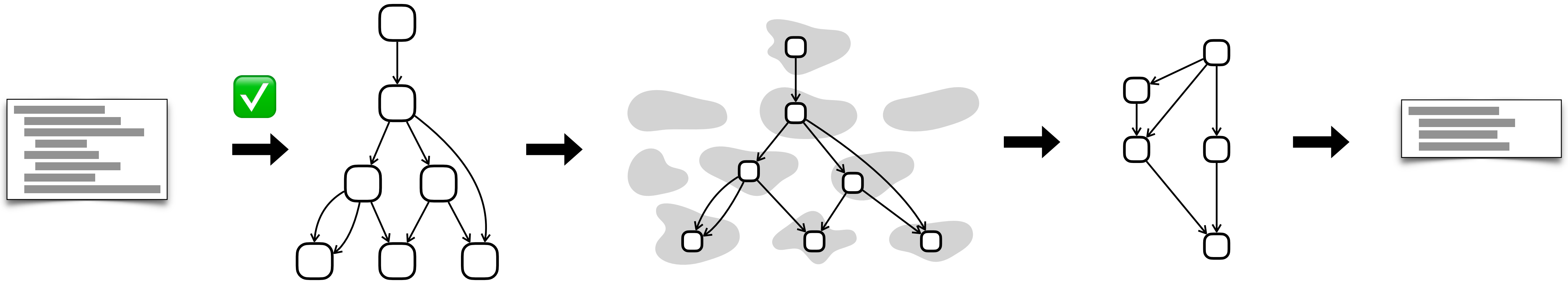
```
print(10)
print(5)
```



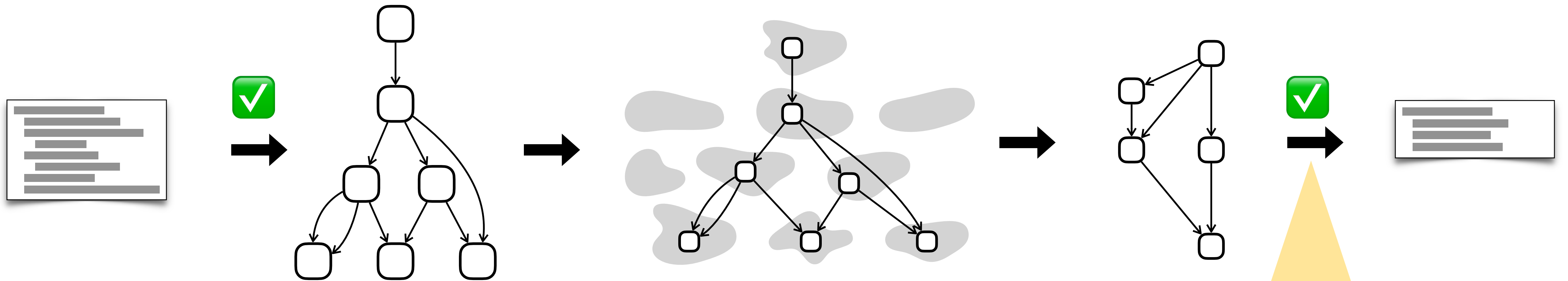
```
print(5)
print(10)
```

**“Forking” the state value is not allowed**

# Effectful Program Optimization with E-Graphs



# Effectful Program Optimization with E-Graphs



**Reconstruction succeeds if effectful operations form a linear sequence**

# Program Equivalence with Side Effects

```
def foo(x):  
    print(x)  
    return x * 2  
  
a = foo(10)  
b = foo(5) + foo(5)
```

Are a and b equivalent?

**Yes! a and b are both 20**

**No! They print different things**

# Two Equivalence Relations

Terms are equivalent if they have the same value.

**Important for optimization**

Terms are equivalent if they have the same value **and the same side effects.**

**Important for correctness**

# Update

```
x = update(a, v)
```

# Update

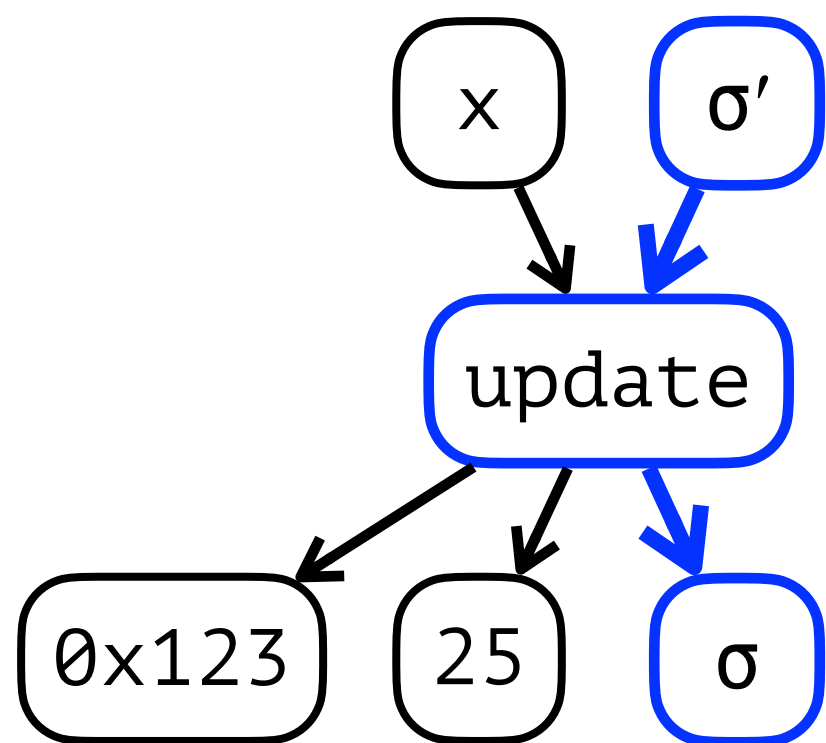
```
x = update(a, v)
```

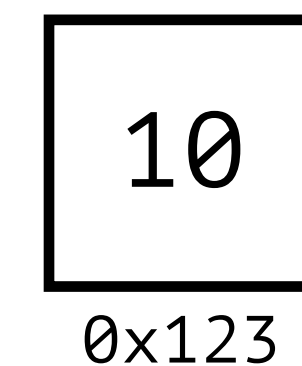
Writes  $v$  to memory location  $a$ ,  
returns the previous value stored there

# Update

$$x = \text{update}(a, v)$$

Writes  $v$  to memory location  $a$ ,  
returns the previous value stored there

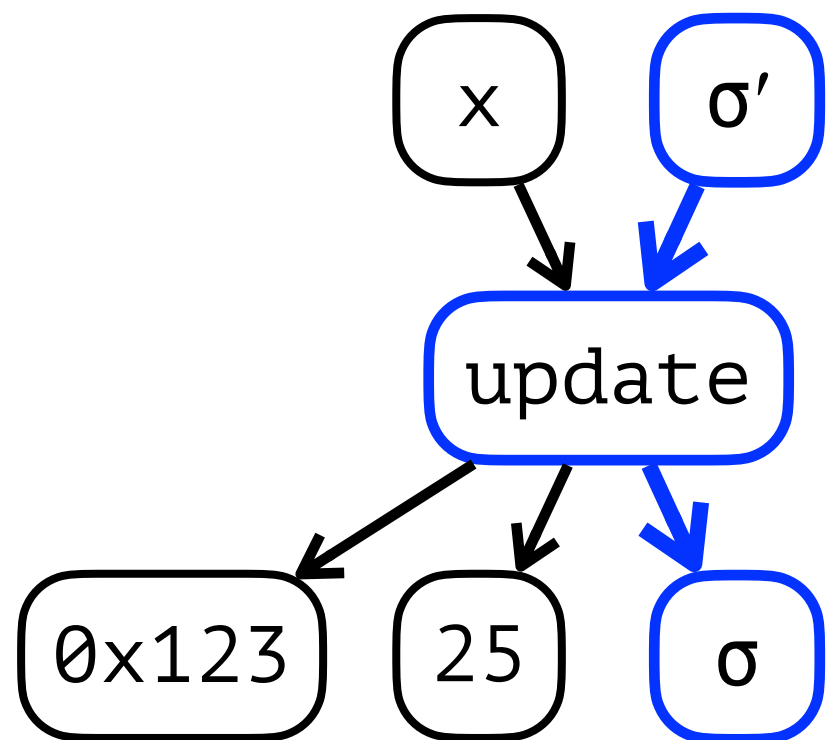


$$x = \text{update}(0x123, 25)$$


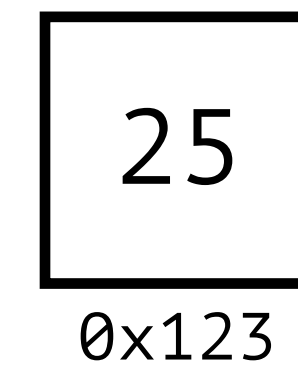
# Update

```
x = update(a, v)
```

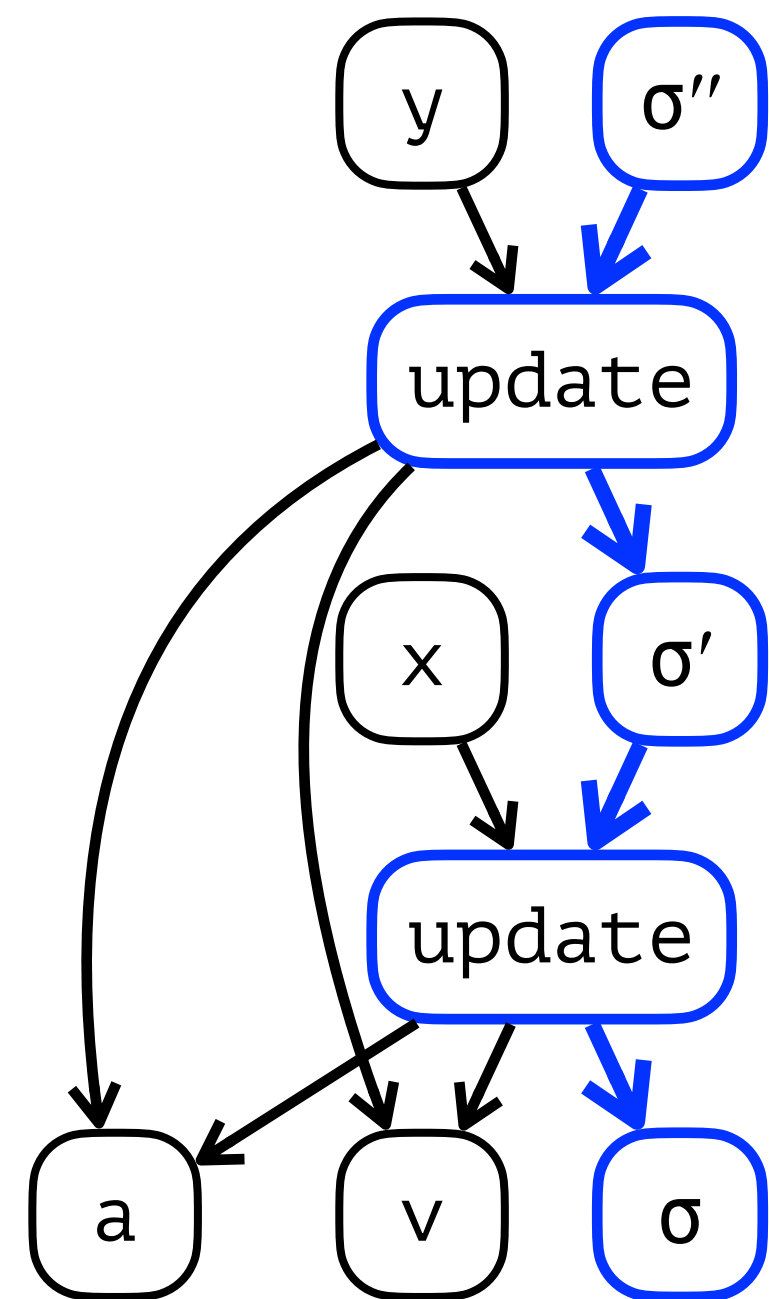
Writes  $v$  to memory location  $a$ ,  
returns the previous value stored there



```
x = update(0x123, 25)
// x is 10
```



# Redundant Update Elimination

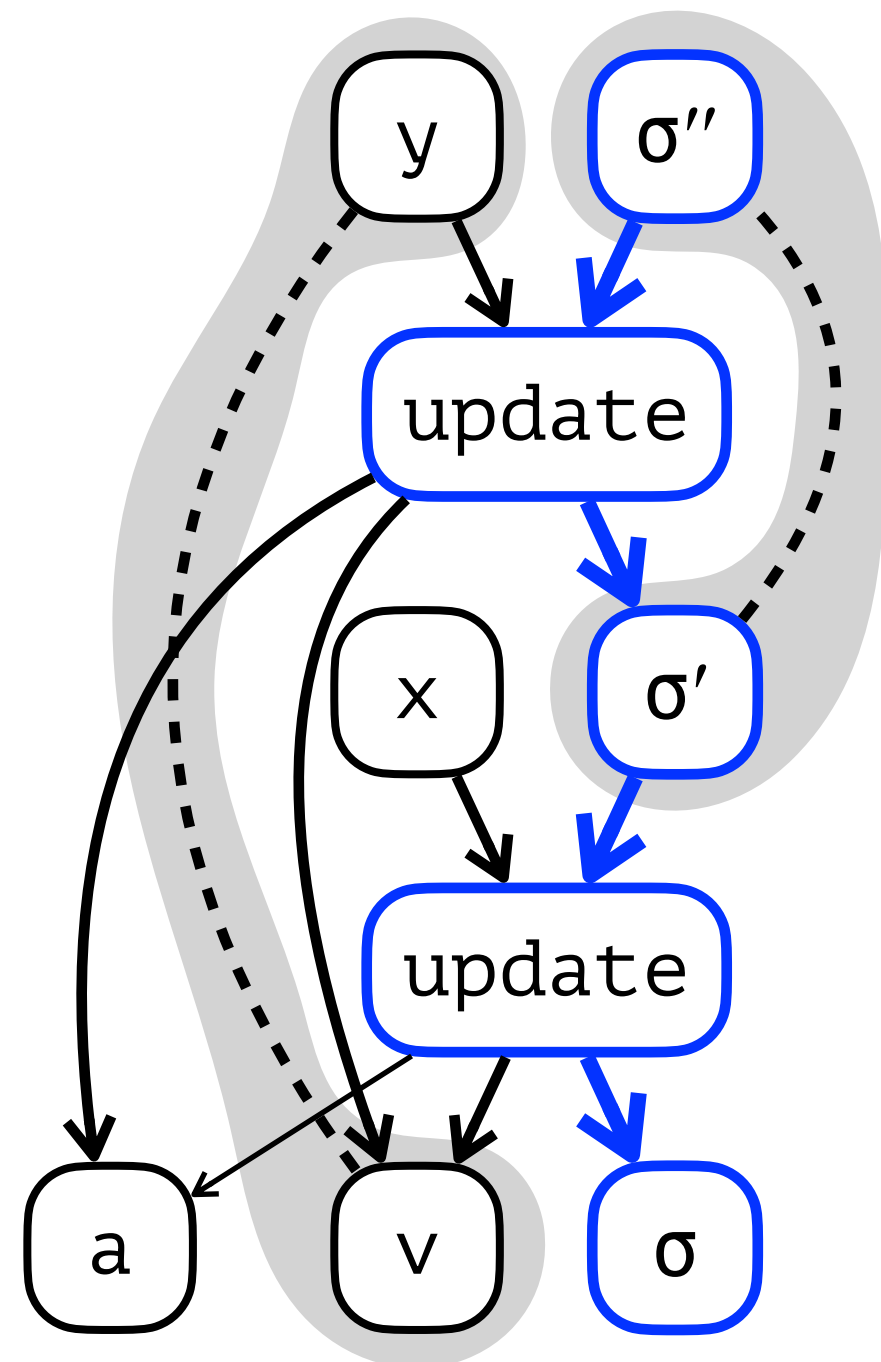


$$x = \text{update}(a, v)$$

$$y = \text{update}(a, v)$$

update is idempotent

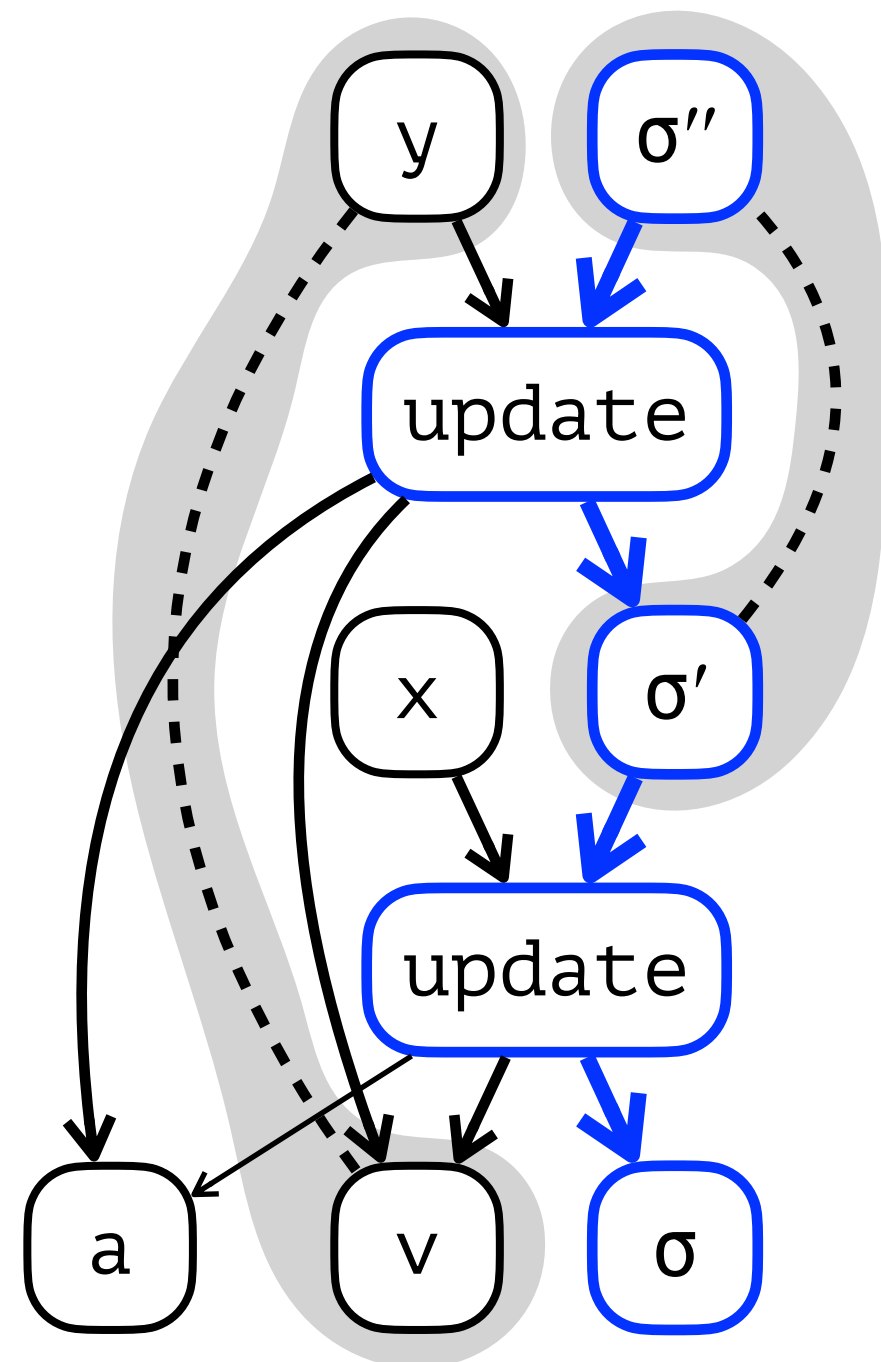
# Redundant Update Elimination



```
x = update(a, v)
y = update(a, v)
```

update is idempotent

# Redundant Update Elimination

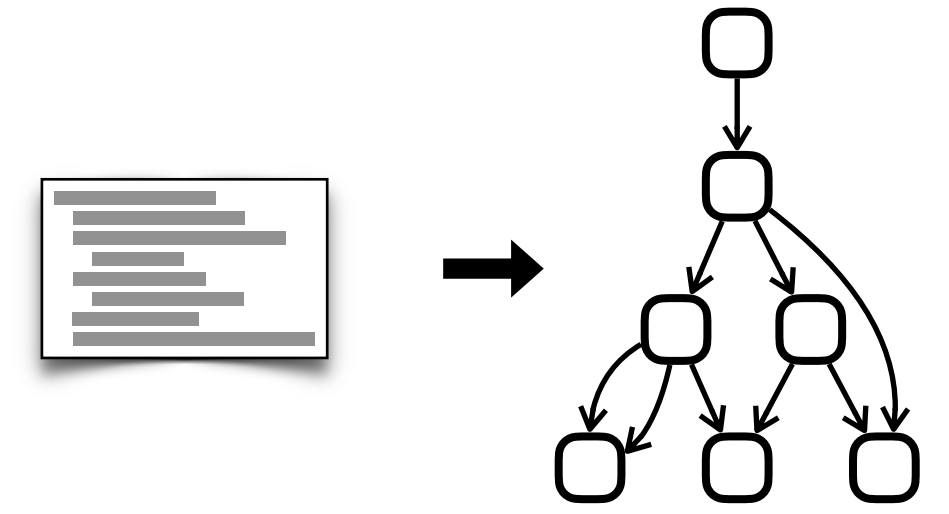


```
x = update(a, v)
y = update(a, v)
```

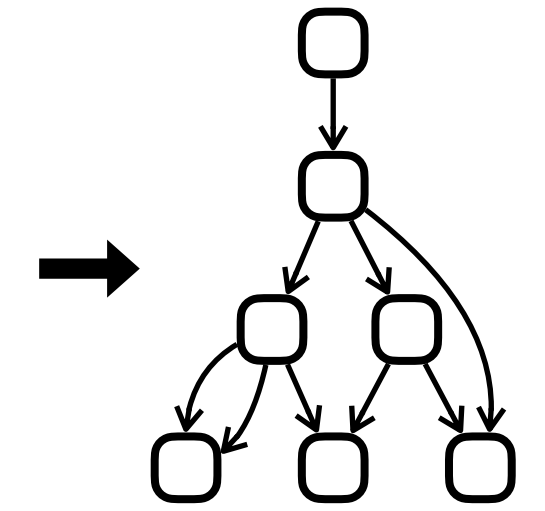
update is idempotent

## Is this optimization safe?

# Redundant Update Elimination


$$(v_1, \sigma_1) = \text{update}(a, x)$$
$$(v_2, \sigma_2) = \text{update}(a, x)$$
$$(v_3, \sigma_3) = \text{update}(b, y)$$
$$(v_4, \sigma_4) = \text{update}(c, v_2)$$

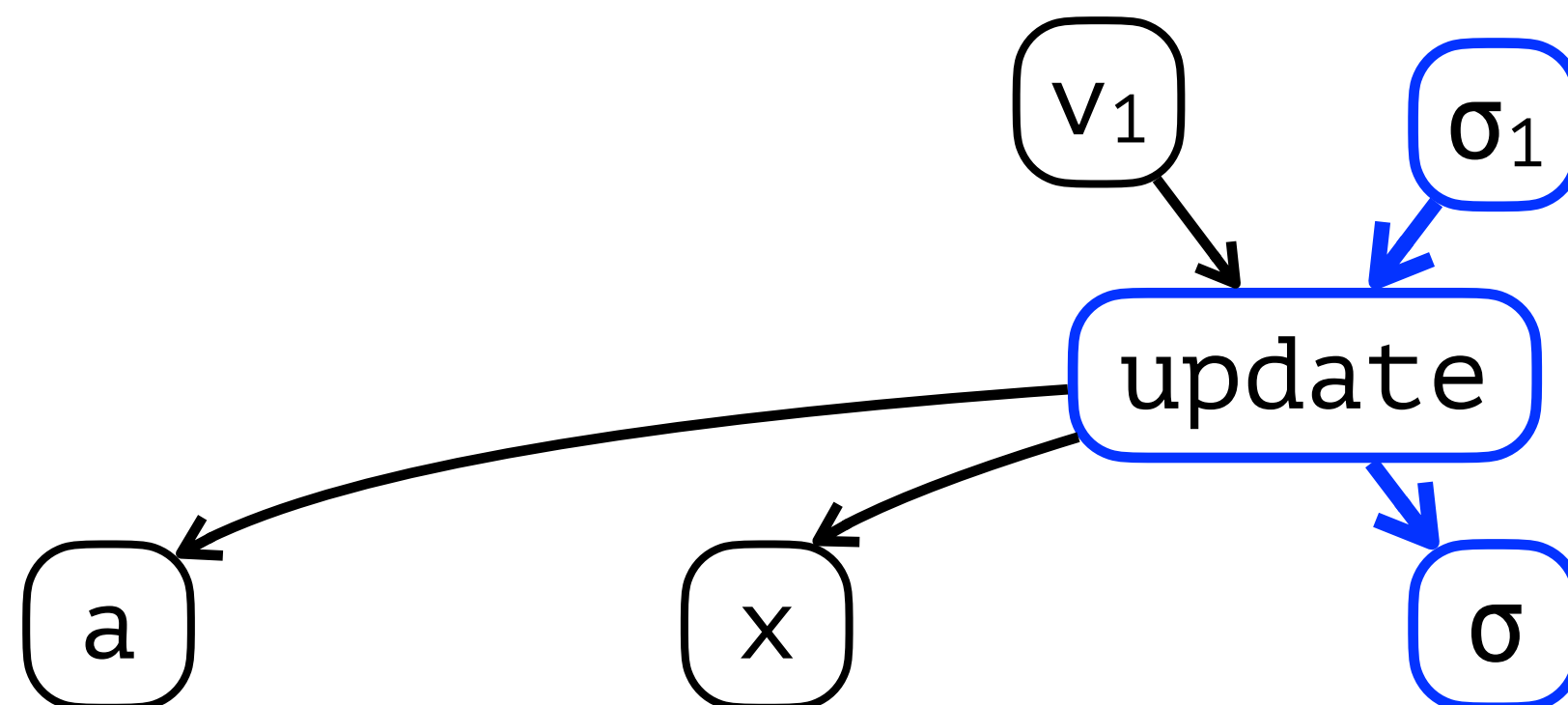
# Redundant Update Elimination



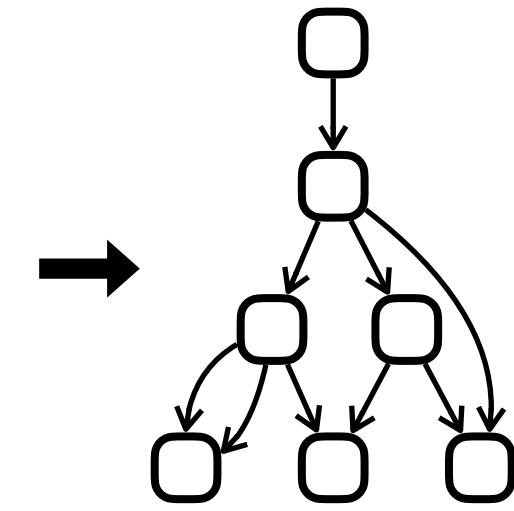
$$(v_1, \sigma_1) = \text{update}(a, x)$$

$$(v_2, \sigma_2) = \text{update}(a, x)$$

$$(v_3, \sigma_3) = \text{update}(b, y)$$

$$(v_4, \sigma_4) = \text{update}(c, v_2)$$


# Redundant Update Elimination

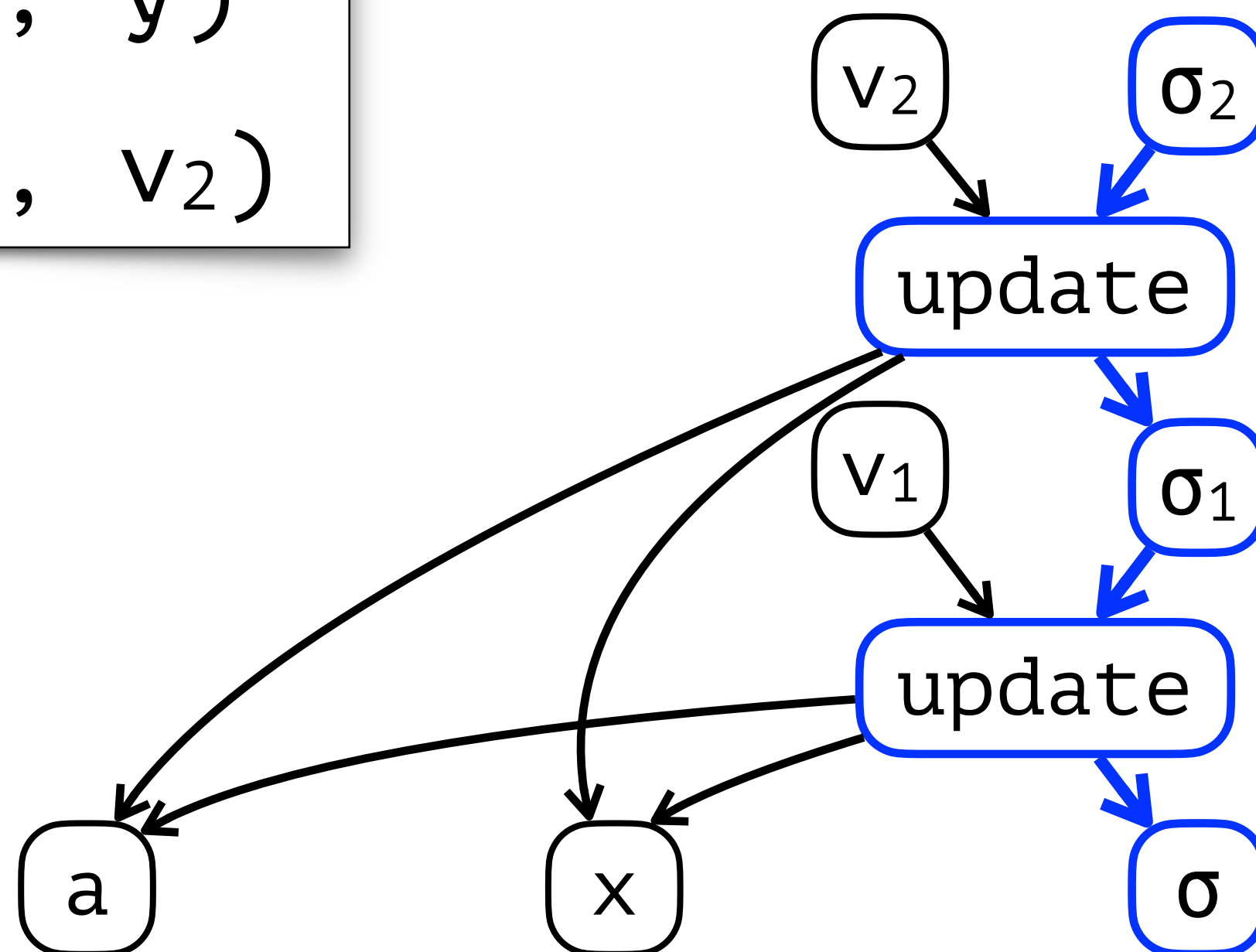


$(v_1, \sigma_1) = \text{update}(a, x)$

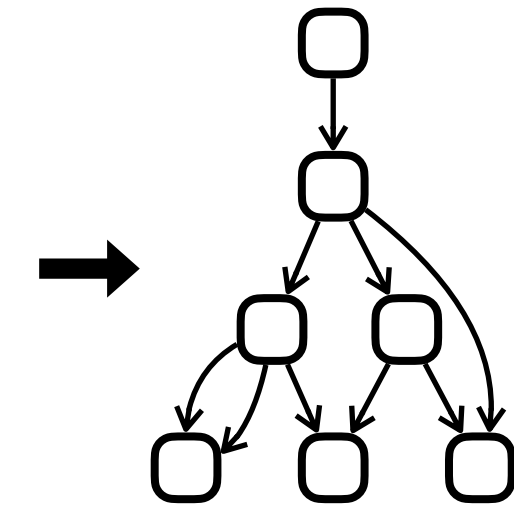
$(v_2, \sigma_2) = \text{update}(a, x)$

$(v_3, \sigma_3) = \text{update}(b, y)$

$(v_4, \sigma_4) = \text{update}(c, v_2)$



# Redundant Update Elimination

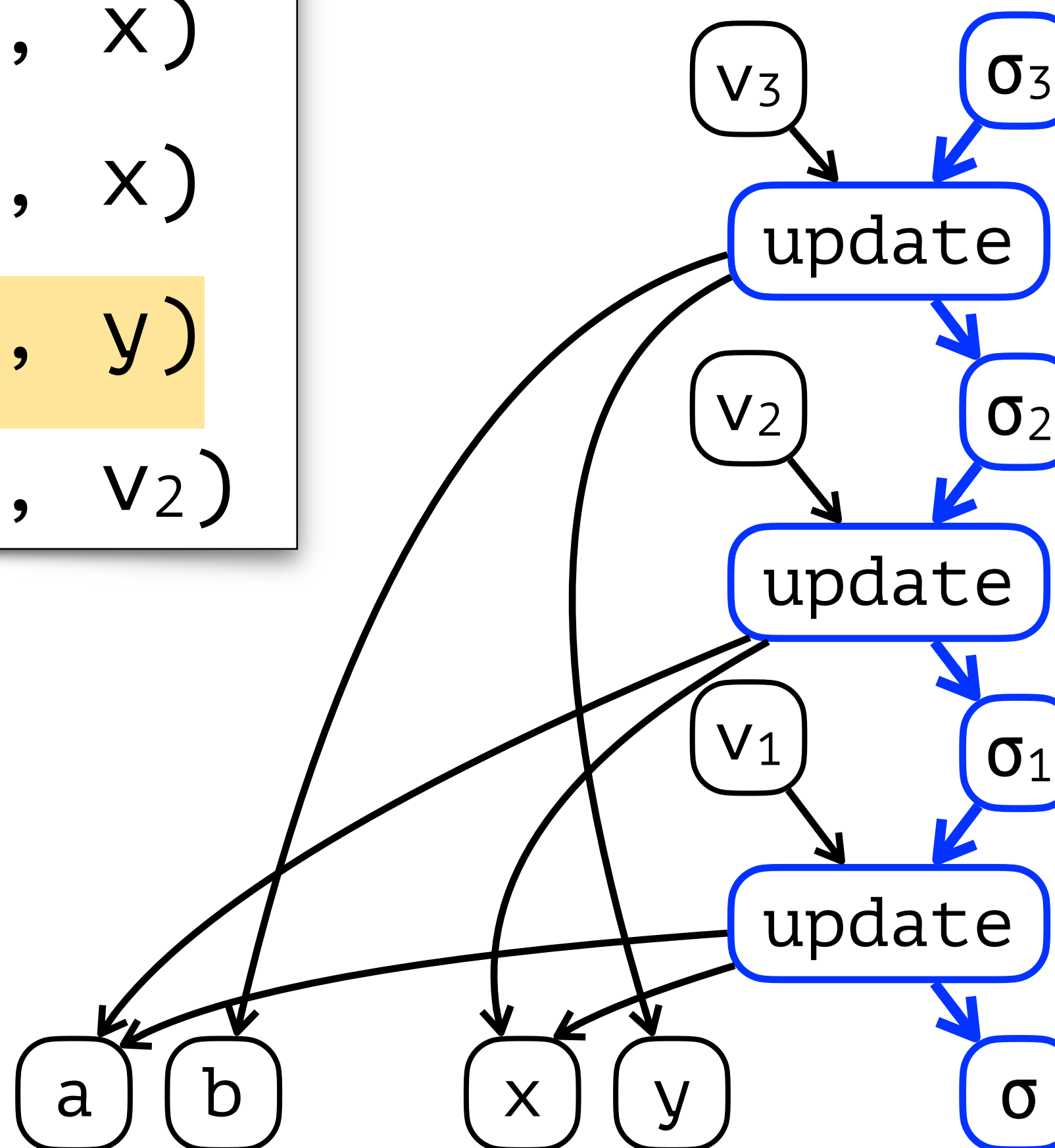


$(v_1, \sigma_1) = \text{update}(a, x)$

$(v_2, \sigma_2) = \text{update}(a, x)$

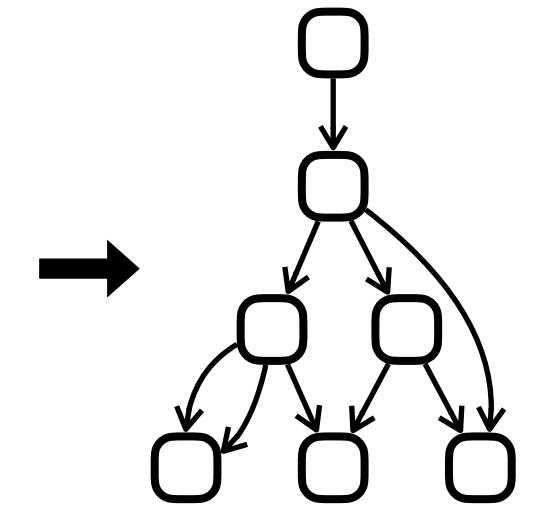
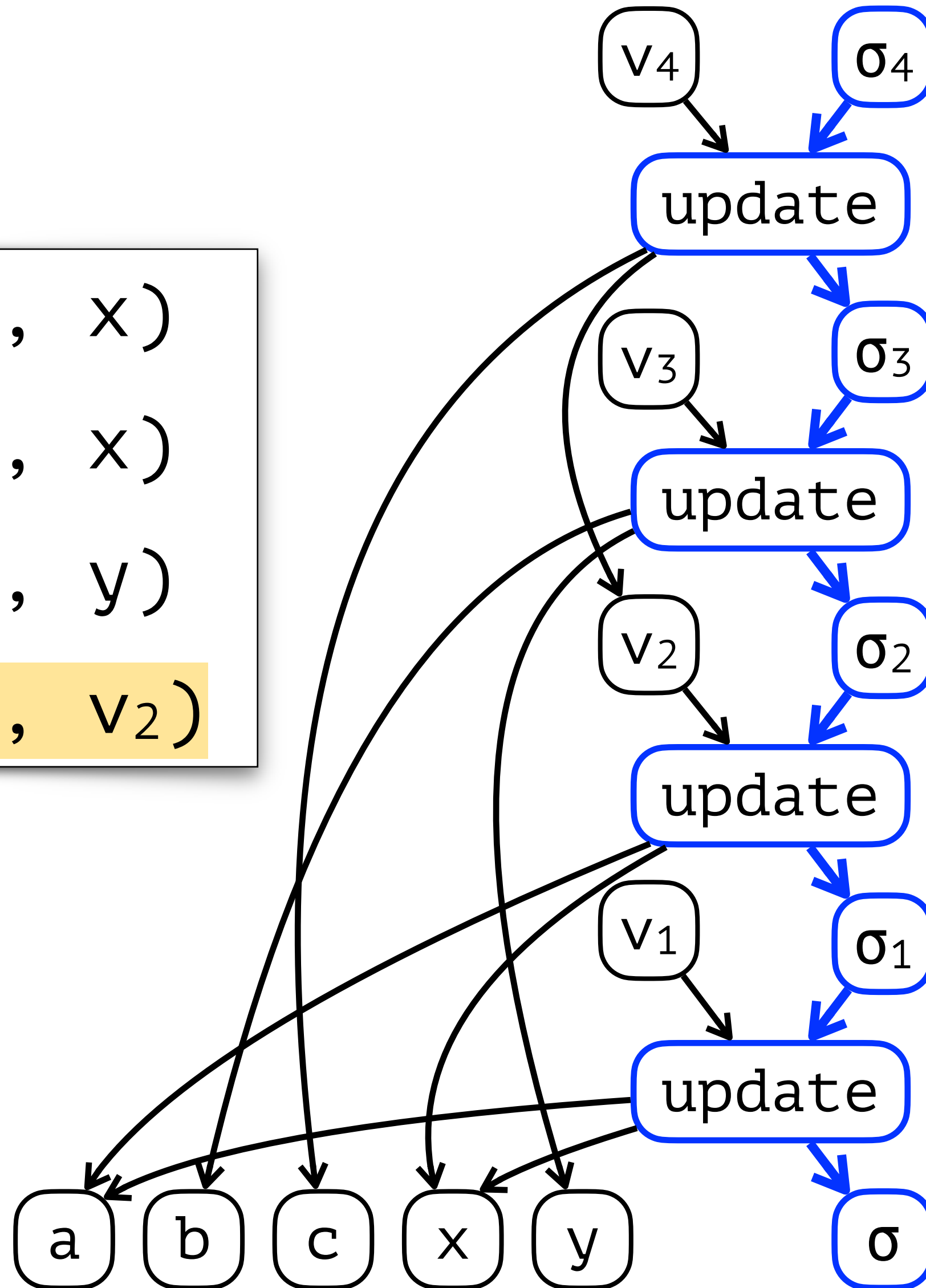
$(v_3, \sigma_3) = \text{update}(b, y)$

$(v_4, \sigma_4) = \text{update}(c, v_2)$



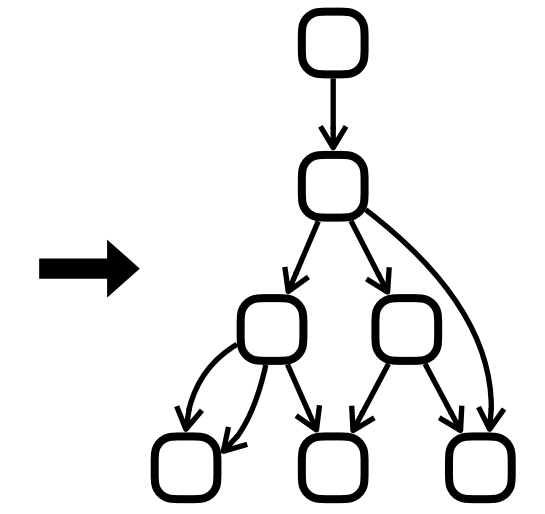
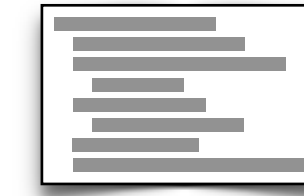
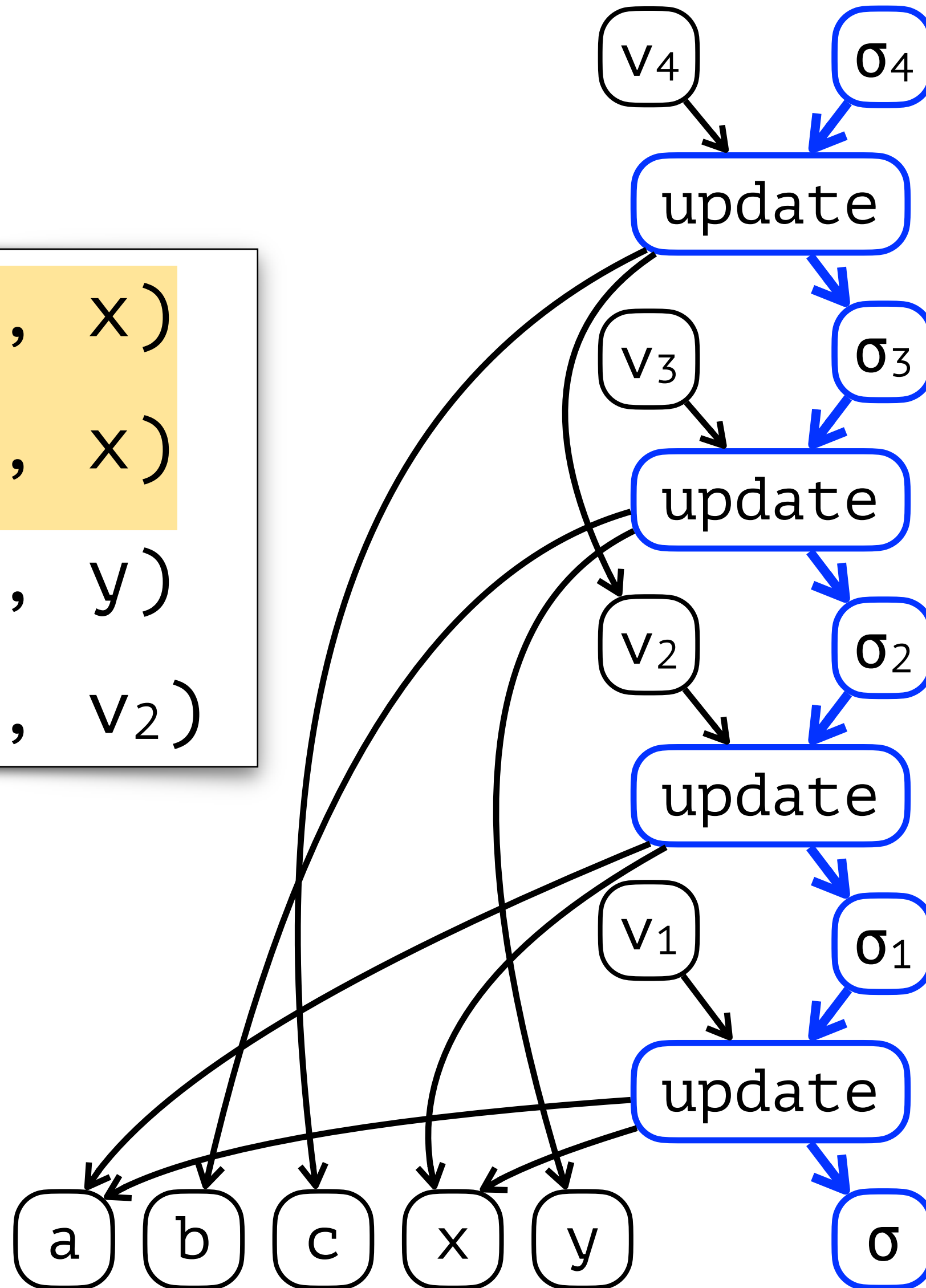
# Redundant Update Elimination

$(v_1, \sigma_1) = \text{update}(a, x)$   
 $(v_2, \sigma_2) = \text{update}(a, x)$   
 $(v_3, \sigma_3) = \text{update}(b, y)$   
 $(v_4, \sigma_4) = \text{update}(c, v_2)$



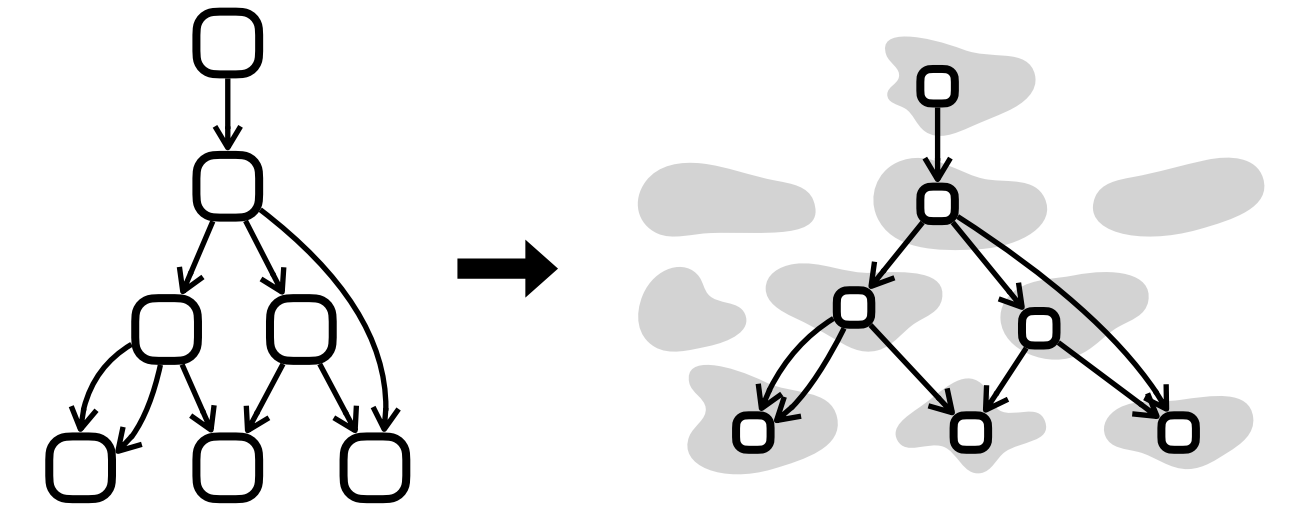
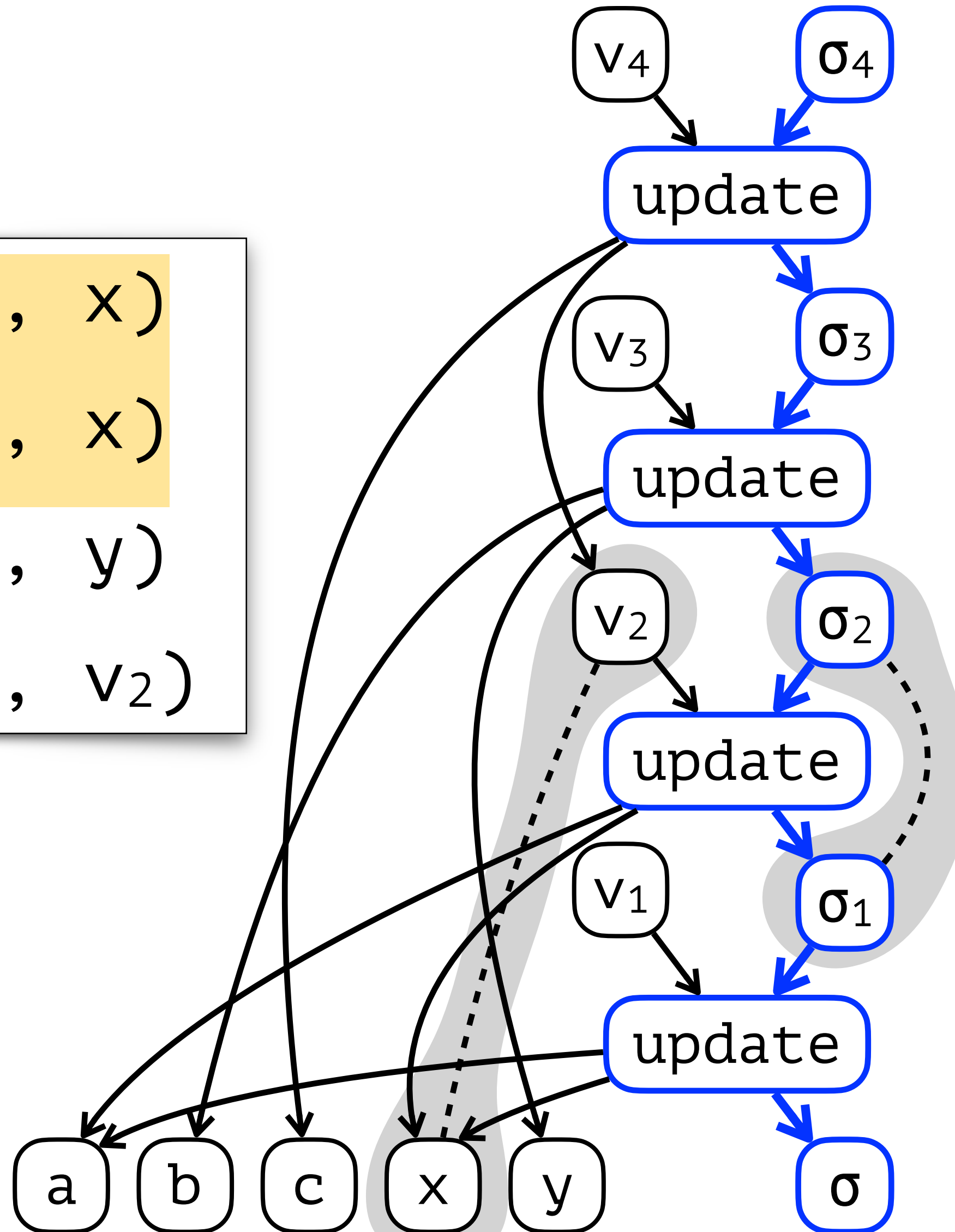
# Redundant Update Elimination

$(v_1, \sigma_1) = \text{update}(a, x)$   
 $(v_2, \sigma_2) = \text{update}(a, x)$   
 $(v_3, \sigma_3) = \text{update}(b, y)$   
 $(v_4, \sigma_4) = \text{update}(c, v_2)$

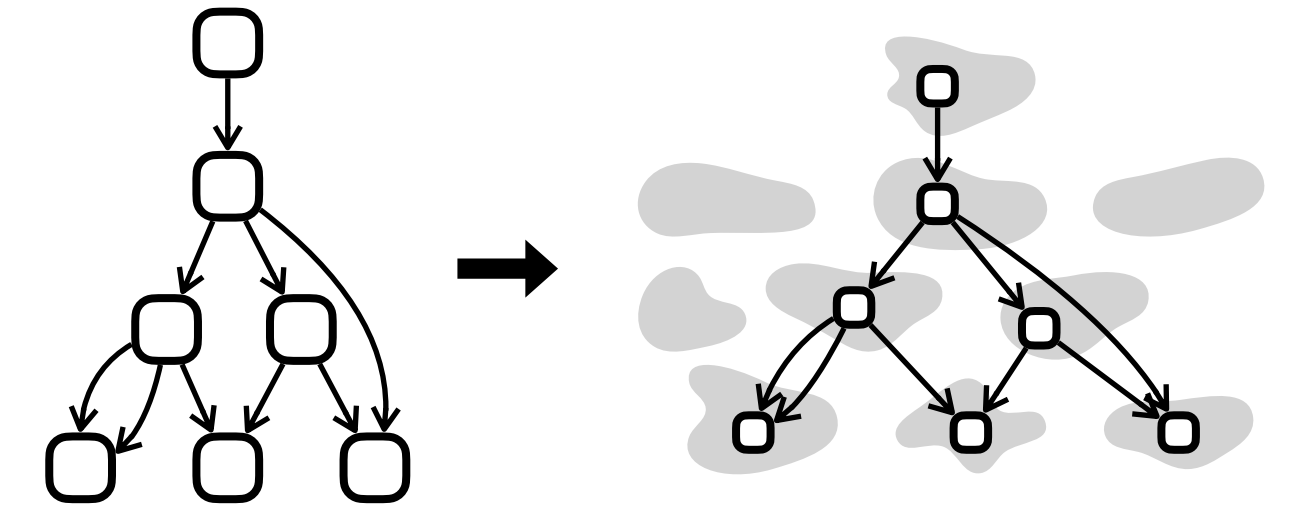


# Redundant Update Elimination

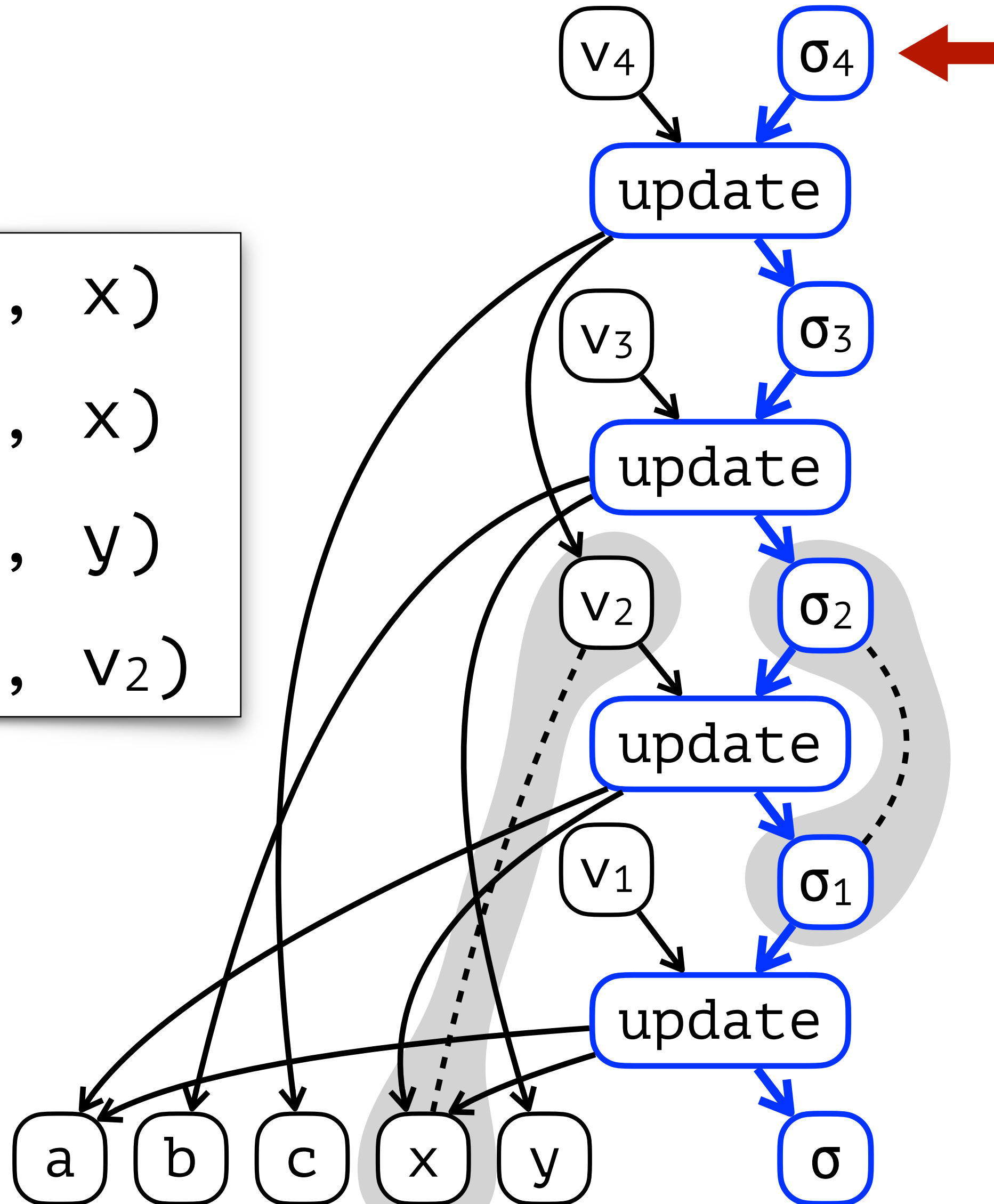
$(v_1, \sigma_1) = \text{update}(a, x)$   
 $(v_2, \sigma_2) = \text{update}(a, x)$   
 $(v_3, \sigma_3) = \text{update}(b, y)$   
 $(v_4, \sigma_4) = \text{update}(c, v_2)$



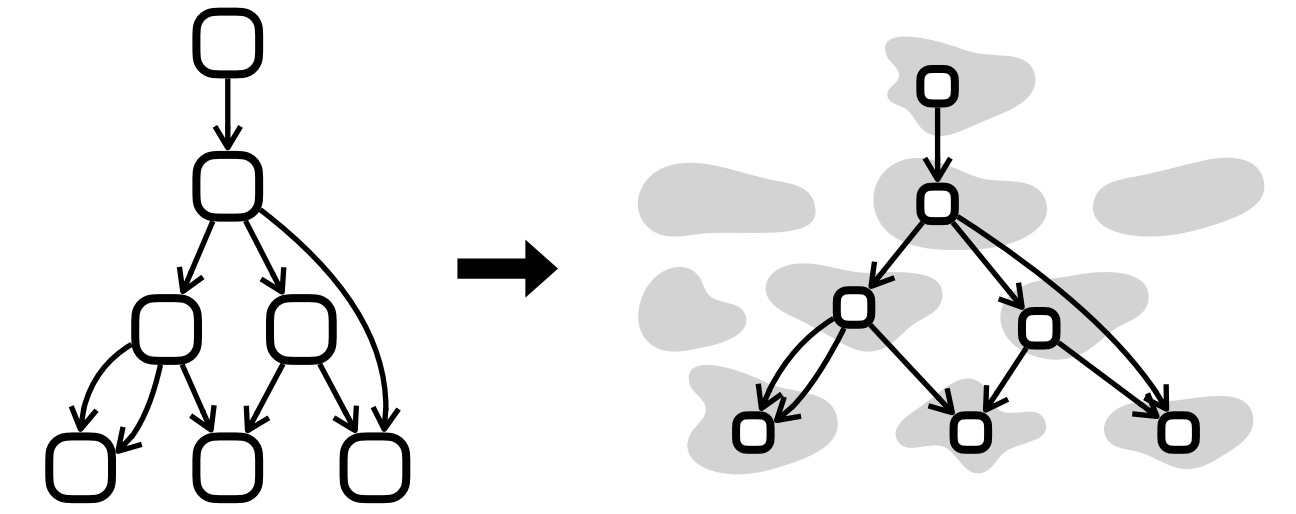
# Redundant Update Elimination



$(v_1, \sigma_1) = \text{update}(a, x)$   
 $(v_2, \sigma_2) = \text{update}(a, x)$   
 $(v_3, \sigma_3) = \text{update}(b, y)$   
 $(v_4, \sigma_4) = \text{update}(c, v_2)$

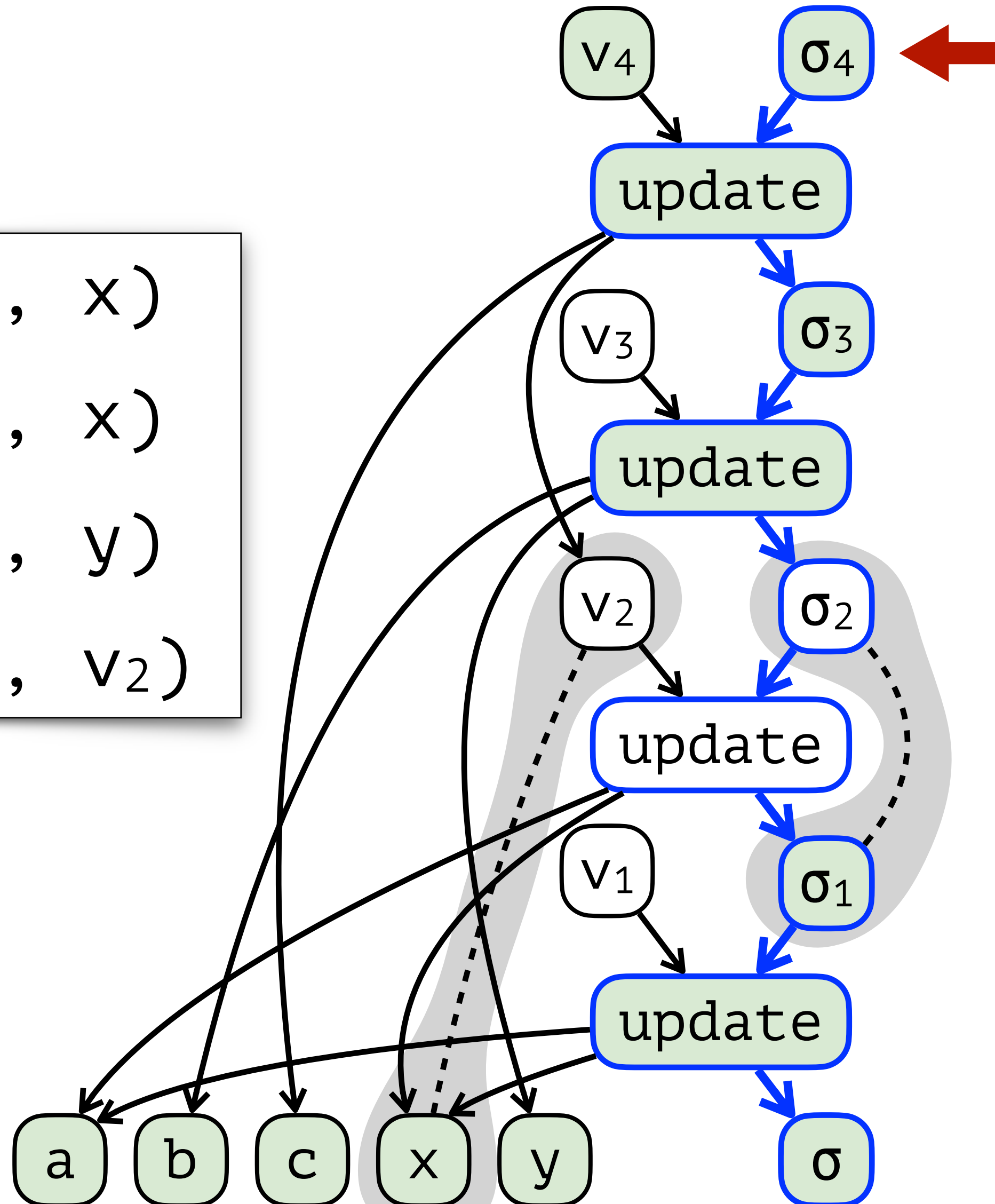


# Redundant Update Elimination

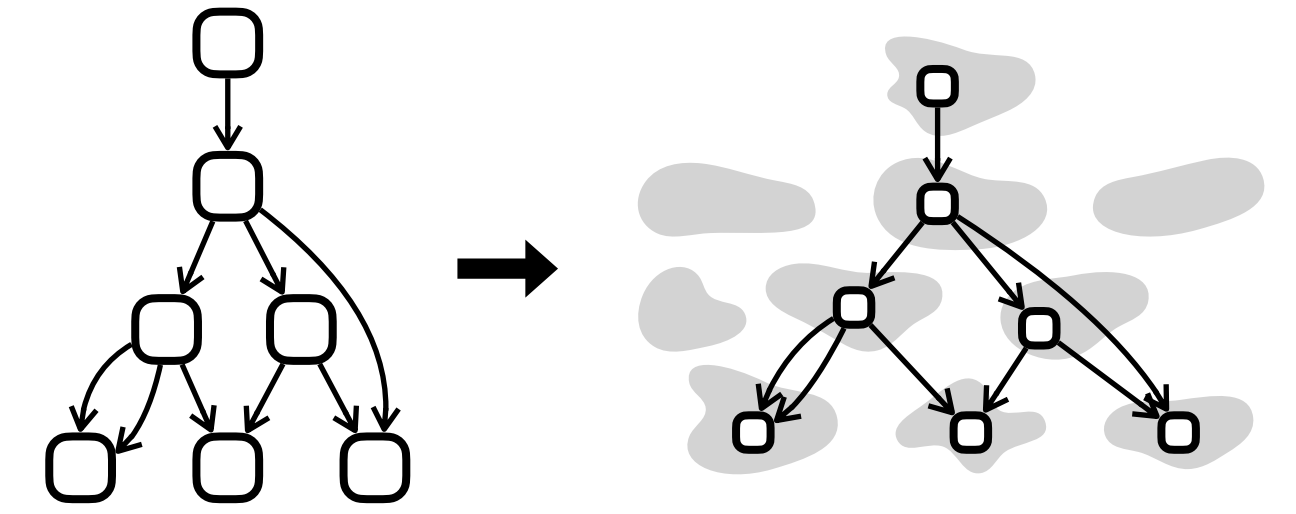


$(v_1, \sigma_1) = \text{update}(a, x)$   
 $(v_2, \sigma_2) = \text{update}(a, x)$   
 $(v_3, \sigma_3) = \text{update}(b, y)$   
 $(v_4, \sigma_4) = \text{update}(c, v_2)$

**Extraction Option 1**

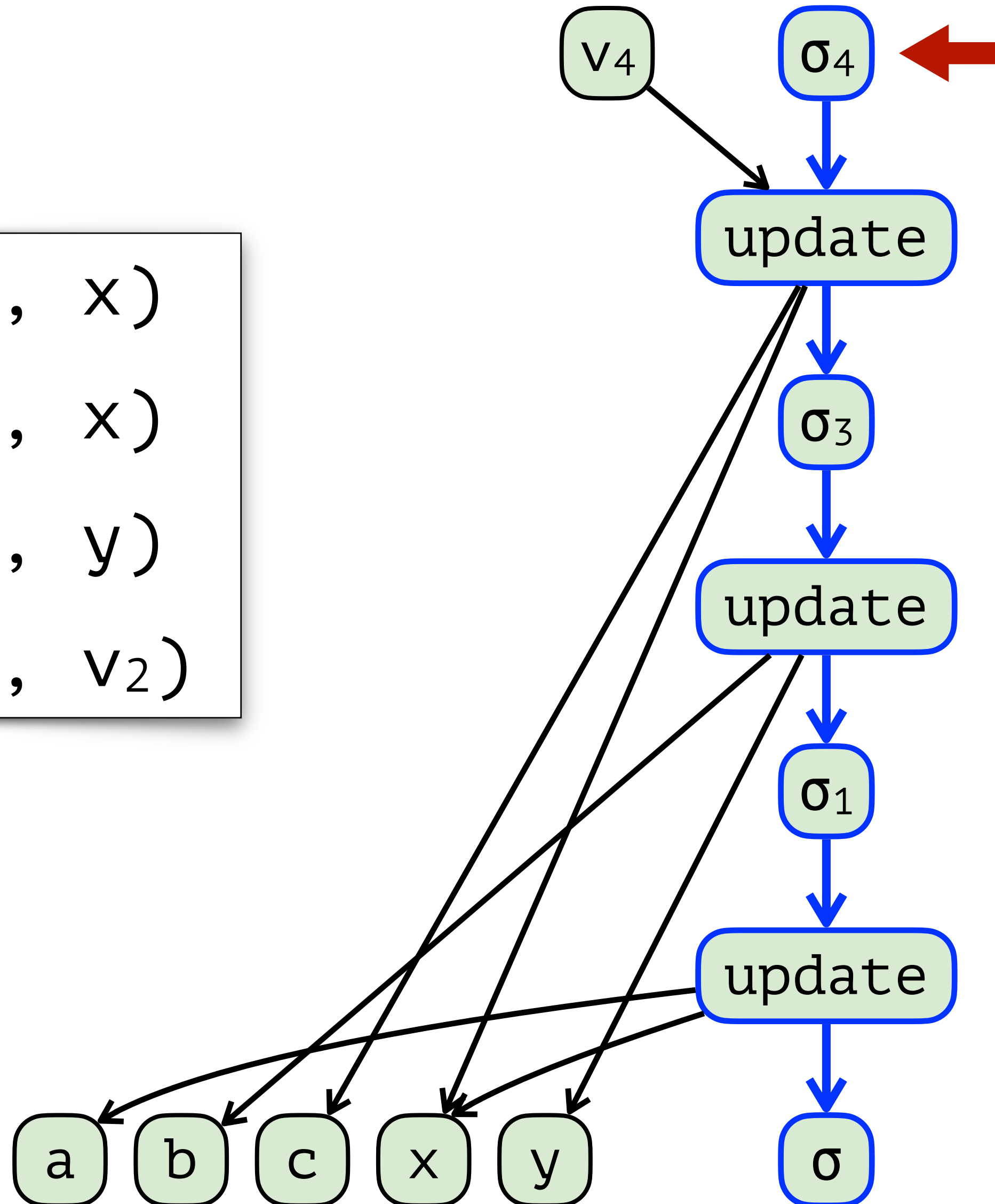


# Redundant Update Elimination

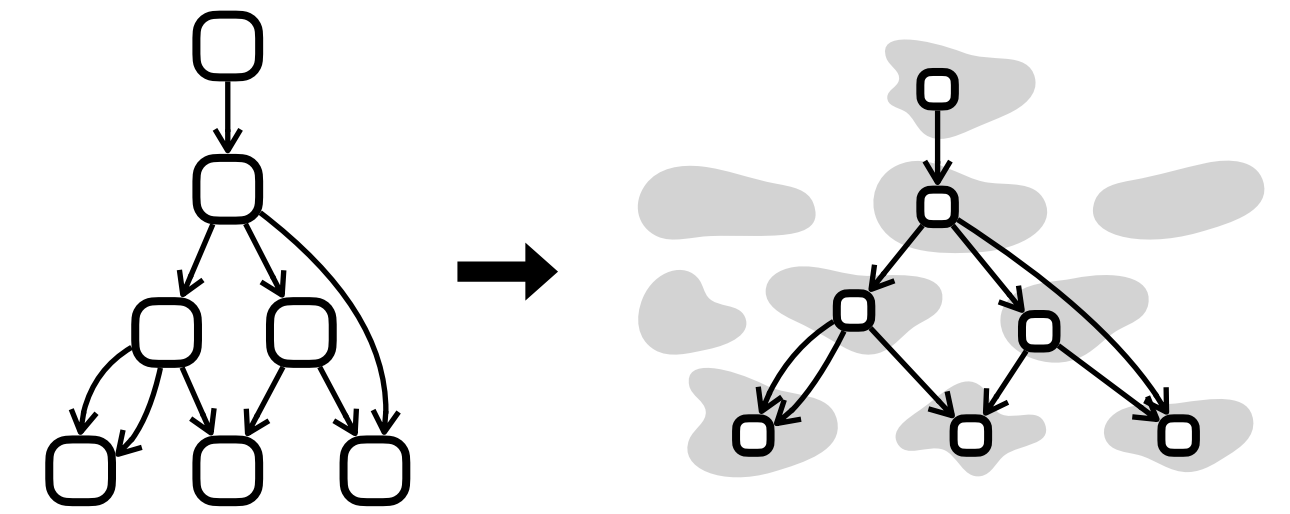


$(v_1, \sigma_1) = \text{update}(a, x)$   
 $(v_2, \sigma_2) = \text{update}(a, x)$   
 $(v_3, \sigma_3) = \text{update}(b, y)$   
 $(v_4, \sigma_4) = \text{update}(c, v_2)$

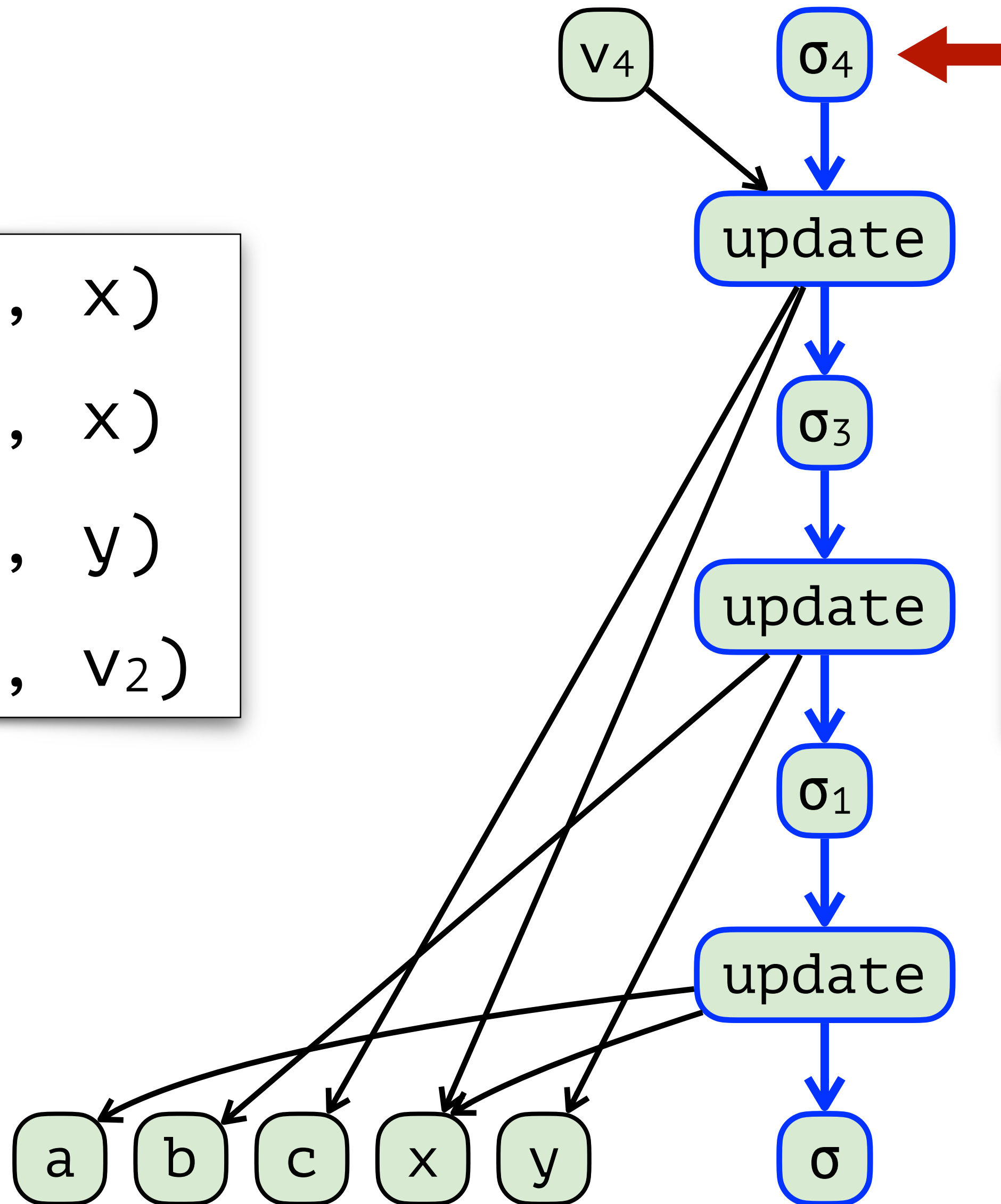
**Extraction Option 1**



# Redundant Update Elimination



$(v_1, \sigma_1) = \text{update}(a, x)$   
 $(v_2, \sigma_2) = \text{update}(a, x)$   
 $(v_3, \sigma_3) = \text{update}(b, y)$   
 $(v_4, \sigma_4) = \text{update}(c, v_2)$

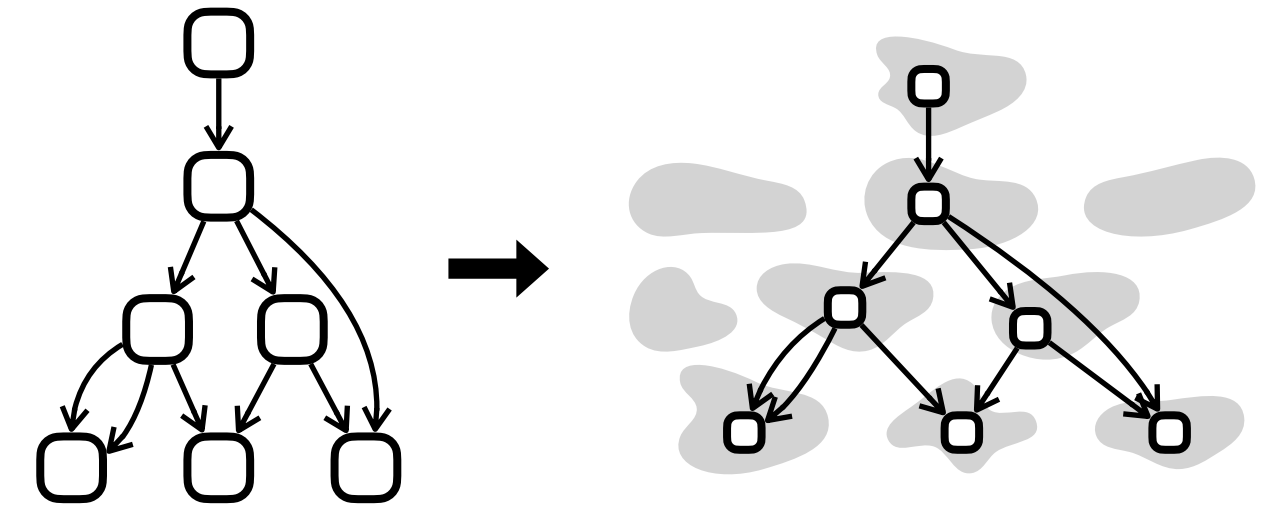


$(v_1, \sigma_1) = \text{update}(a, x)$   
 $(v_3, \sigma_3) = \text{update}(b, y)$   
 $(v_4, \sigma_4) = \text{update}(c, x)$



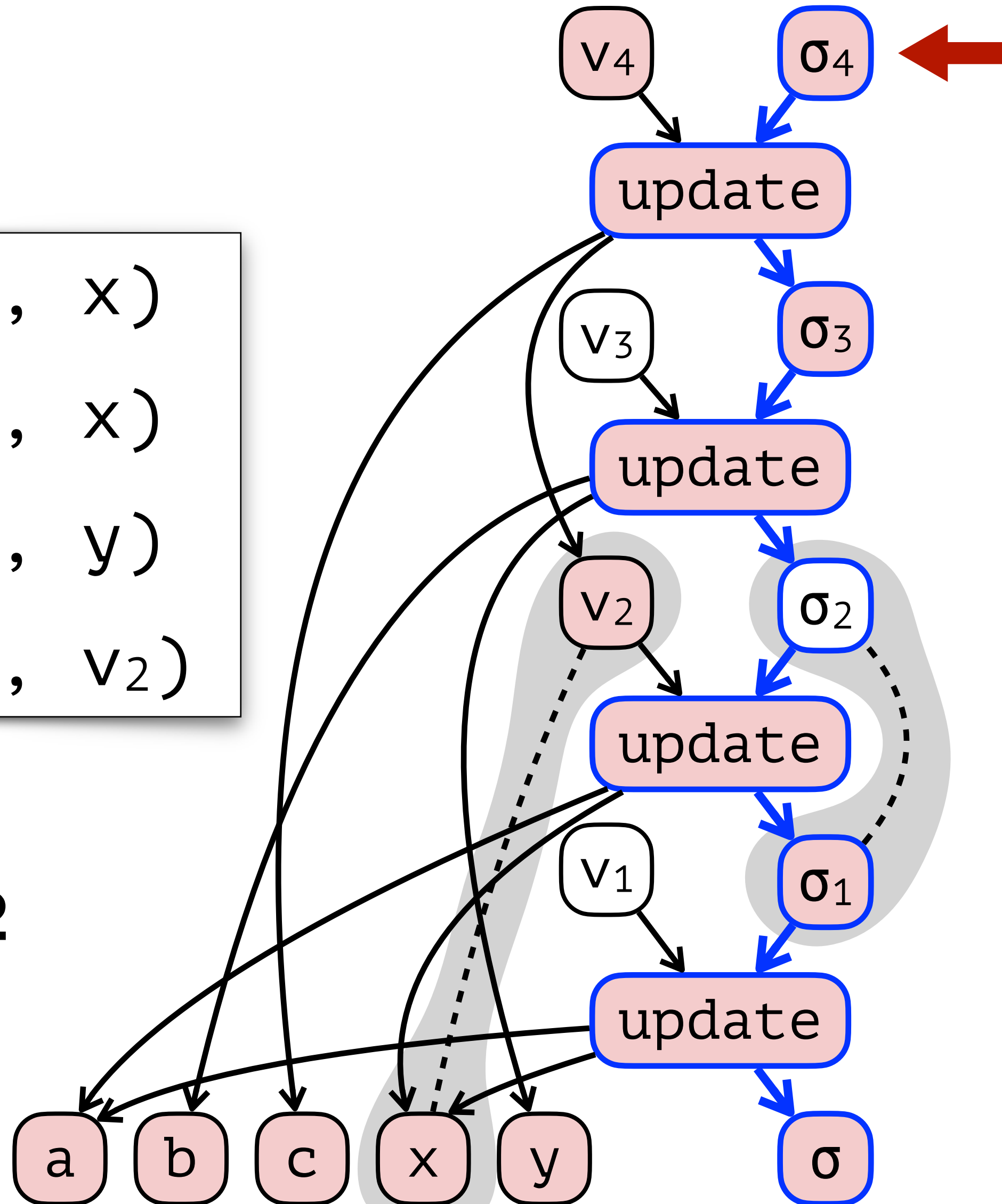
**Extraction Option 1**

# Redundant Update Elimination

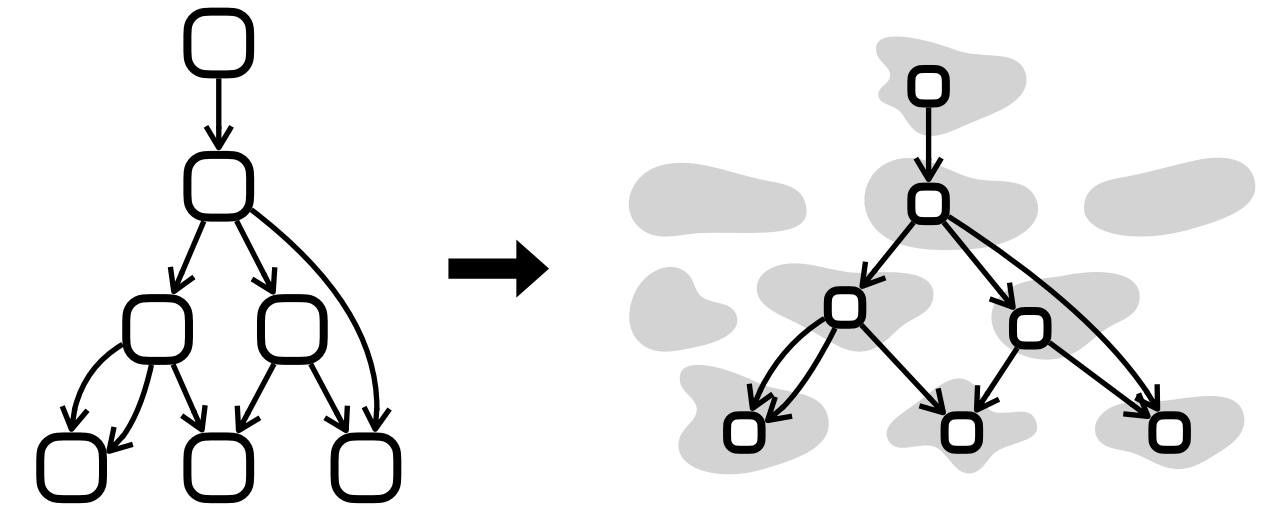


$(v_1, \sigma_1) = \text{update}(a, x)$   
 $(v_2, \sigma_2) = \text{update}(a, x)$   
 $(v_3, \sigma_3) = \text{update}(b, y)$   
 $(v_4, \sigma_4) = \text{update}(c, v_2)$

**Extraction Option 2**



# Redundant Update Elimination



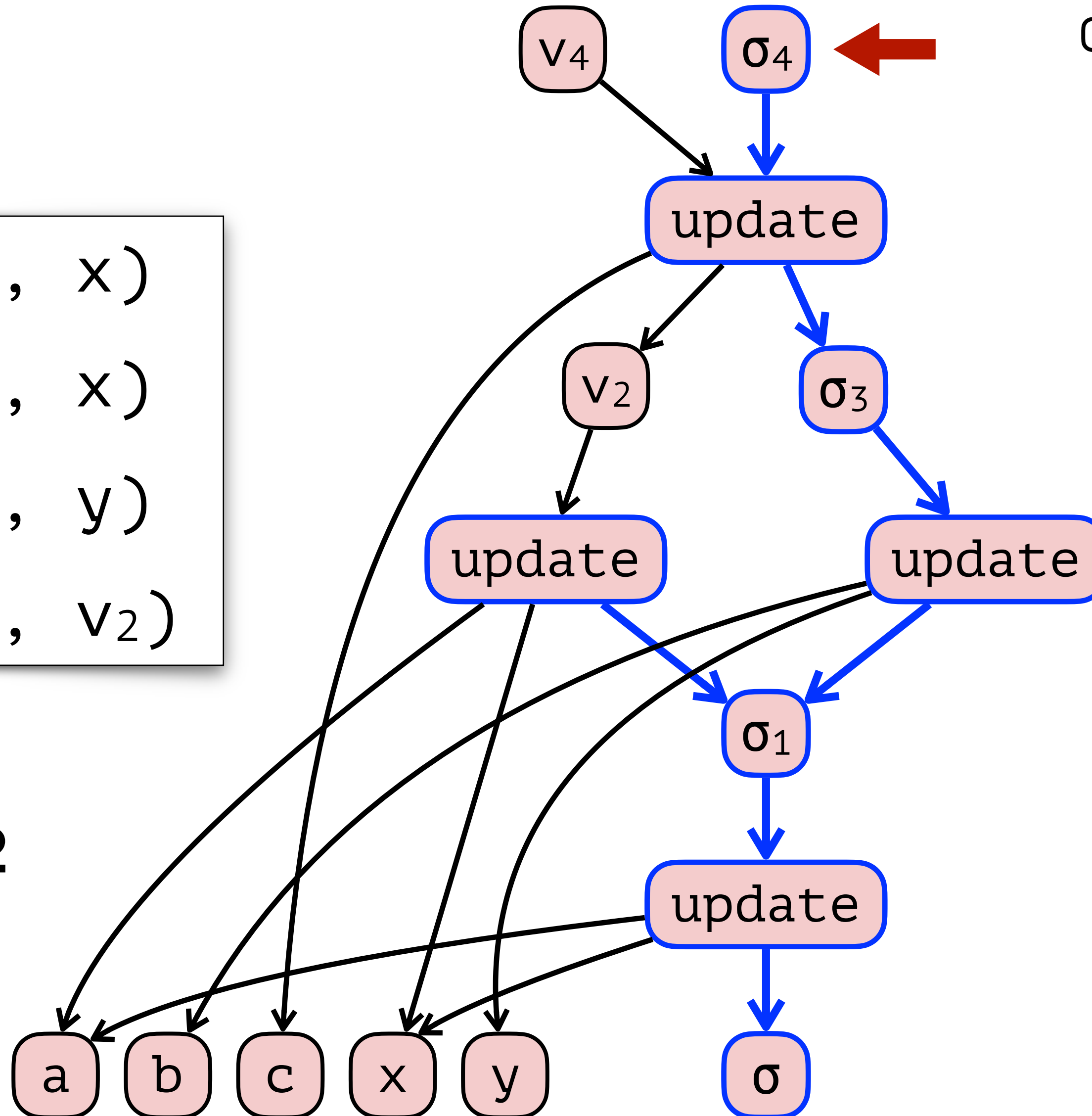
$$(v_1, \sigma_1) = \text{update}(a, x)$$

$$(v_2, \sigma_2) = \text{update}(a, x)$$

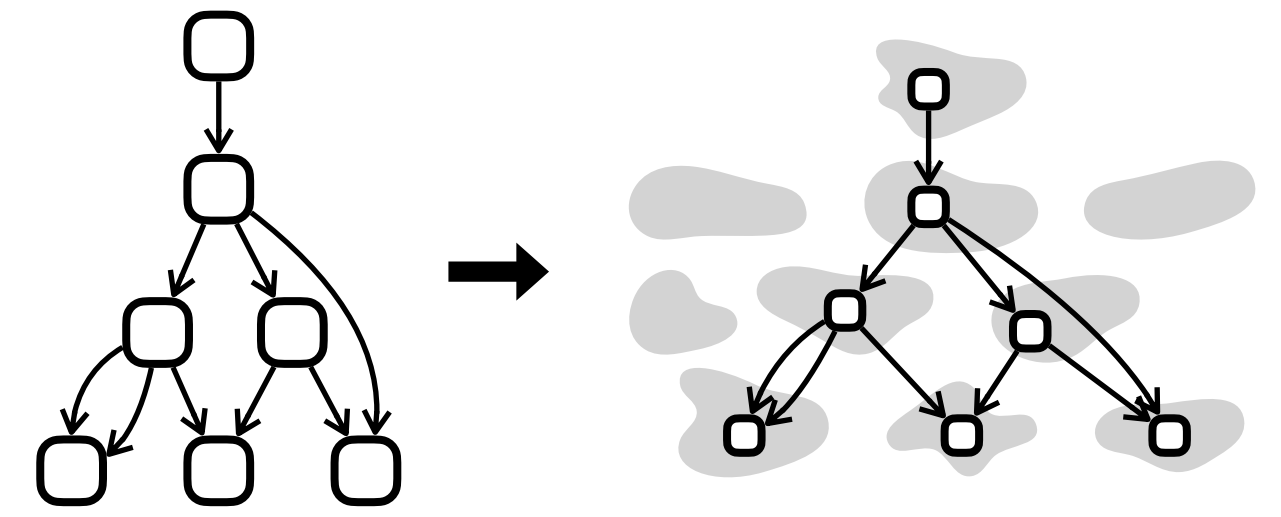
$$(v_3, \sigma_3) = \text{update}(b, y)$$

$$(v_4, \sigma_4) = \text{update}(c, v_2)$$

## Extraction Option 2

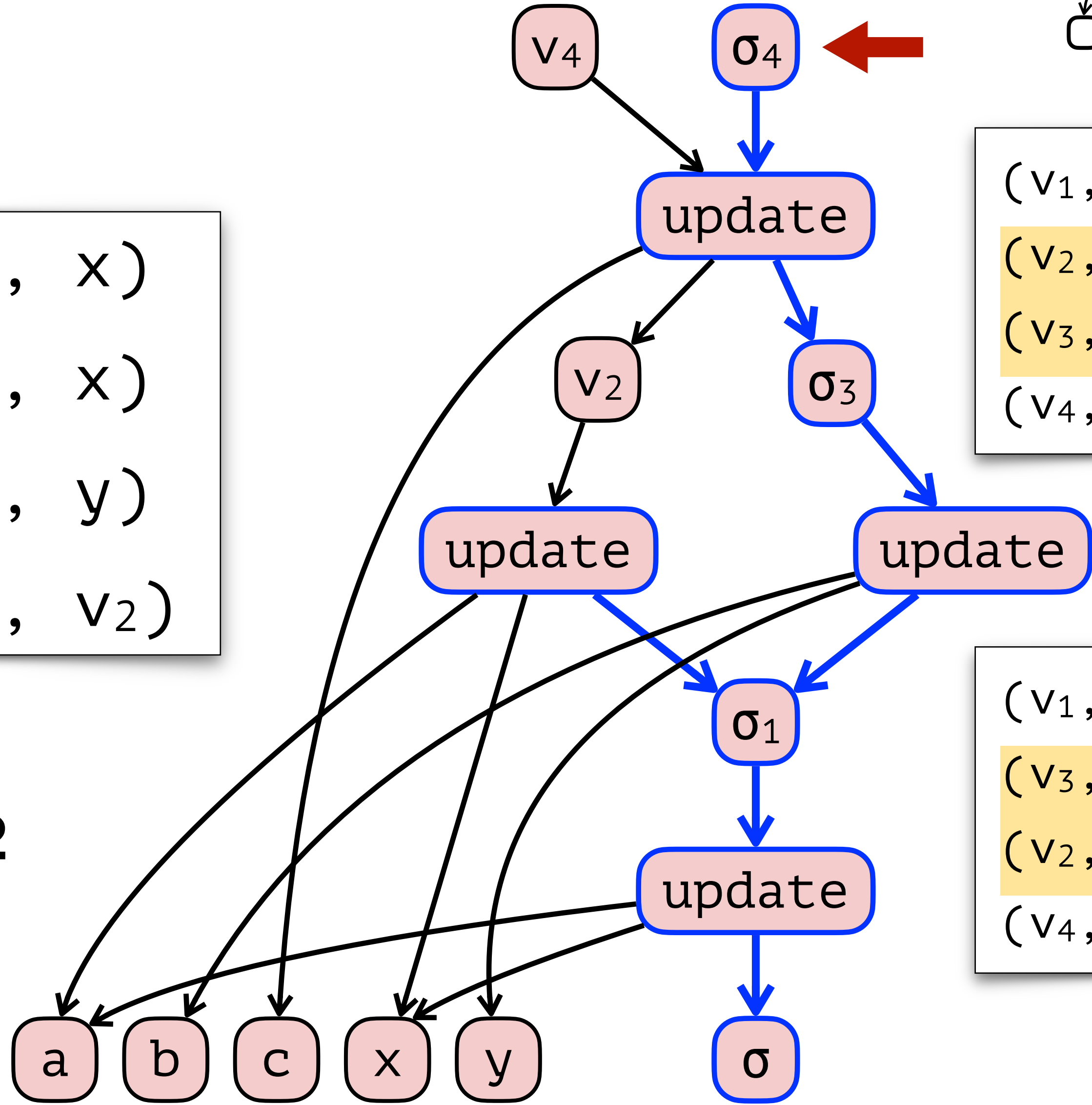


# Redundant Update Elimination



$(v_1, \sigma_1) = \text{update}(a, x)$   
 $(v_2, \sigma_2) = \text{update}(a, x)$   
 $(v_3, \sigma_3) = \text{update}(b, y)$   
 $(v_4, \sigma_4) = \text{update}(c, v_2)$

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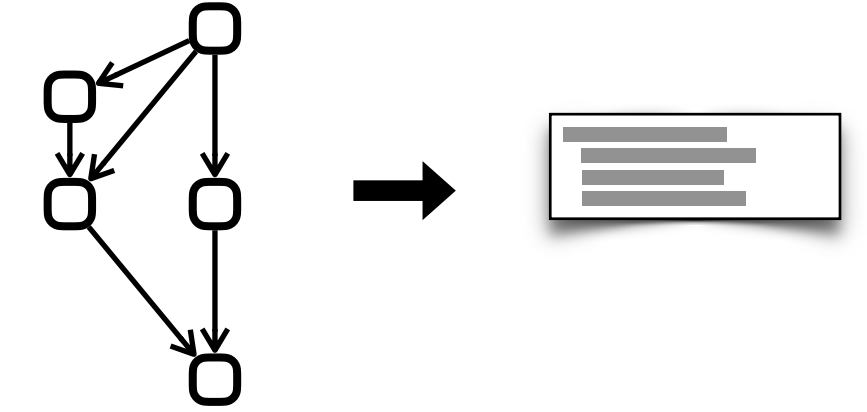


**Which program?**

$(v_1, \sigma_1) = \text{update}(a, x)$   
 $(v_3, \sigma_3) = \text{update}(b, y)$   
 $(v_2, \sigma_2) = \text{update}(a, x)$   
 $(v_4, \sigma_4) = \text{update}(c, v_2)$

**Extraction Option 2**

# Redundant Update Elimination



$$\begin{aligned} (v_1, \sigma_1) &= \text{update}(a, x) \\ (v_2, \sigma_2) &= \text{update}(a, x) \\ (v_3, \sigma_3) &= \text{update}(b, y) \\ (v_4, \sigma_4) &= \text{update}(c, v_2) \end{aligned}$$

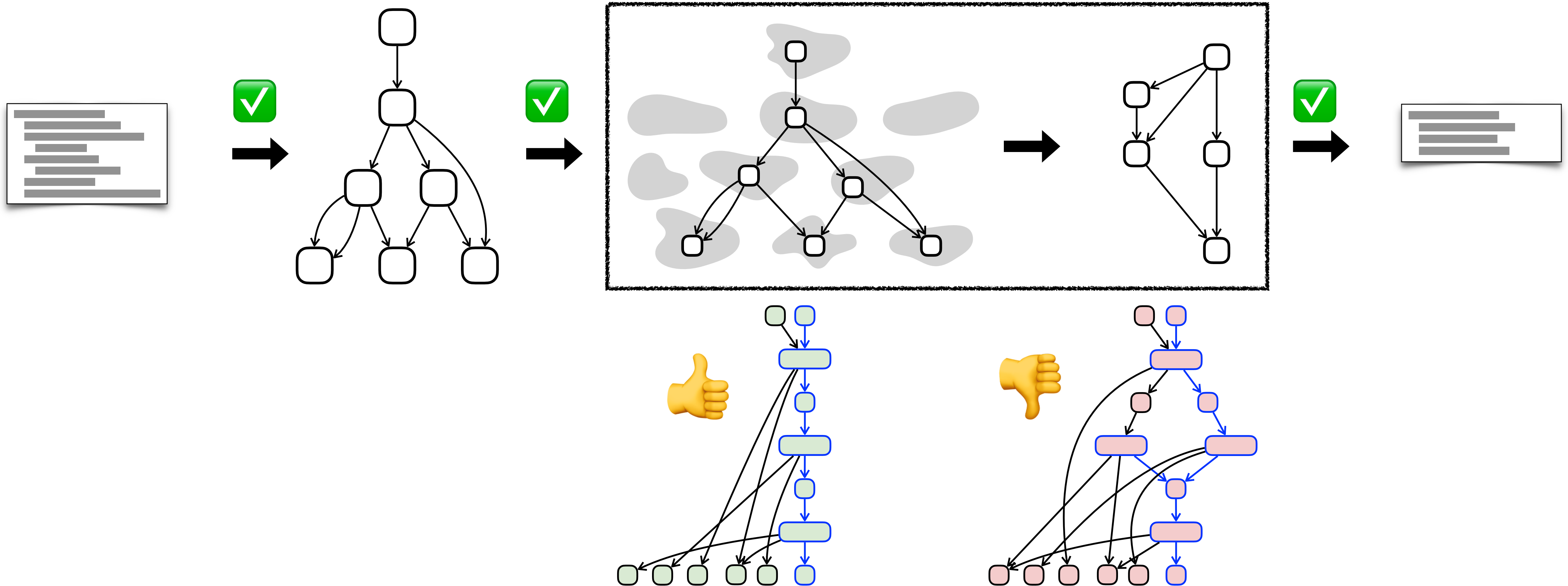
$$\begin{aligned} (v_1, \sigma_1) &= \text{update}(a, x) \\ (v_3, \sigma_3) &= \text{update}(b, y) \\ (v_2, \sigma_2) &= \text{update}(a, x) \\ (v_4, \sigma_4) &= \text{update}(c, v_2) \end{aligned}$$

## Does it matter?

What if  $a$  and  $b$  are the same address?

# Effect-safe Extraction

NP Complete





**If Problem  $\mathcal{A}$  is NP-Hard, then Problem  $\mathcal{B}$  is NP-Hard**

# Effect-safe Extraction is NP-Hard



**If Problem  $\mathcal{A}$  is NP-Hard, then Effect-Safe Extraction is NP-Hard**

# Effect-safe Extraction is NP-Hard



**If SAT is NP-Hard, then Effect-Safe Extraction is NP-Hard**

# Effect-safe Extraction is NP-Hard

## Proof Strategy

1. Take a boolean formula  $\phi$ .
2. Construct an e-graph  $\mathcal{G}$ .
3. Show that  $\mathcal{G}$  has an effect-safe extraction if and only if  $\phi$  is satisfiable.

# Effect-safe Extraction is NP-Hard

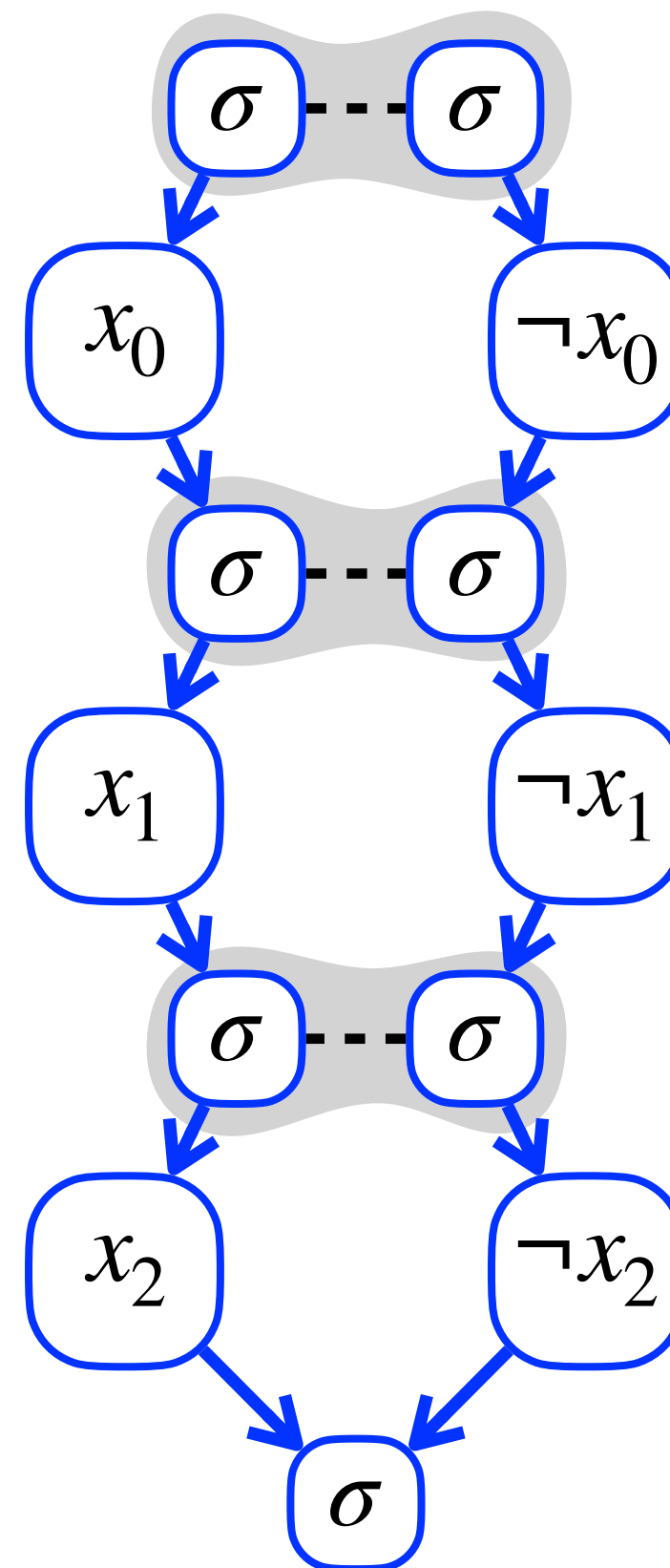
$$\phi = \neg x_0 \wedge (\neg x_1 \vee x_0) \wedge (x_2 \vee x_1 \vee \neg x_2)$$

## Proof Strategy

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$$\phi = \neg x_0 \wedge (\neg x_1 \vee x_0) \wedge (x_2 \vee x_1 \vee \neg x_2)$$



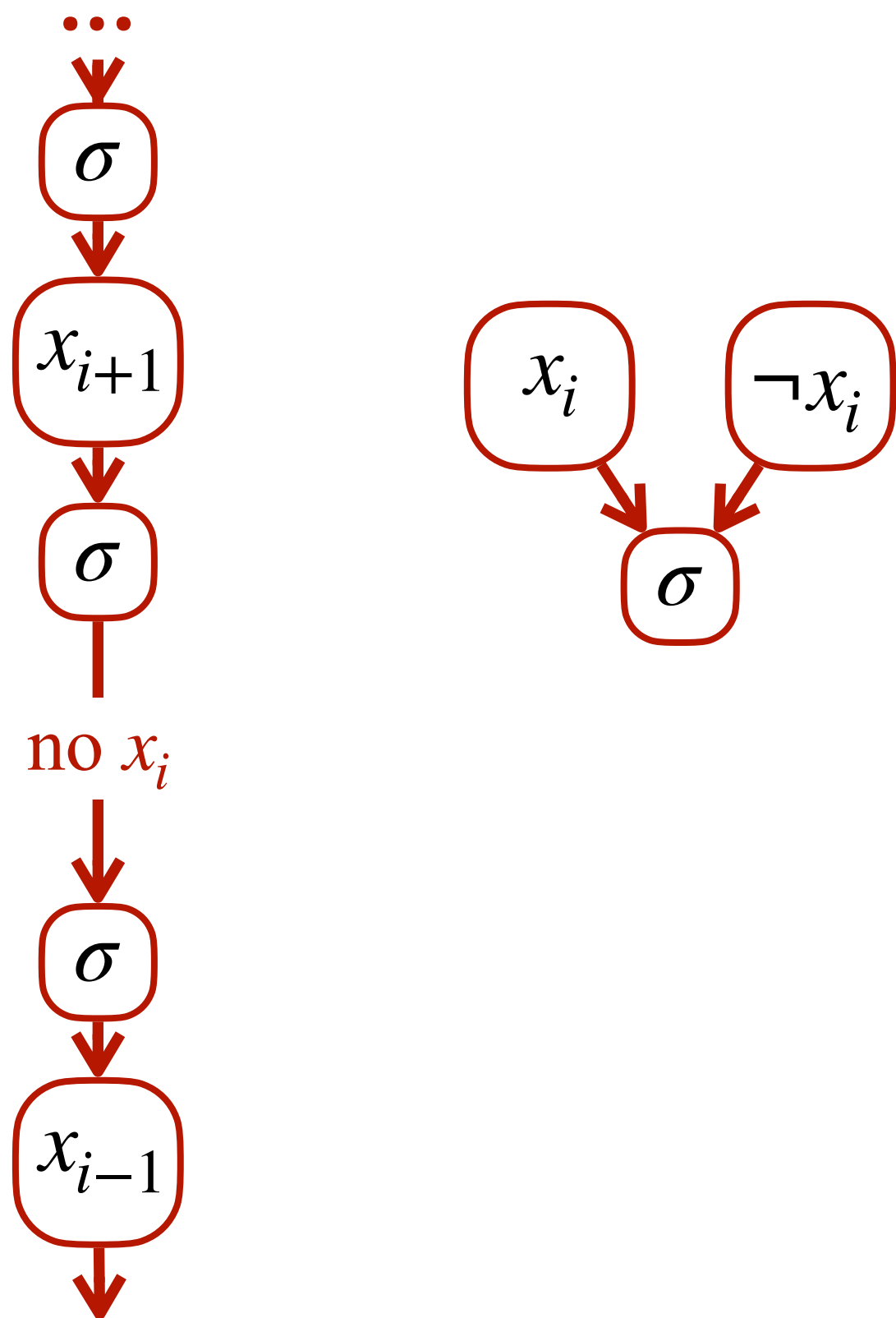
## Proof Strategy

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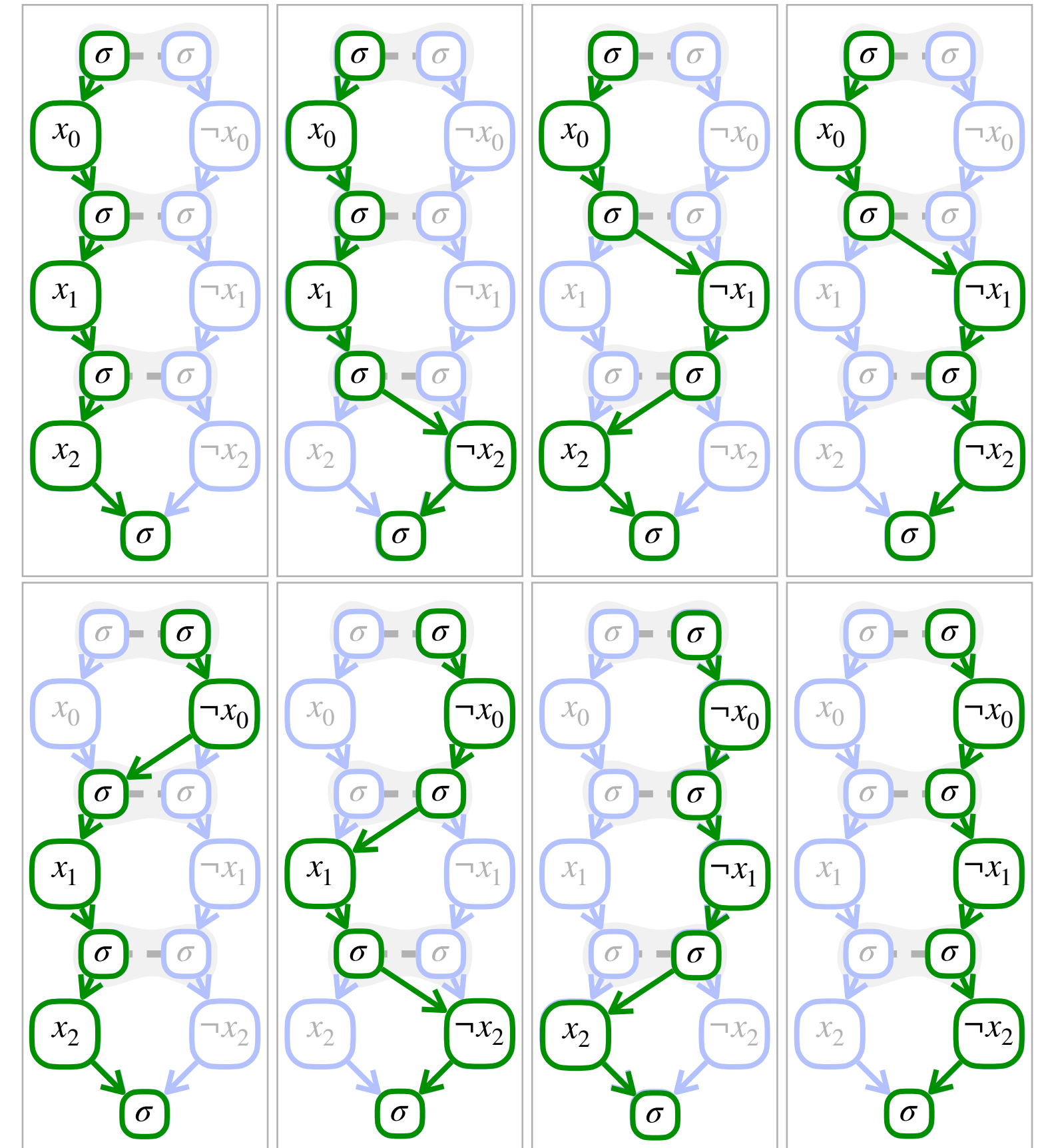
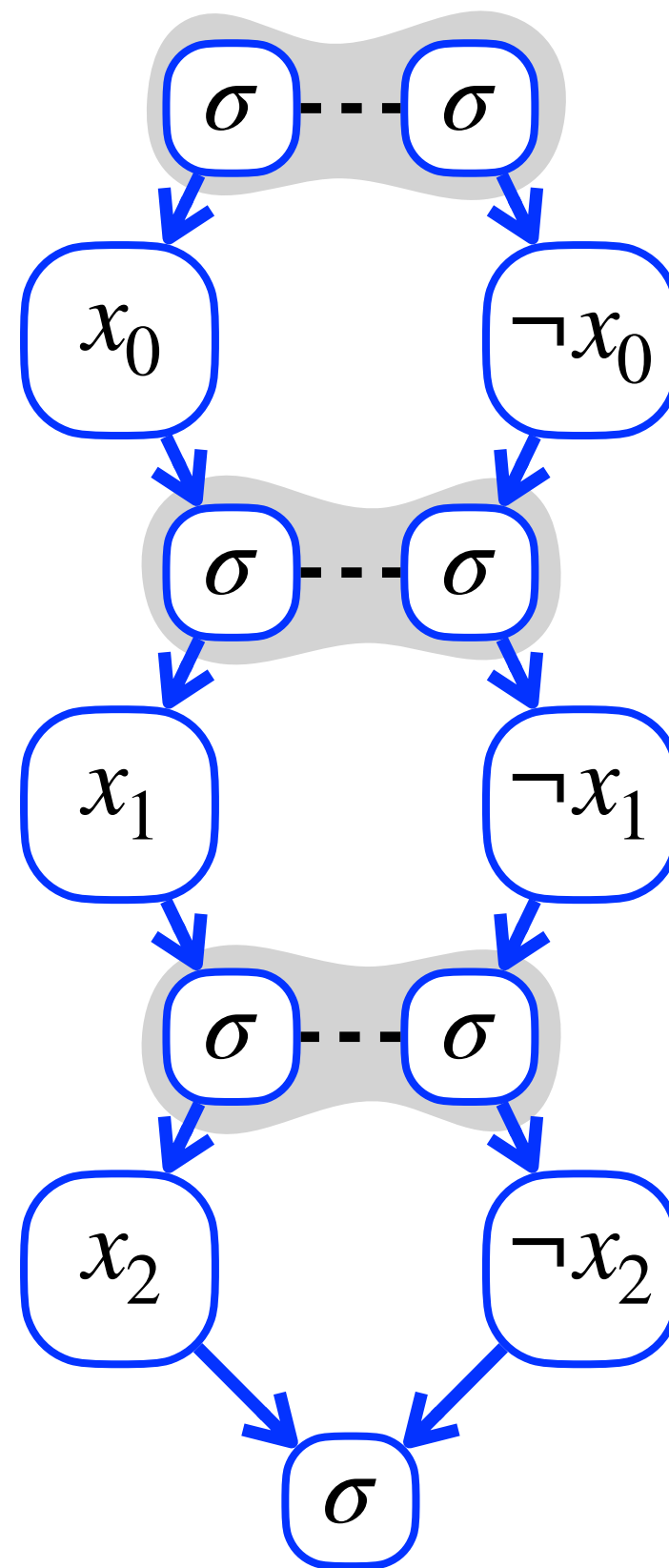
# Effect-safe Extraction is NP-Hard

$$\phi = \neg x_0 \wedge (\neg x_1 \vee x_0) \wedge (x_2 \vee x_1 \vee \neg x_2)$$

Invalid Assignment  $\Rightarrow$  Not Effect-Safe

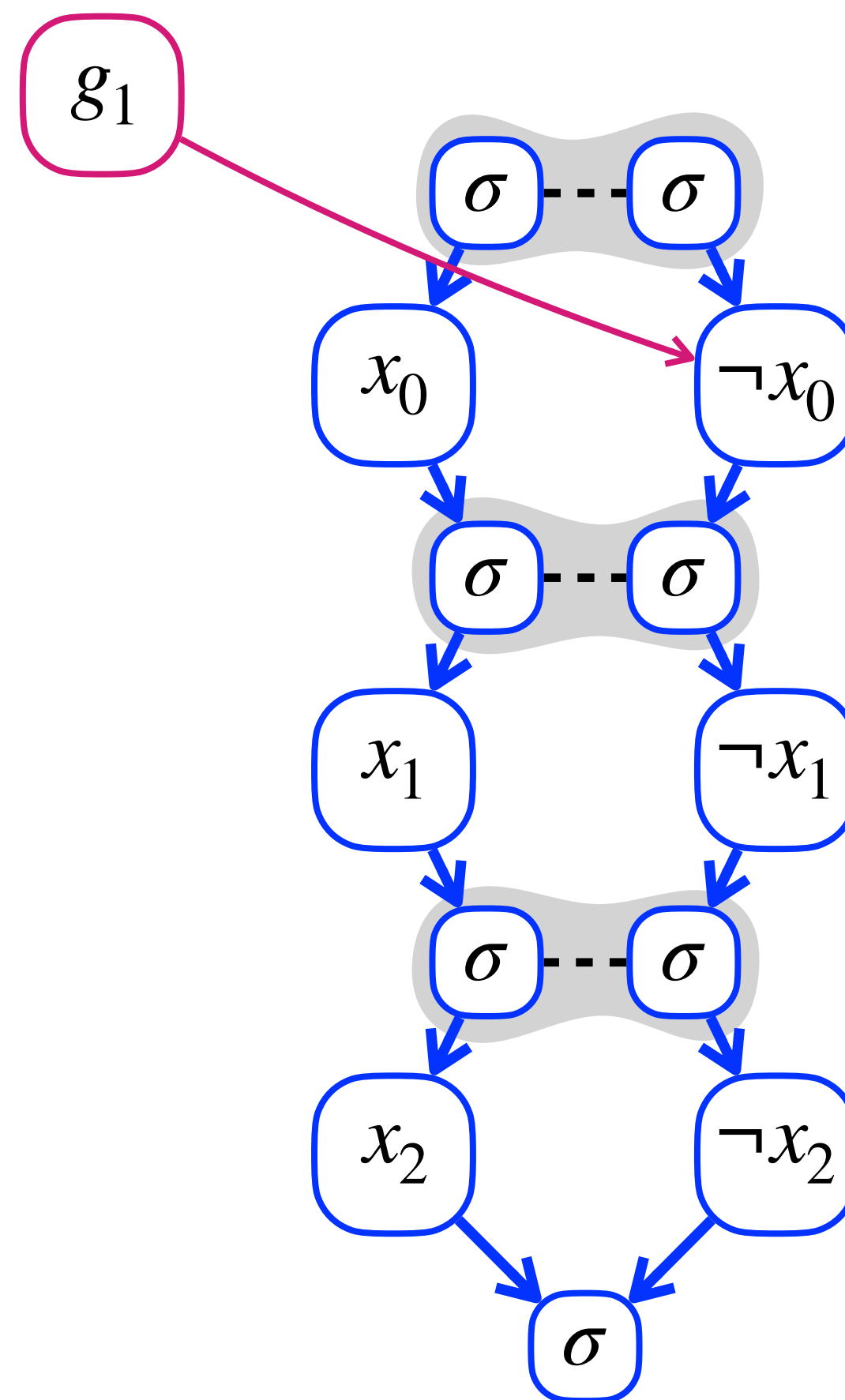


Valid Assignment  $\Rightarrow$  Effect-Safe



# Effect-safe Extraction is NP-Hard

$$\phi = \underline{\neg x_0} \wedge (\neg x_1 \vee x_0) \wedge (x_2 \vee x_1 \vee \neg x_2)$$

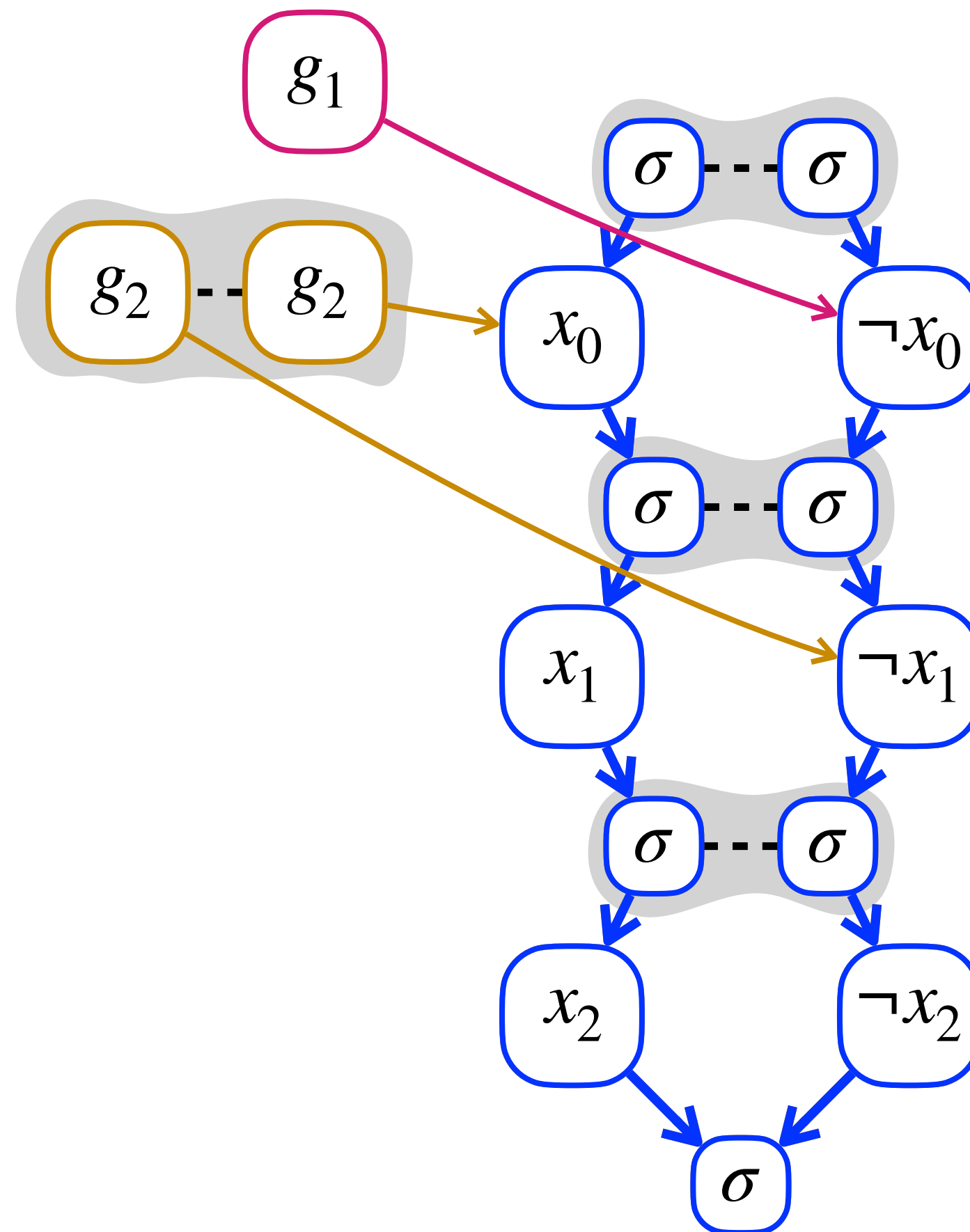


## Proof Strategy

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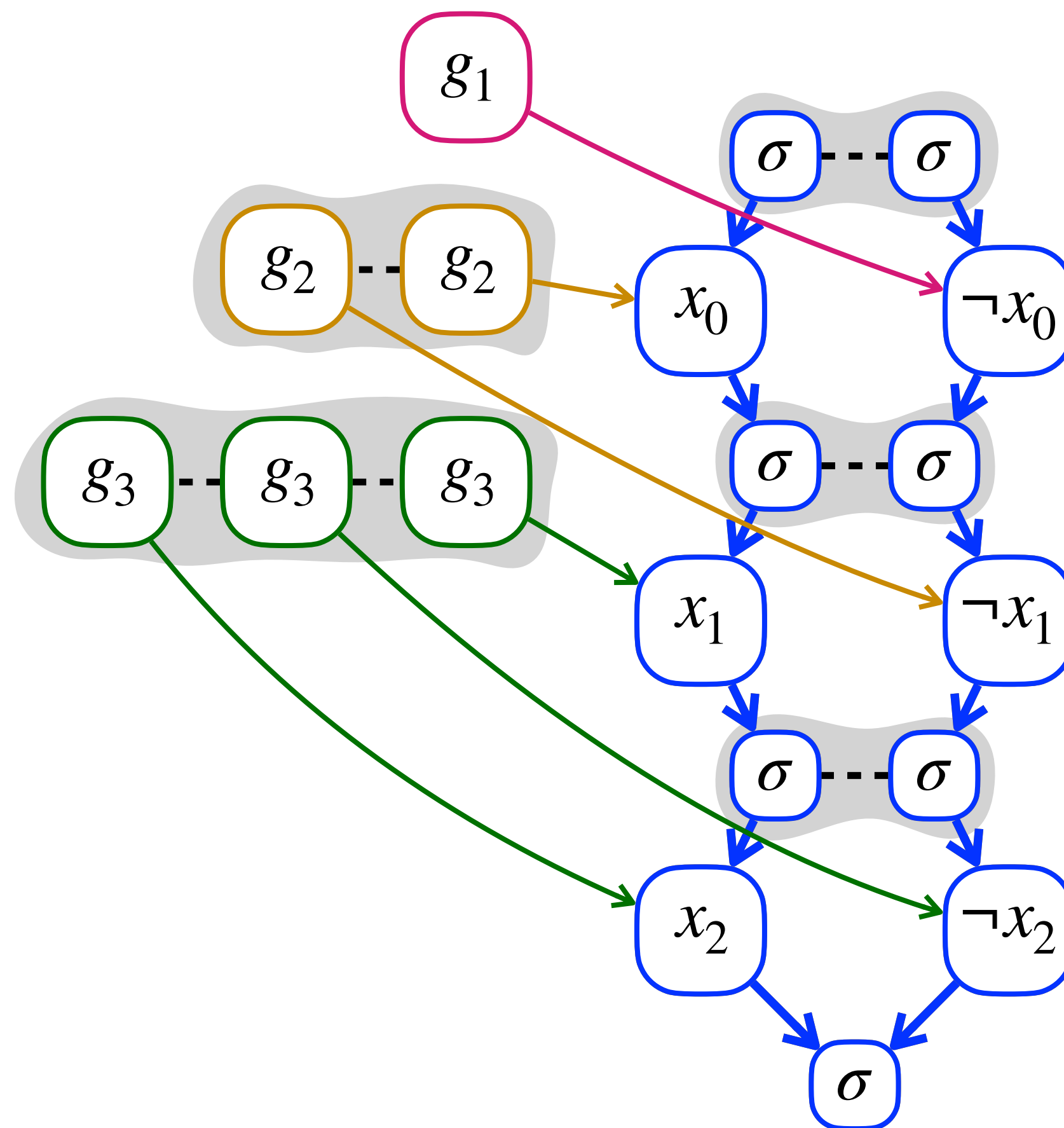


## Proof Strategy

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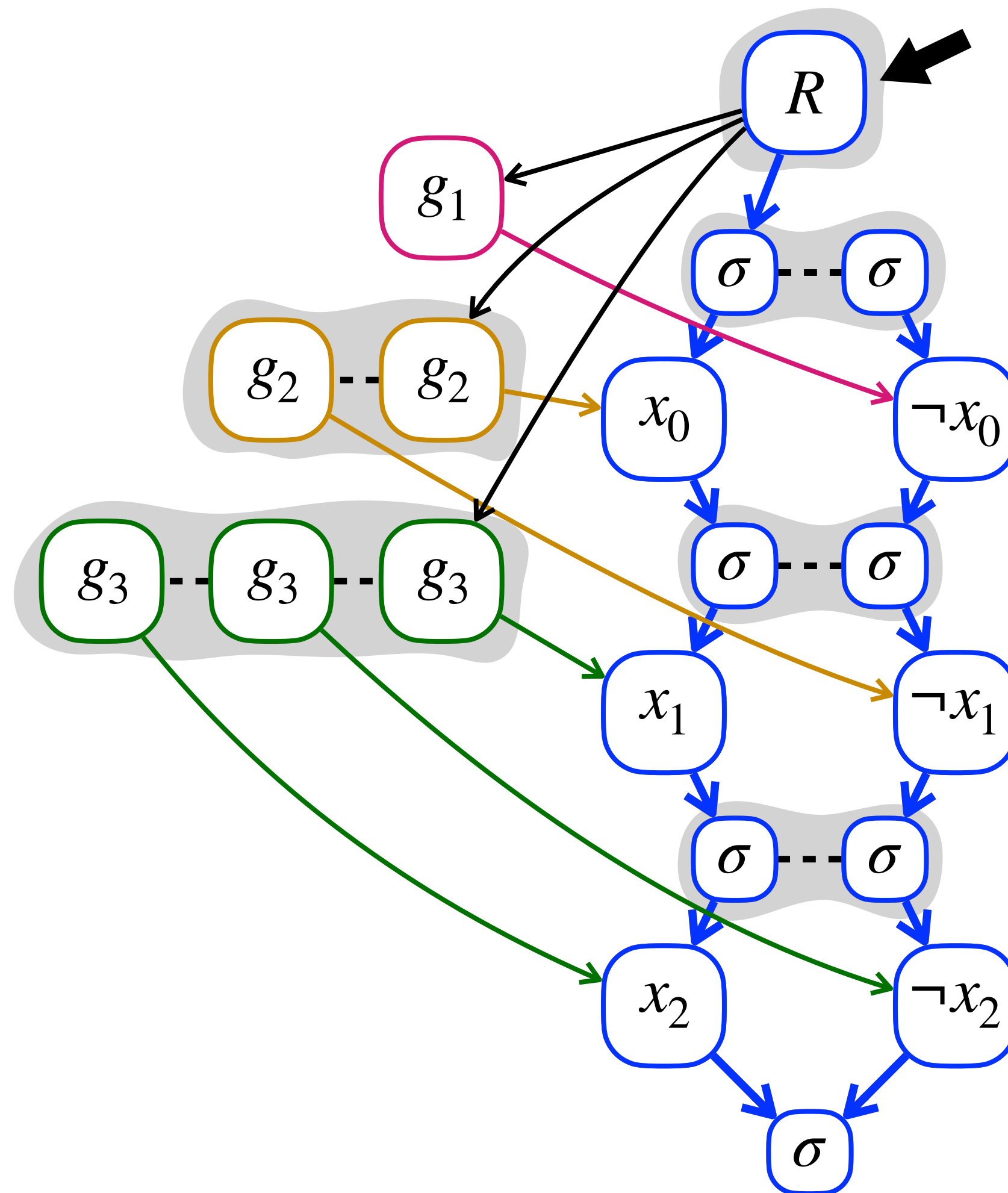


## Proof Strategy

1. Take a boolean formula  $\phi$ .
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# Effect-safe Extraction is NP-Hard

$$\phi = \underline{\neg x_0} \wedge (\underline{\neg x_1 \vee x_0}) \wedge (\underline{x_2 \vee x_1 \vee \neg x_2})$$



## Proof Strategy

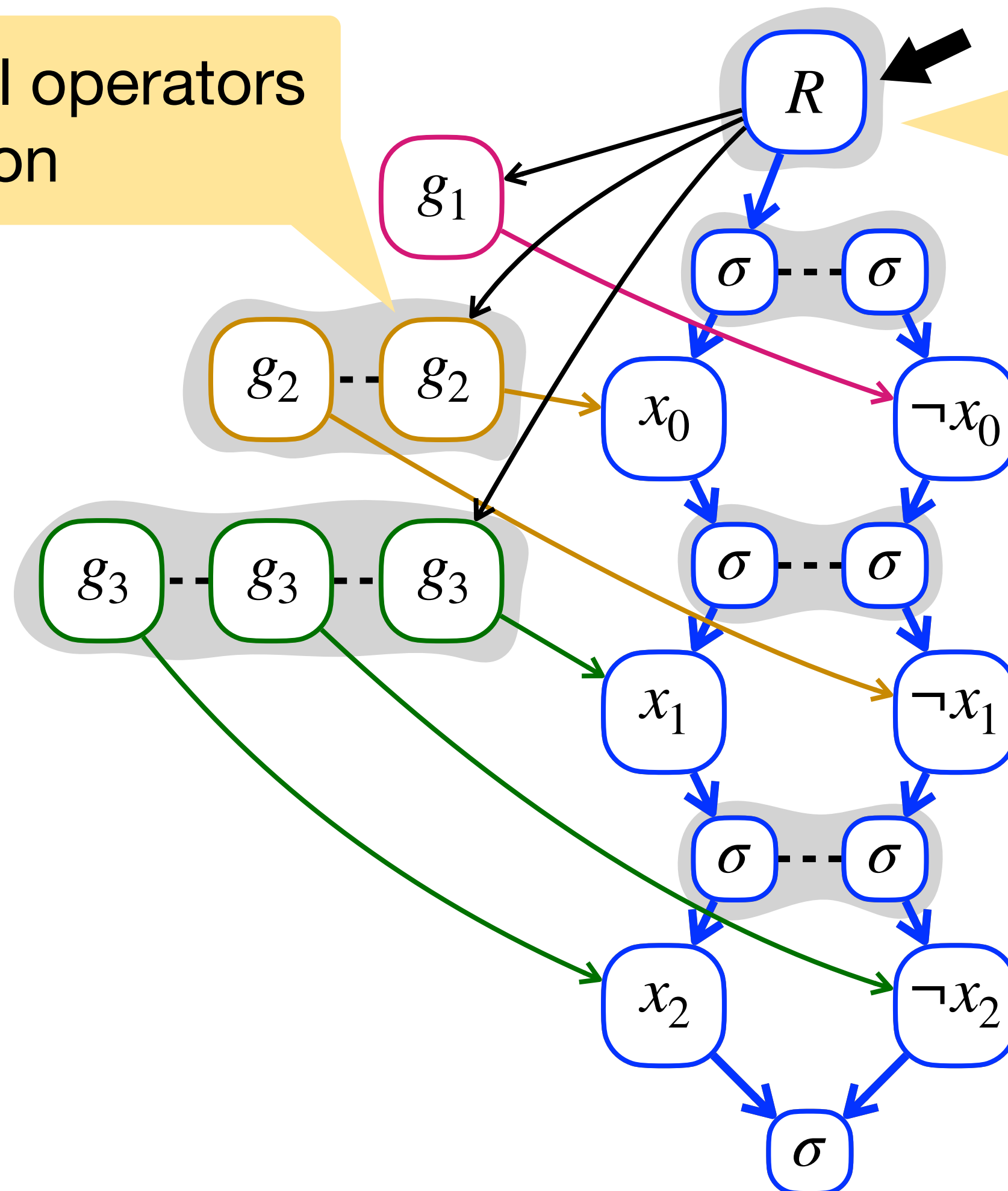
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# Effect-safe Extraction is NP-Hard

$$\phi = \underline{\neg x_0} \wedge (\underline{\neg x_1 \vee x_0}) \wedge (\underline{x_2 \vee x_1 \vee \neg x_2})$$

Terms relying on effectful operators encode clause satisfaction

Extracted term ensures valid assignment and satisfaction of clauses



Effectful operators encode variable assignments

## Proof Strategy

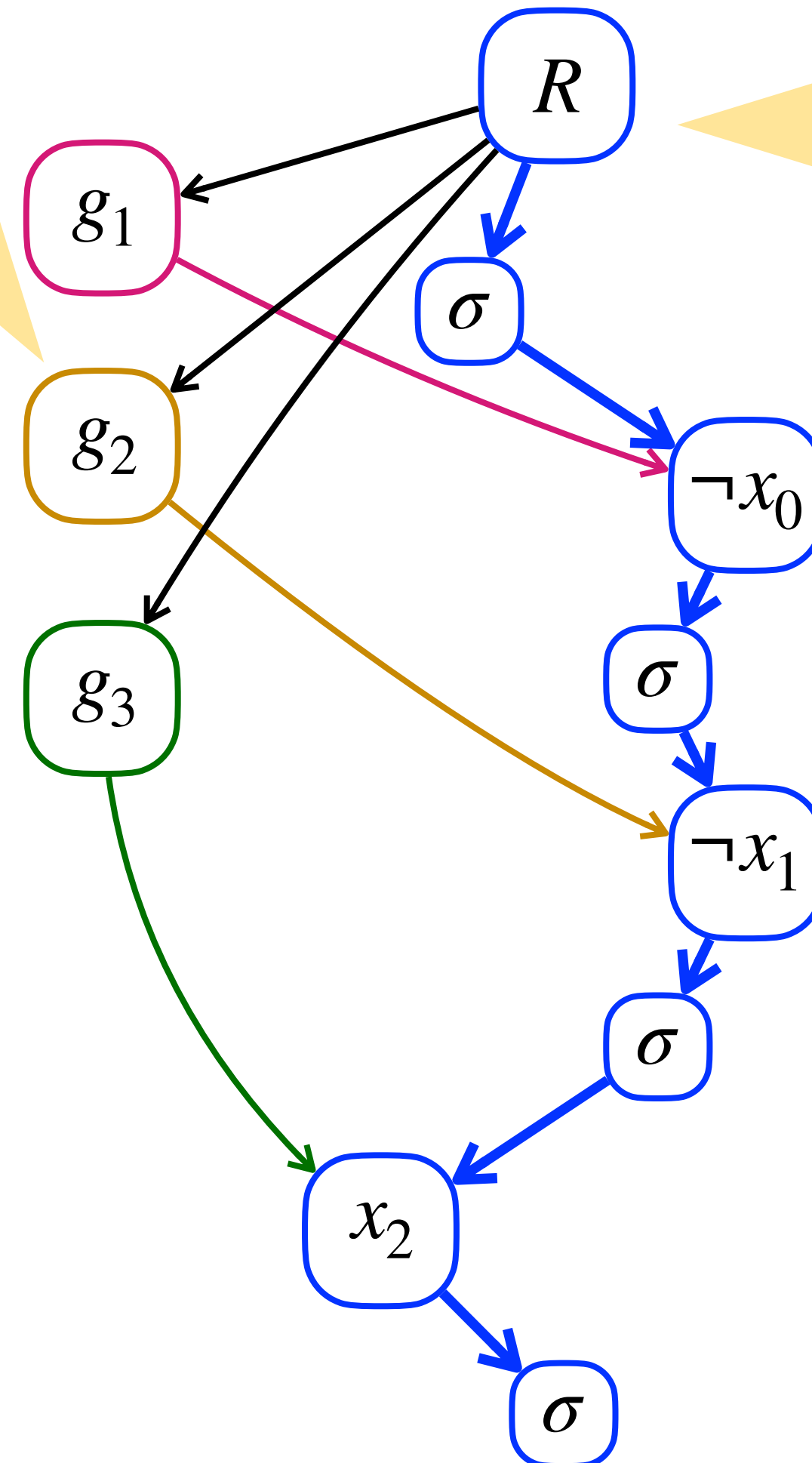
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Effectful operators encode variable assignments

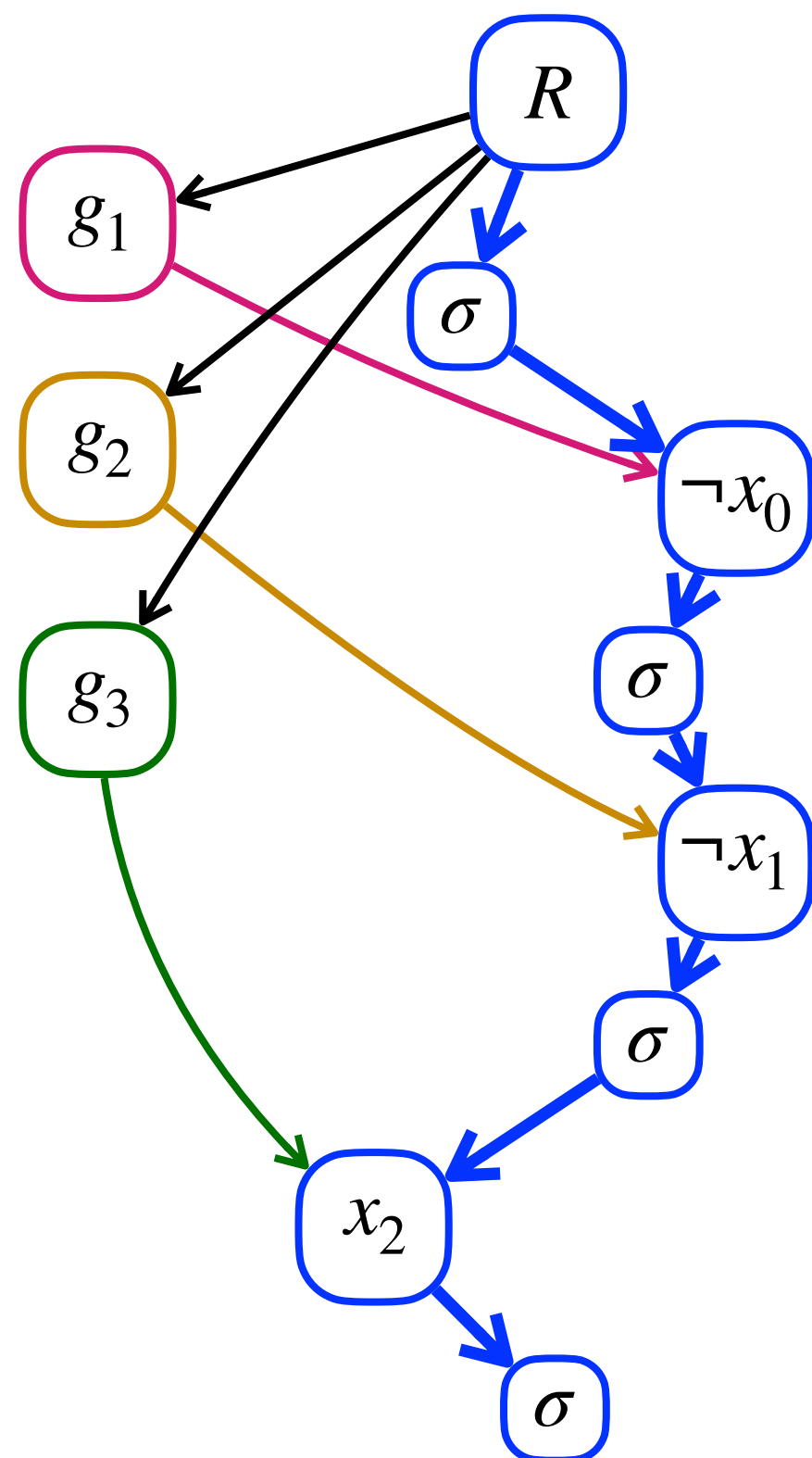
## Proof Strategy

1. Take a boolean formula  $\phi$ .
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# Effect-safe Extraction is NP-Hard

$$\phi = \underline{\neg x_0} \wedge (\underline{\neg x_1 \vee x_0}) \wedge (\underline{x_2 \vee x_1 \vee \neg x_2})$$

Effect-Safe Extraction from  $\mathcal{G}$



Satisfying Assignment of  $\phi$ :

$$x_0 = \perp$$

$$x_1 = \perp$$

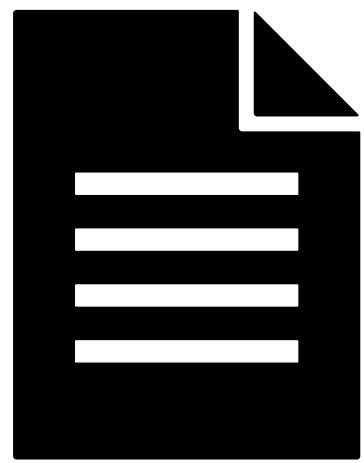
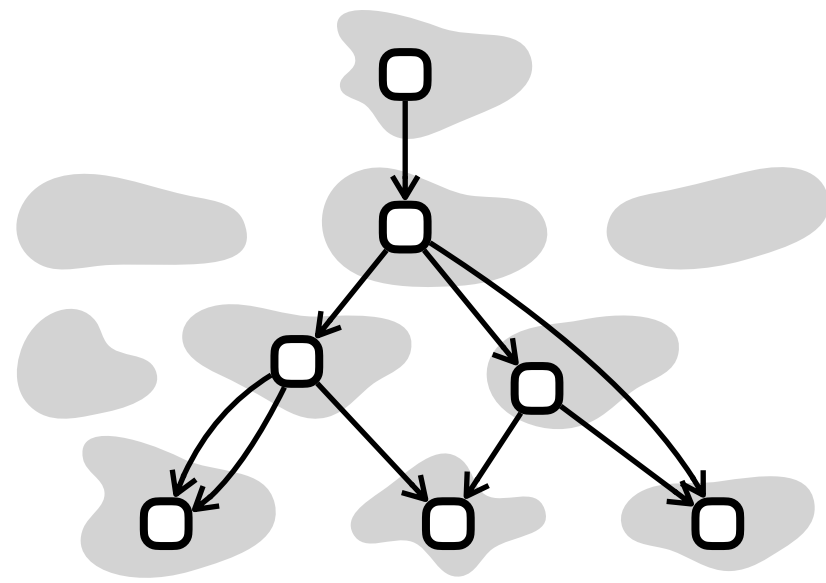
$$x_2 = \top$$

**NP-Hard  $\Rightarrow$  Give Up?**

**NP-Hard  $\Rightarrow$  ~~Give Up?~~**

**NP-Hard  $\Rightarrow$  Try a solver**

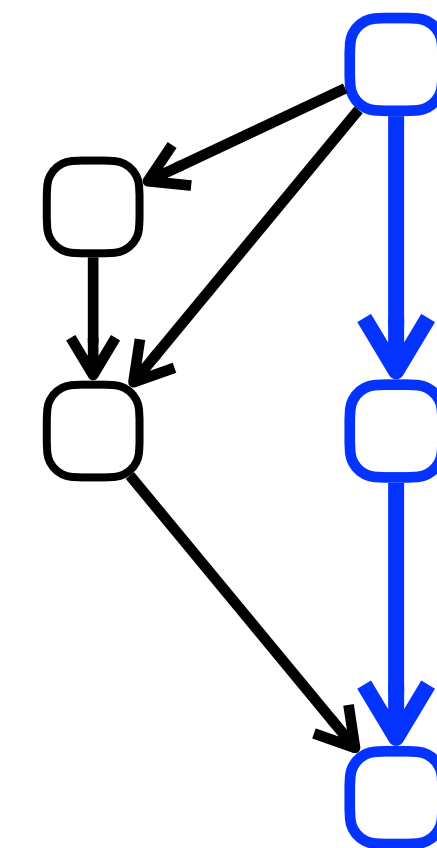
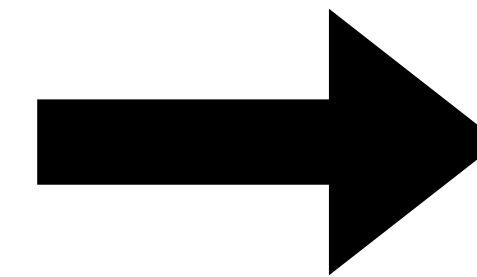
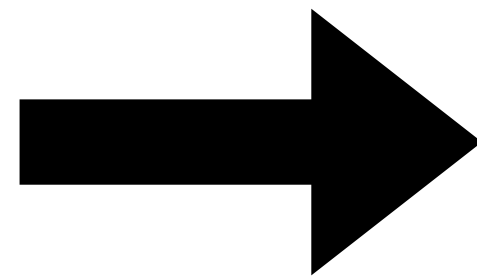
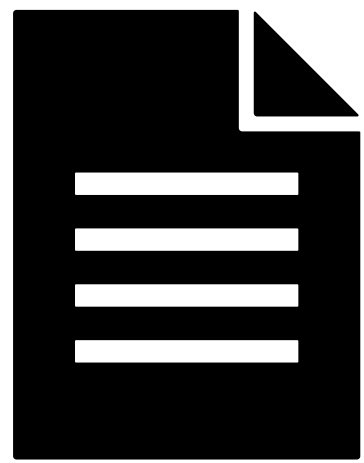
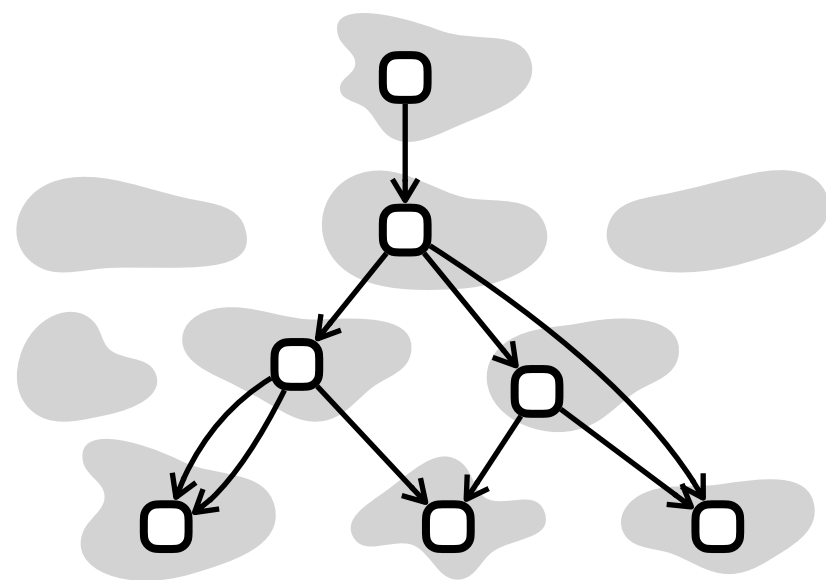
# Solver-Based Effect-Safe Extraction



Set of linear equations

- No cycles
- Well-formed term
- Linearity constraints
- Cost is minimized
- ...

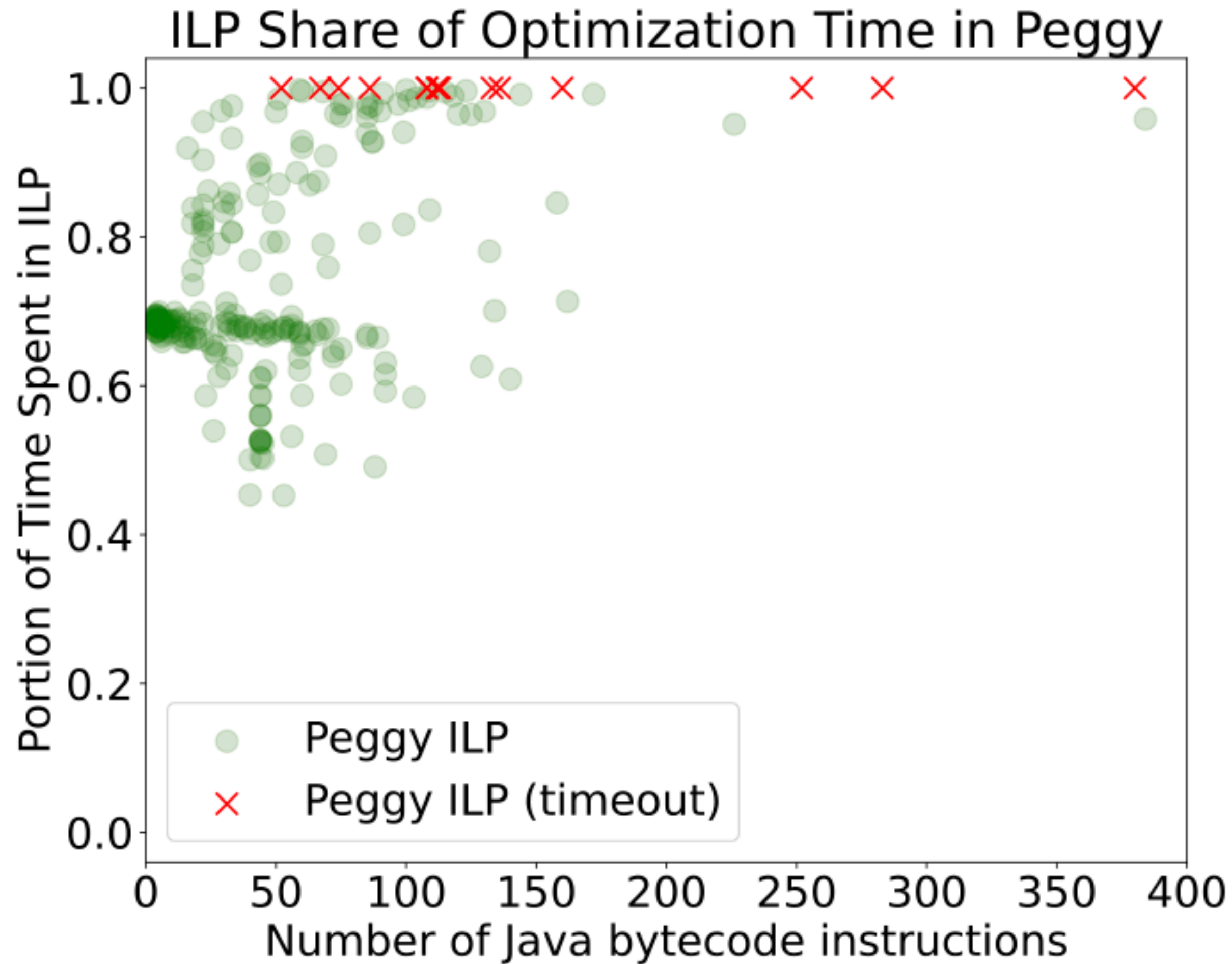
# Solver-Based Effect-Safe Extraction



Set of linear equations

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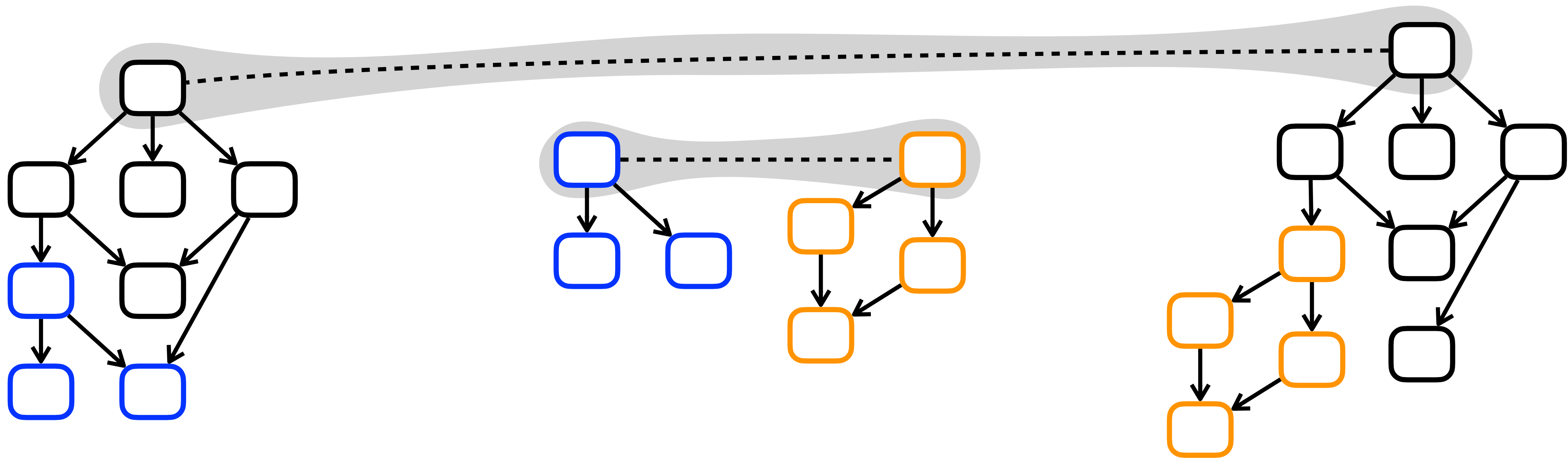
# Solver-Based Effect-Safe Extraction



**ILP-Based Extraction Bottleneck**

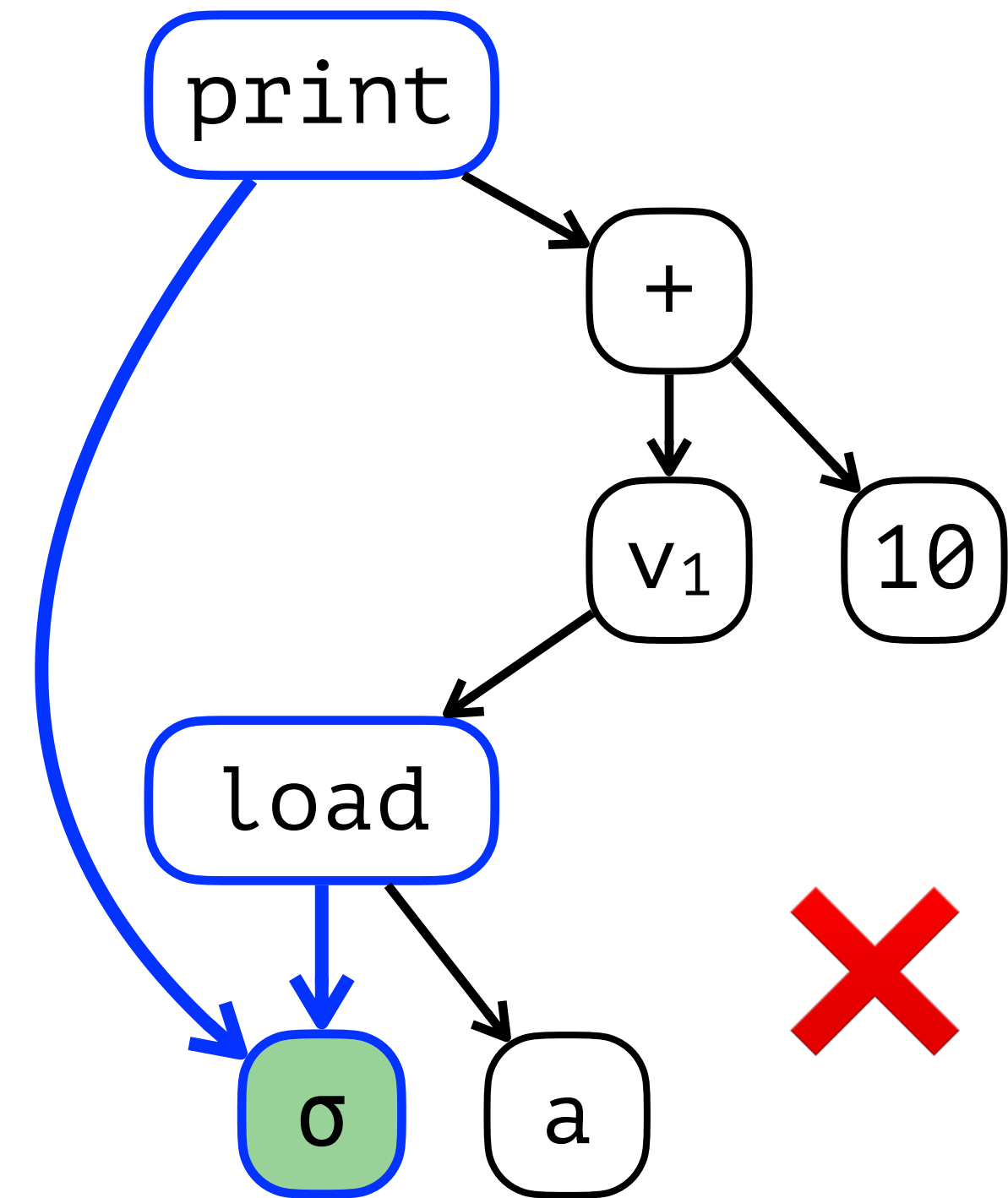
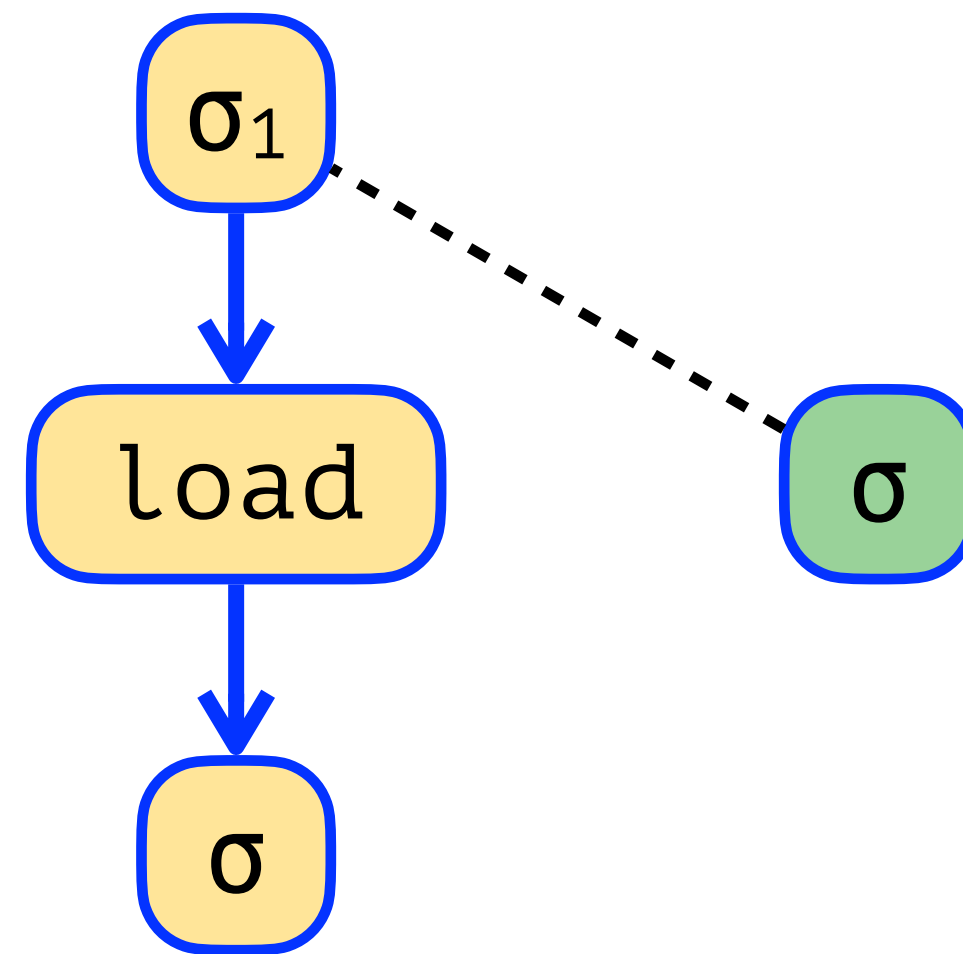
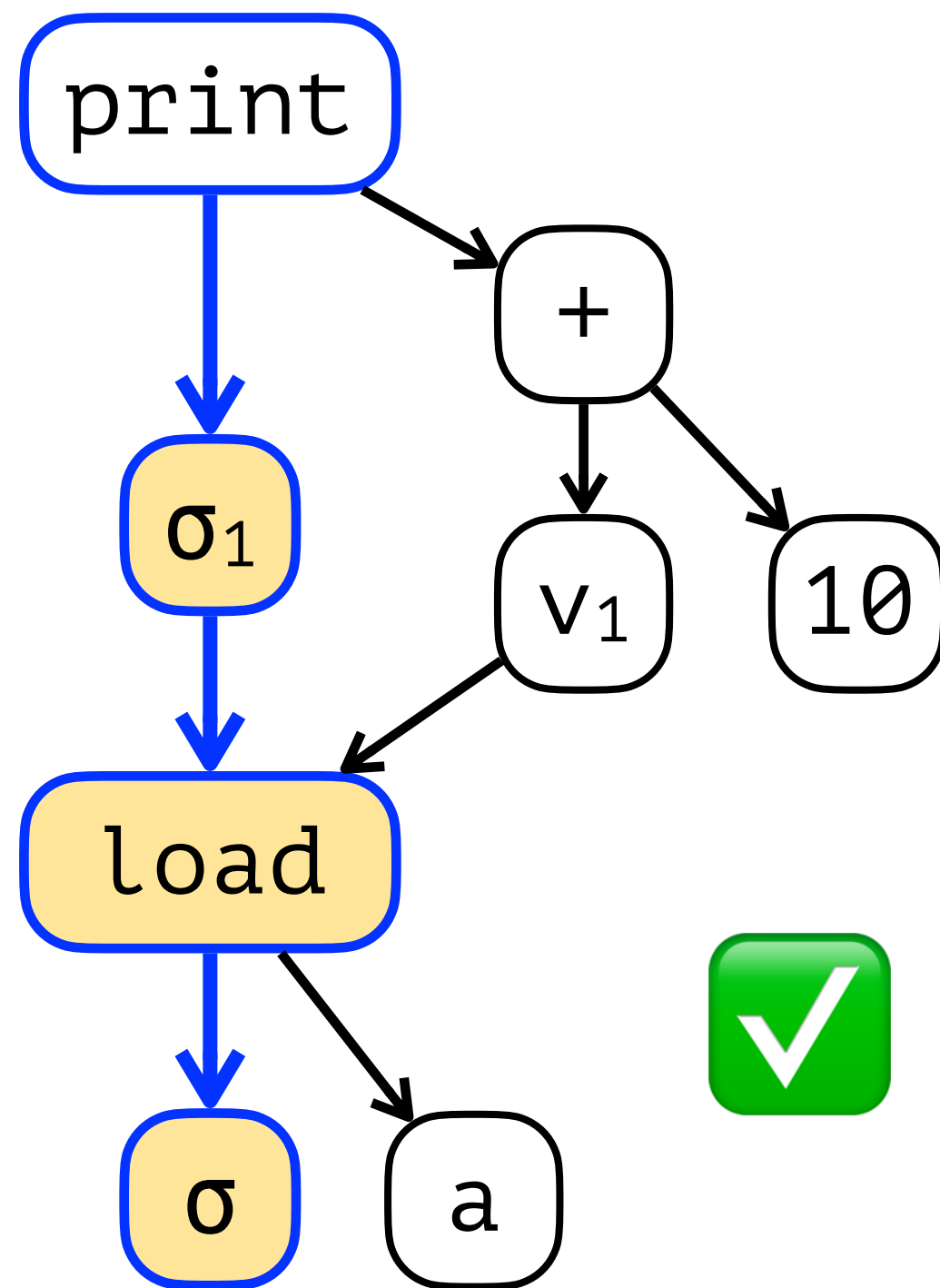
**NP-Hard  $\Rightarrow$  Find a parameterization that is fast in practice**

# Fast Effect-safe Extraction in Practice



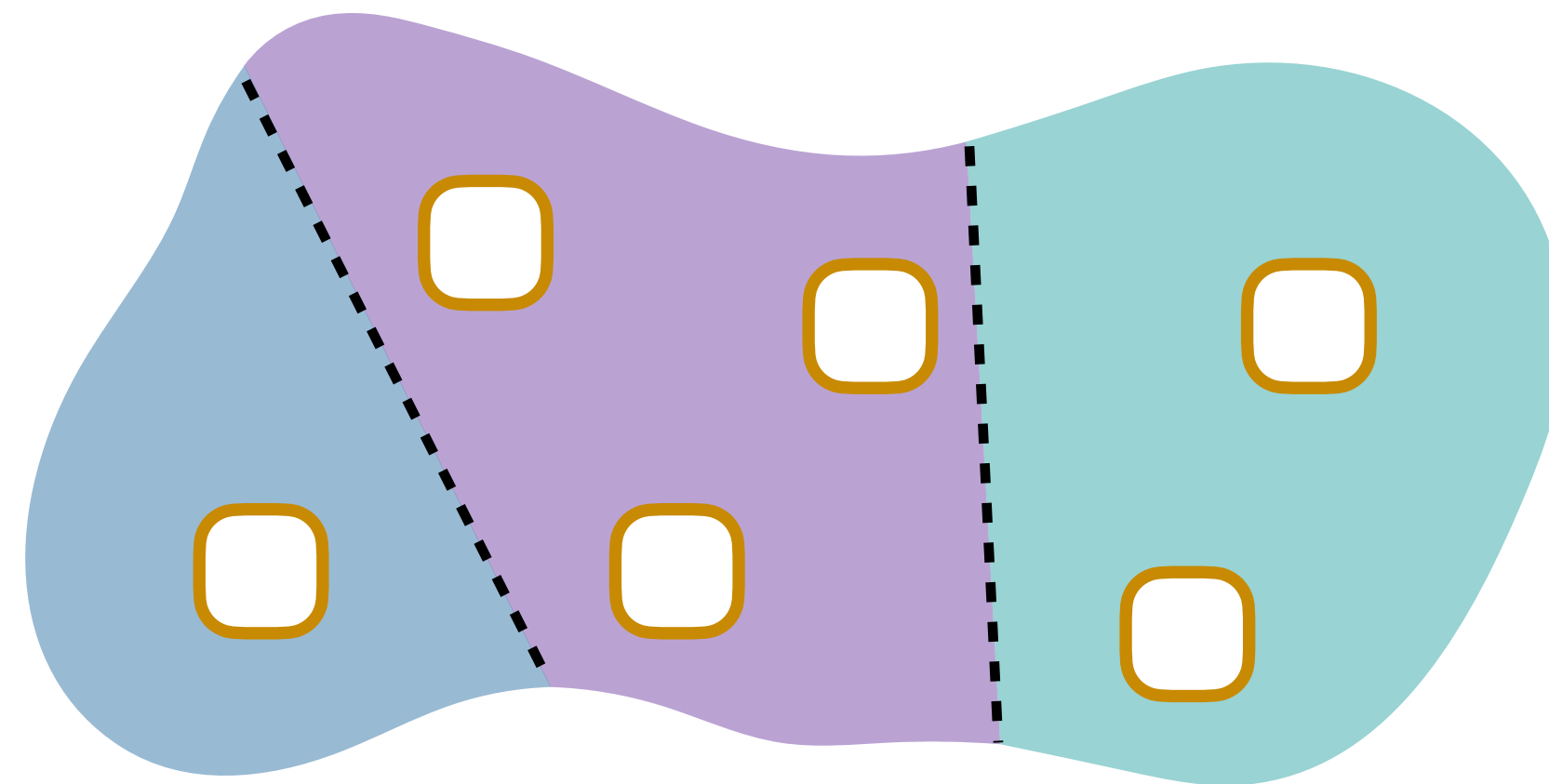
**Greedy extraction relied on interchangeability of equivalent terms**

# Fast Effect-safe Extraction in Practice



Effectful terms are not interchangeable

# Key Idea: Refine the Equivalence Relation



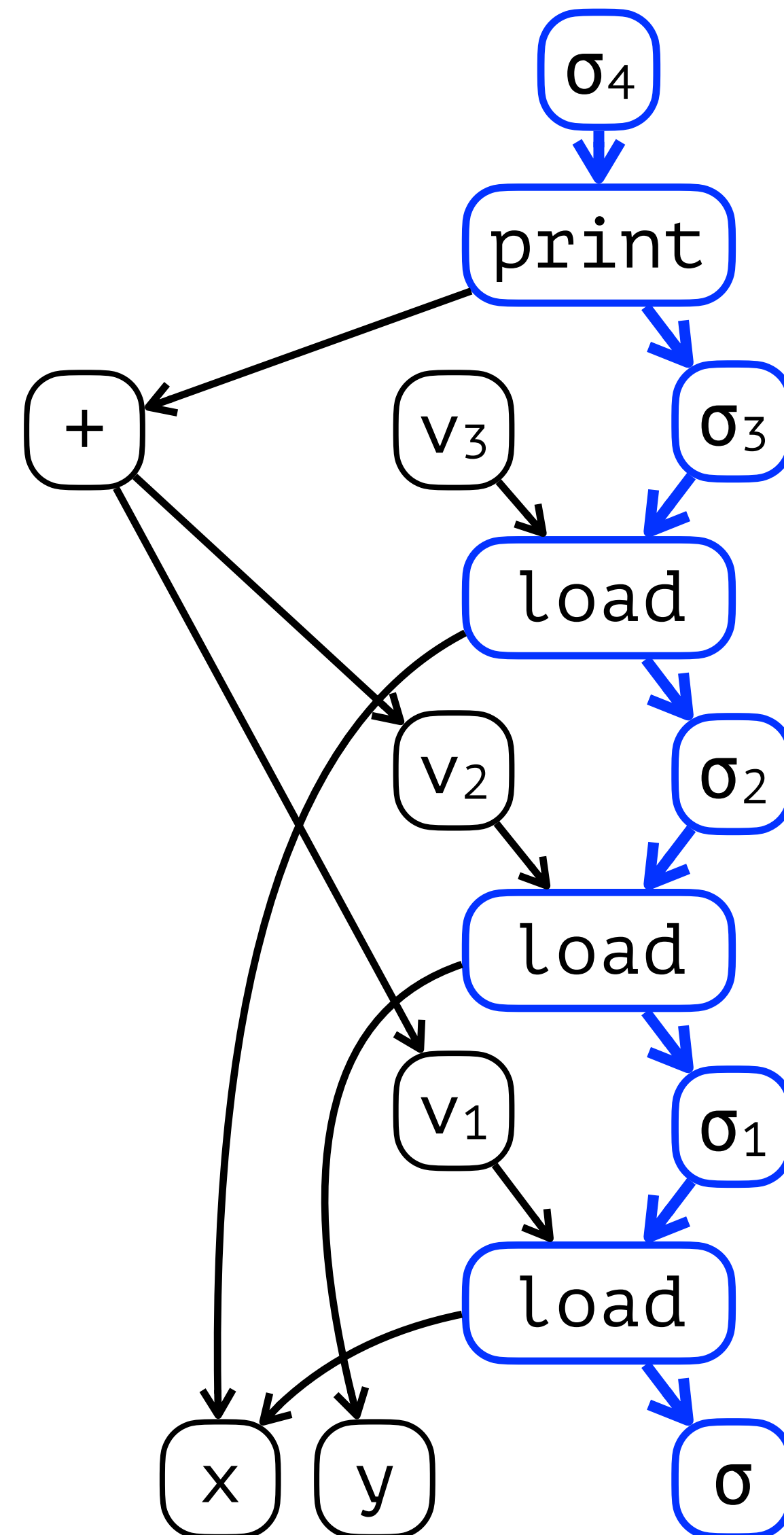
**Group effectful terms by the values they compute**

$$(v_1, \sigma_1) = \text{load}(x)$$
$$(v_2, \sigma_2) = \text{load}(y)$$
$$(v_3, \sigma_3) = \text{load}(x)$$
$$\sigma_4 = \text{print}(v_1 + v_2)$$

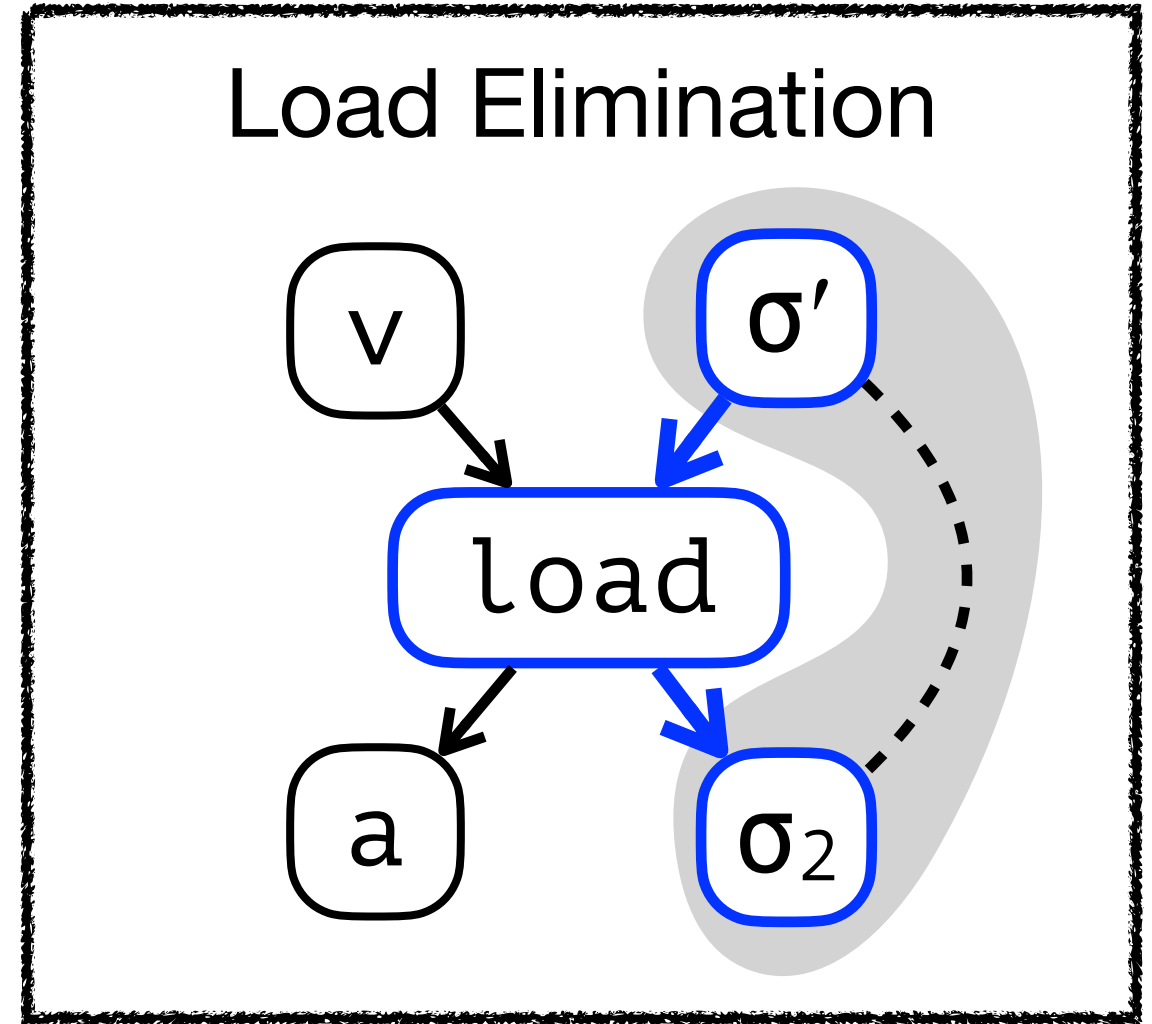
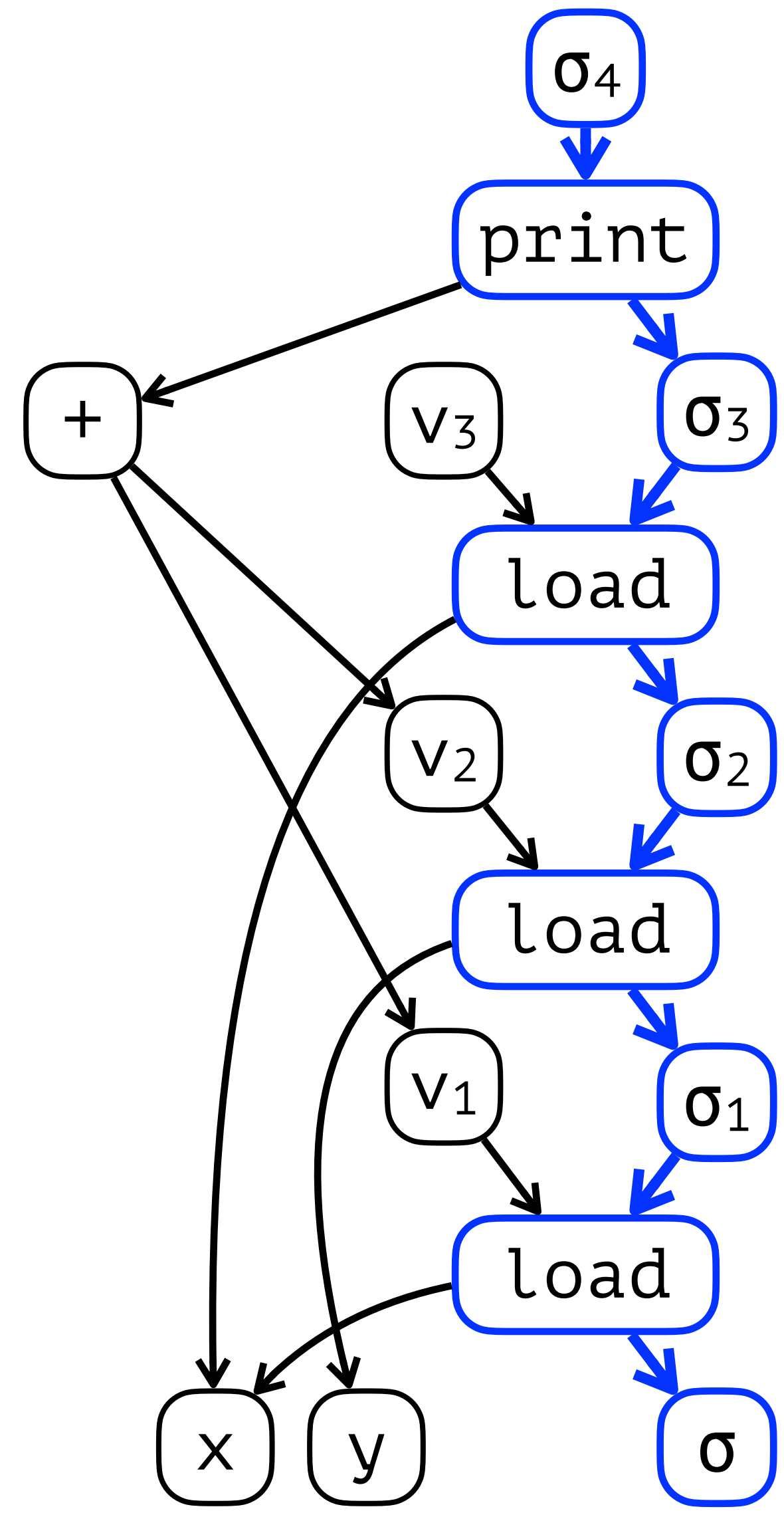
$$(v_1, \sigma_1) = \text{load}(x)$$

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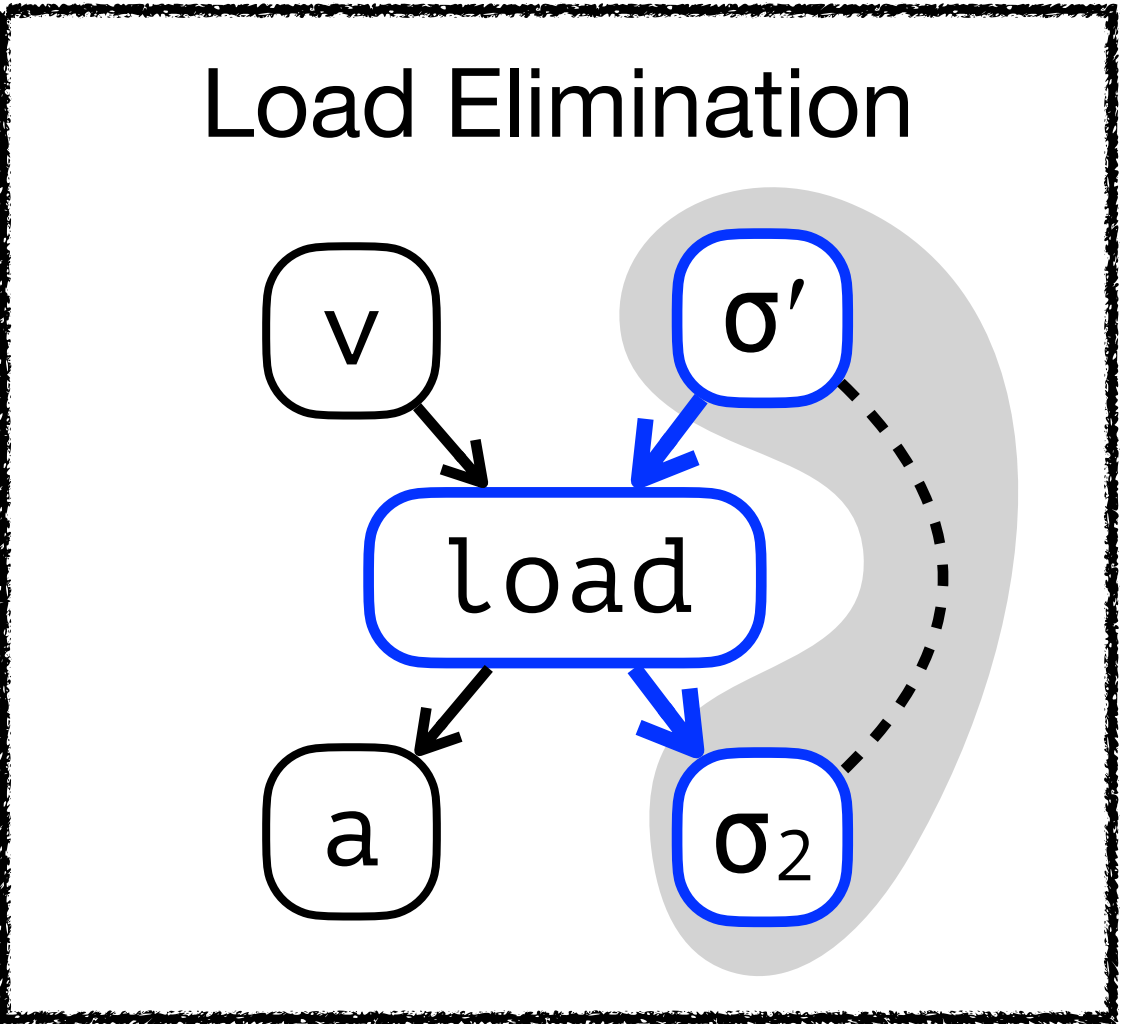
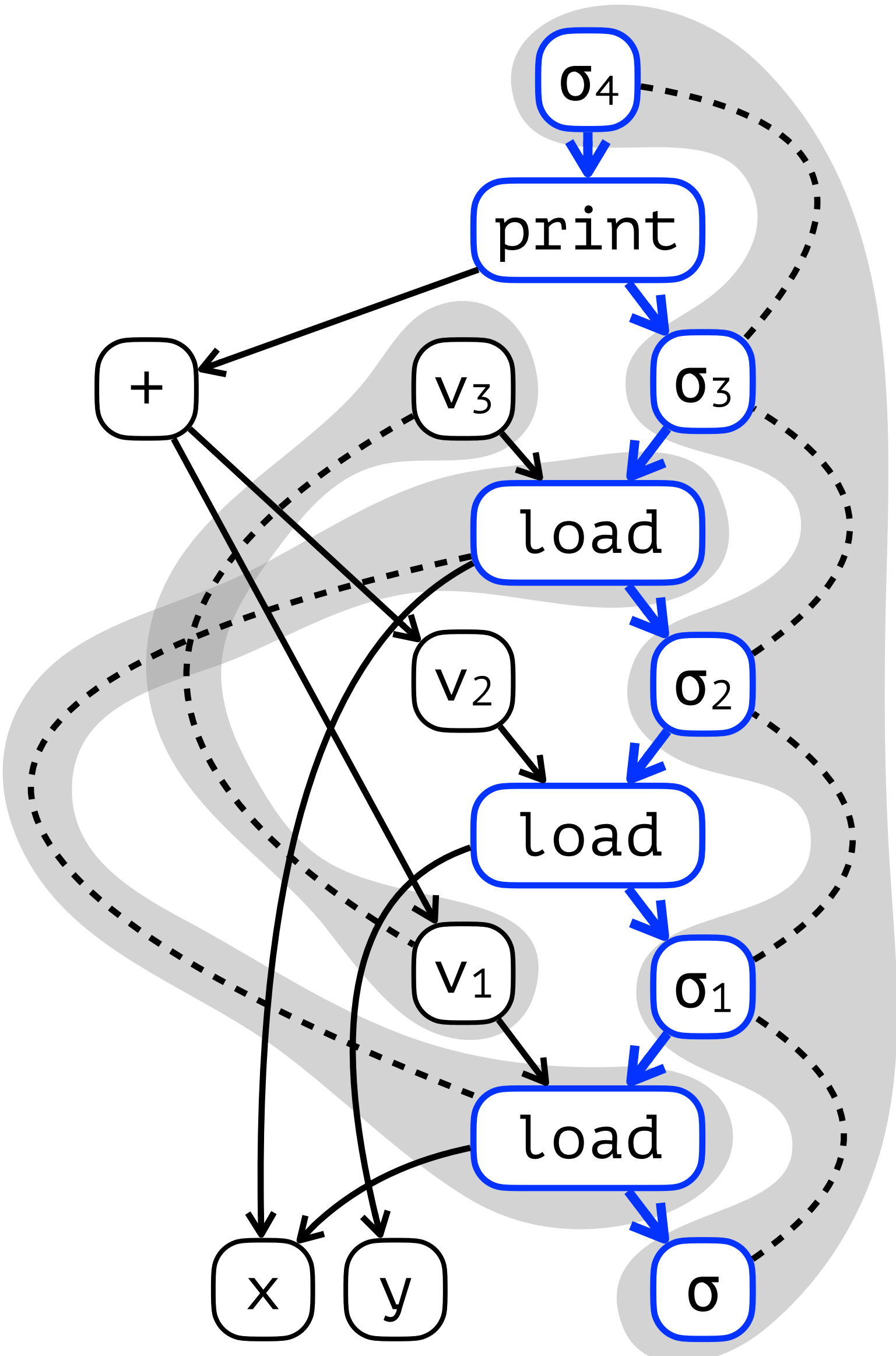
$$(v_3, \sigma_3) = \text{load}(x)$$

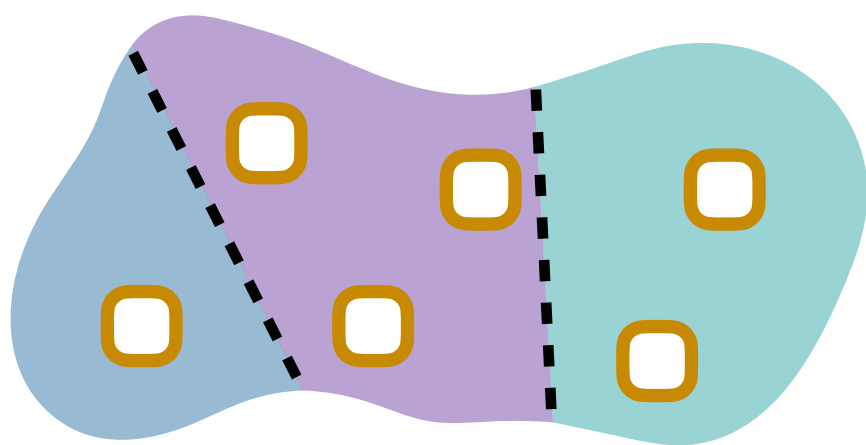
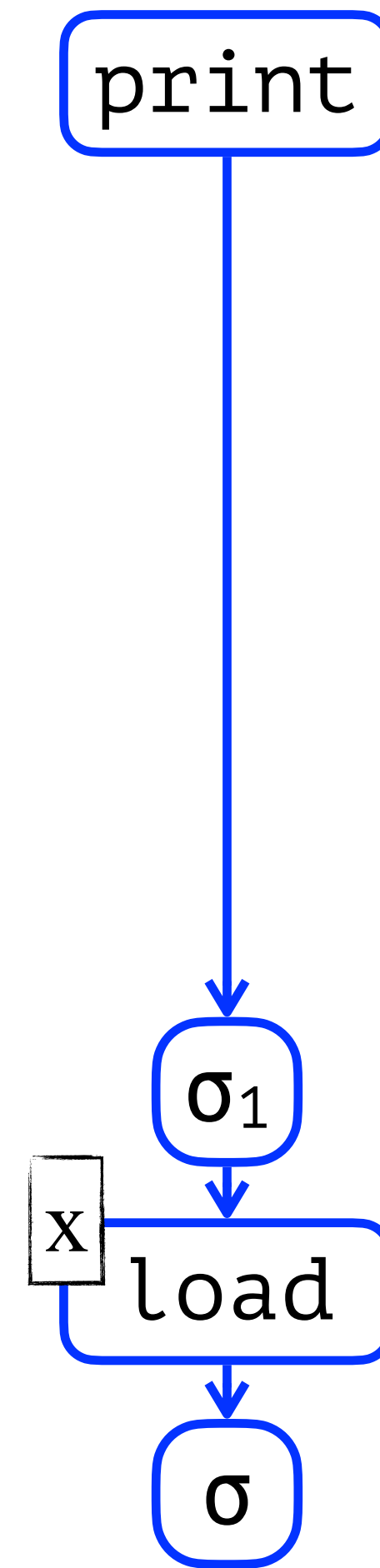
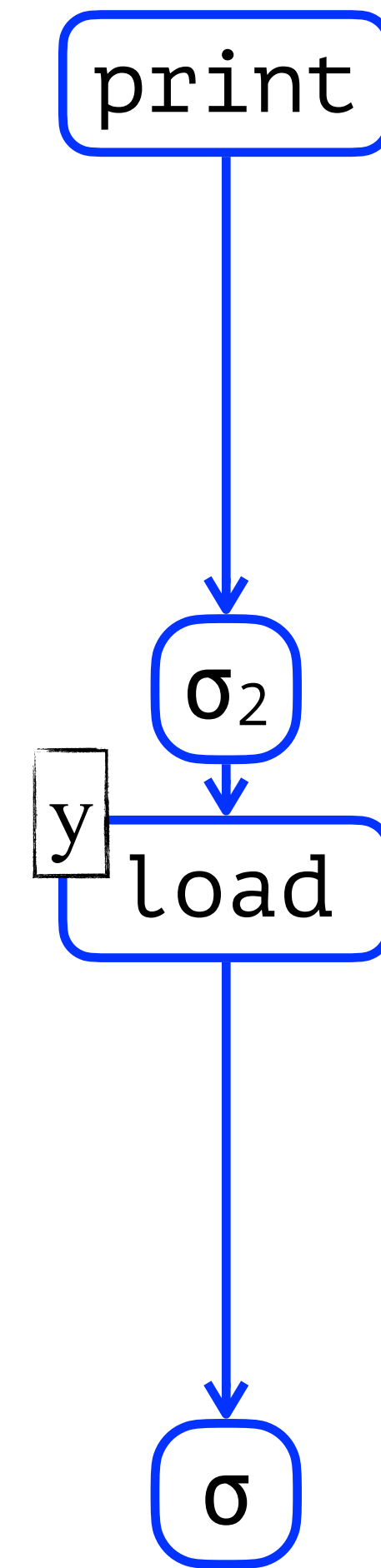
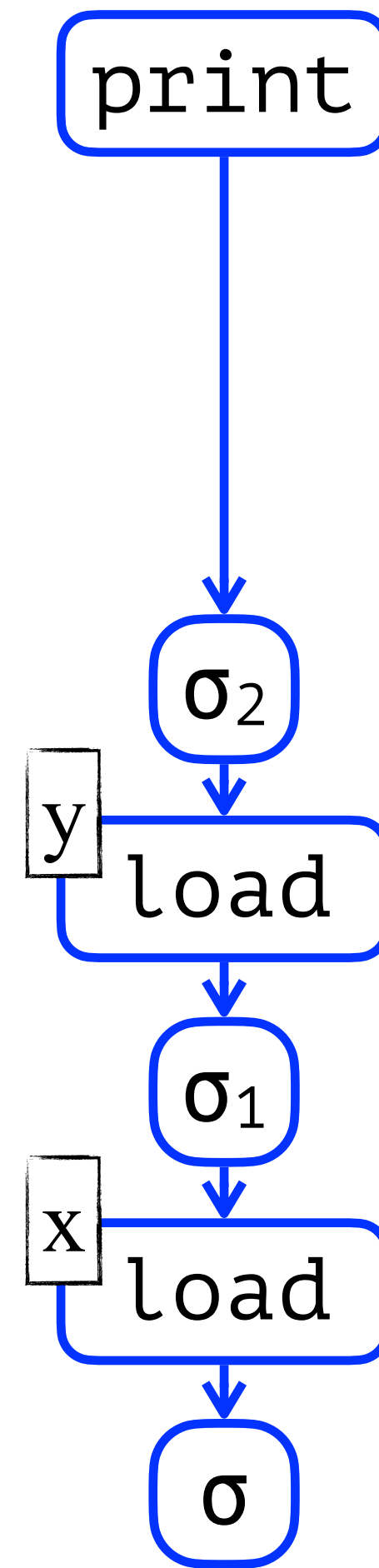
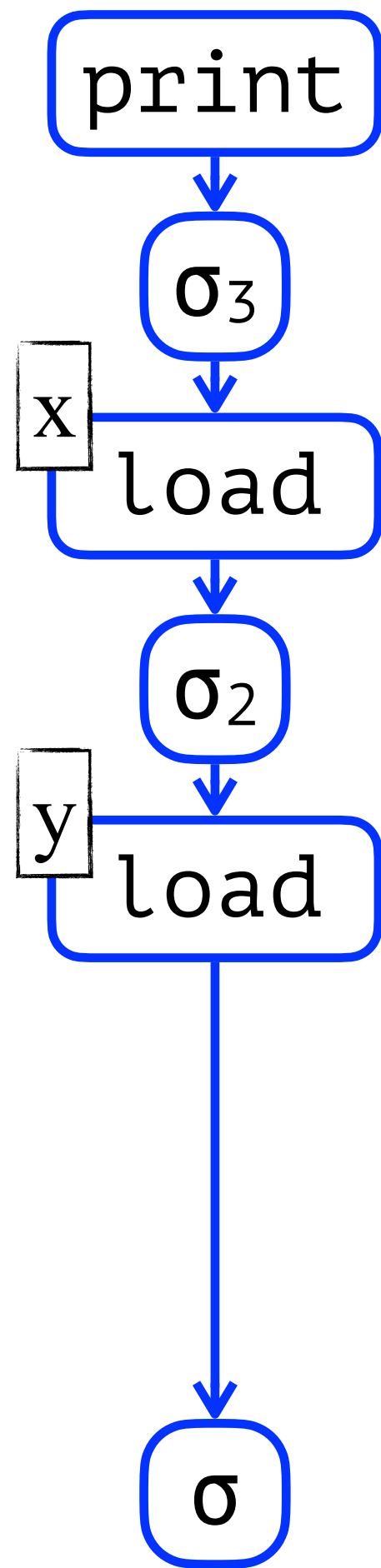
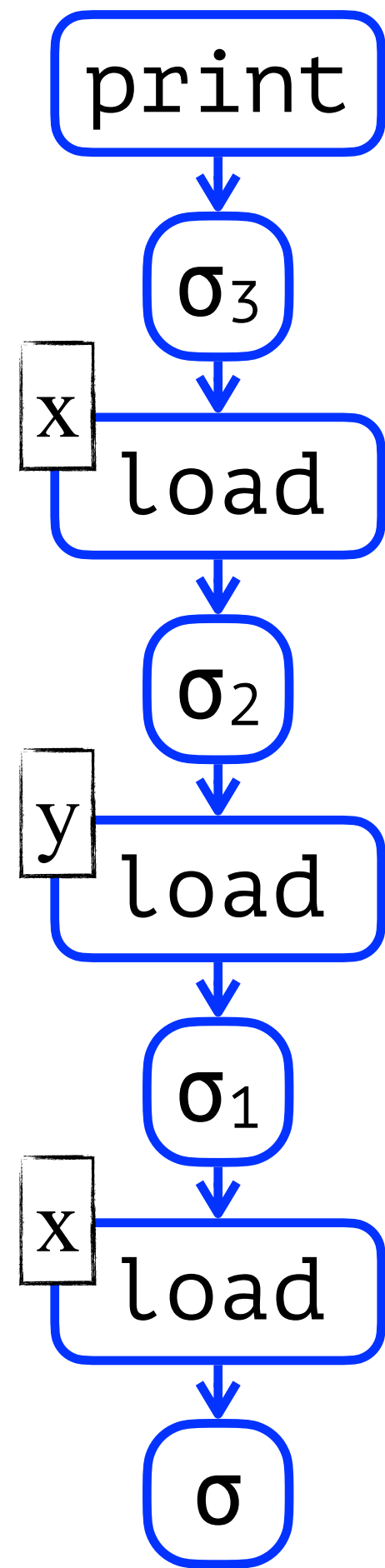
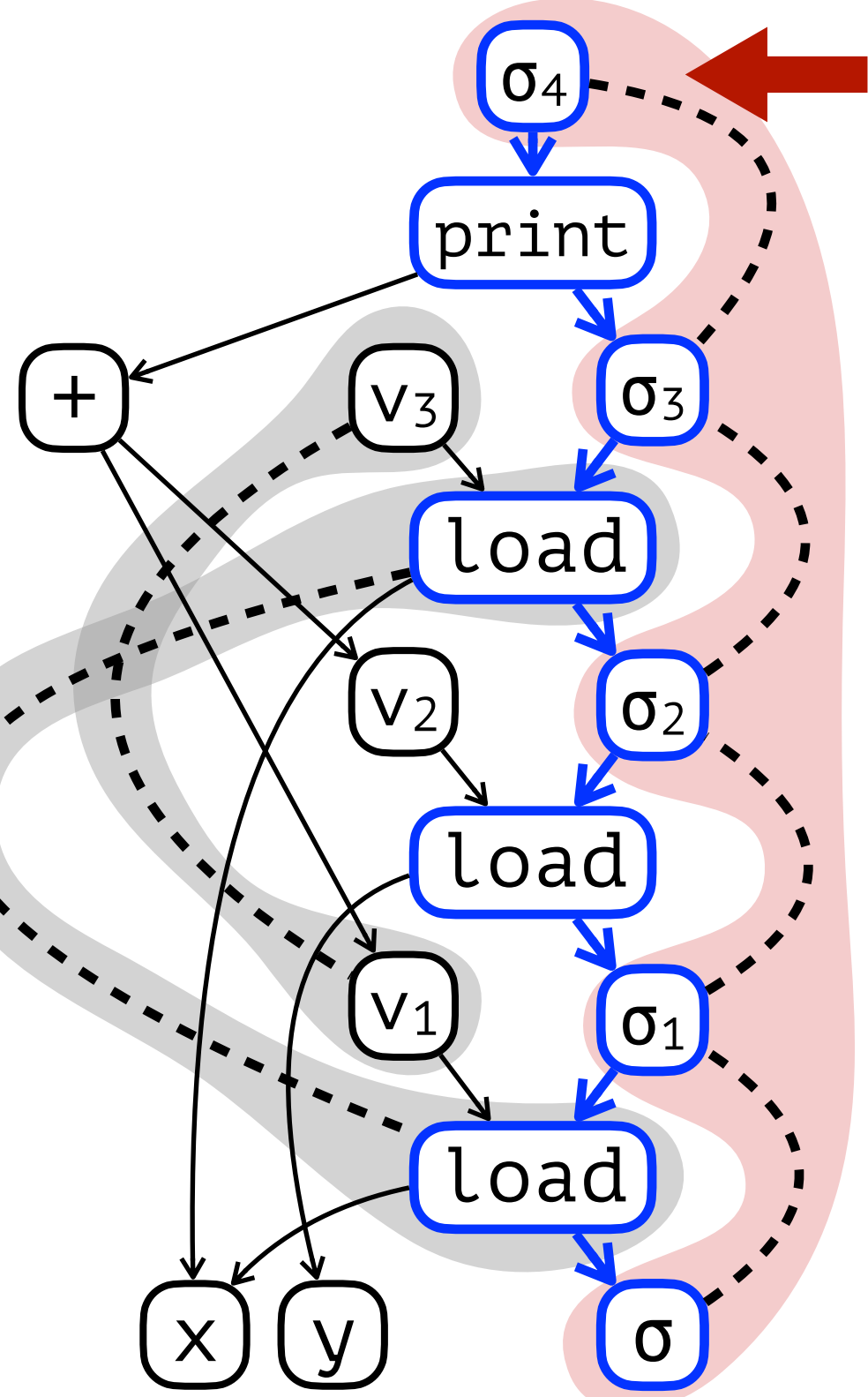
$$\sigma_4 = \text{print}(v_1 + v_2)$$


$(v_1, \sigma_1) = \text{load}(x)$   
 $(v_2, \sigma_2) = \text{load}(y)$   
 $(v_3, \sigma_3) = \text{load}(x)$   
 $\sigma_4 = \text{print}(v_1 + v_2)$

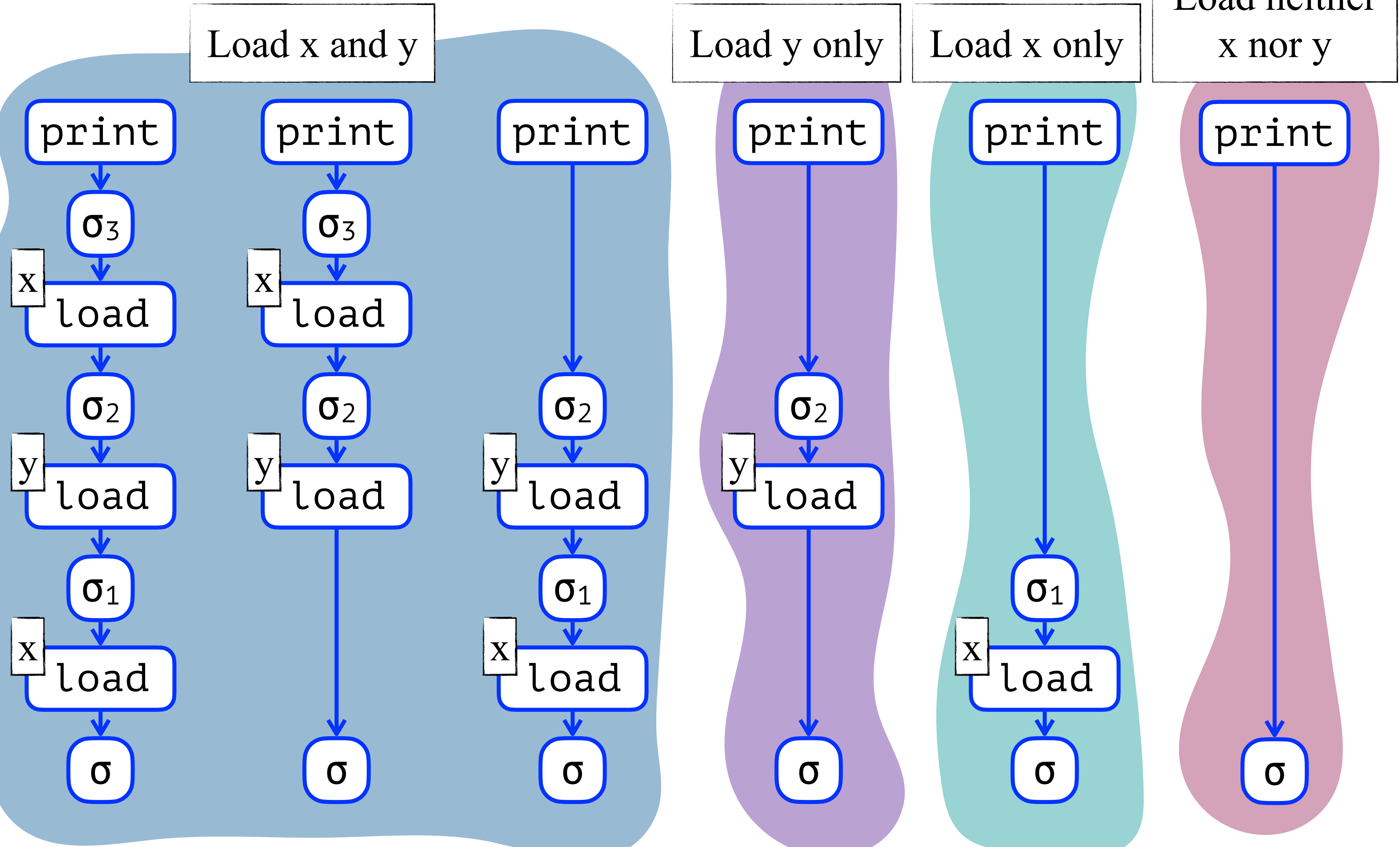
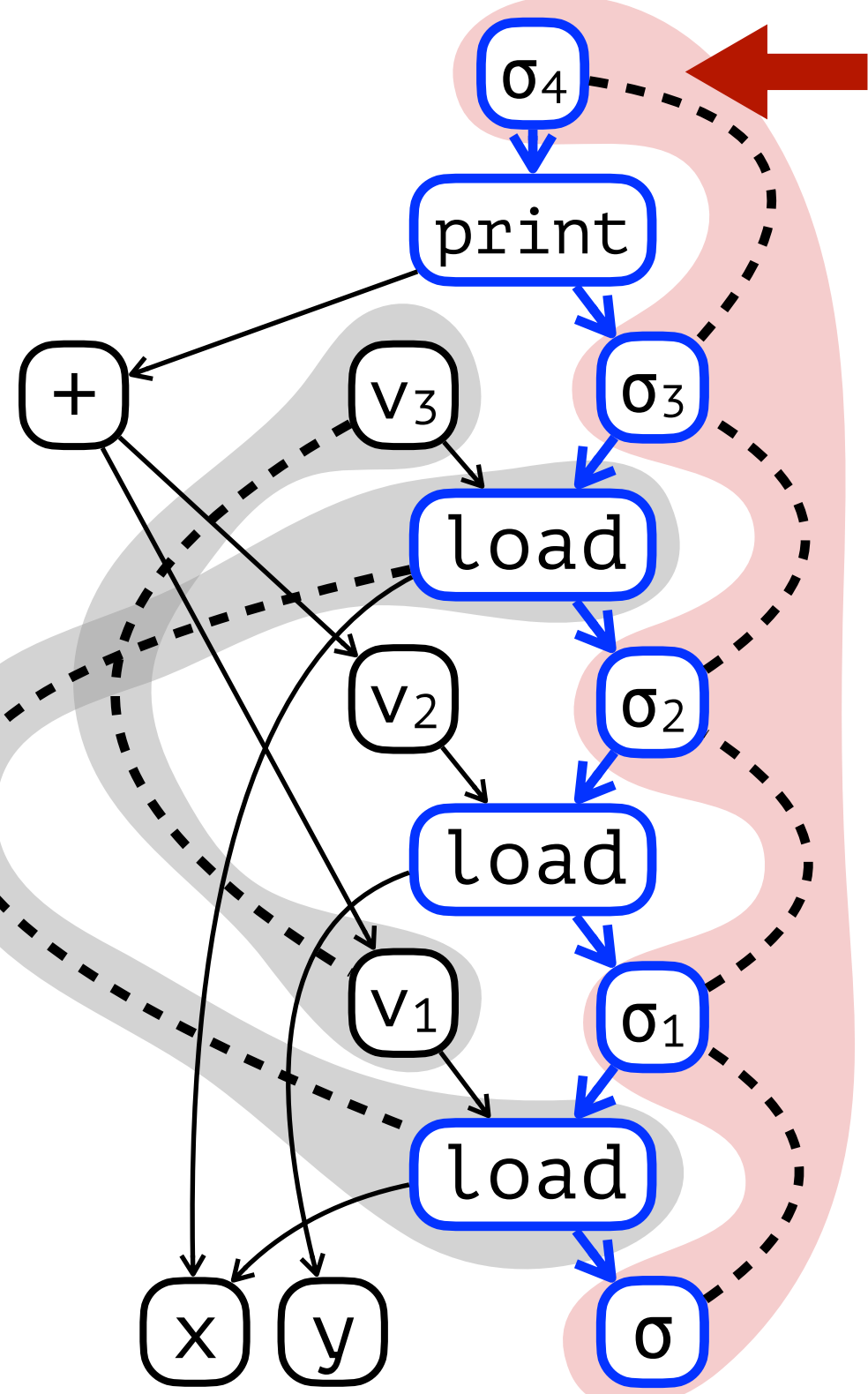


$(v_1, \sigma_1) = \text{load}(x)$   
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 $(v_3, \sigma_3) = \text{load}(x)$   
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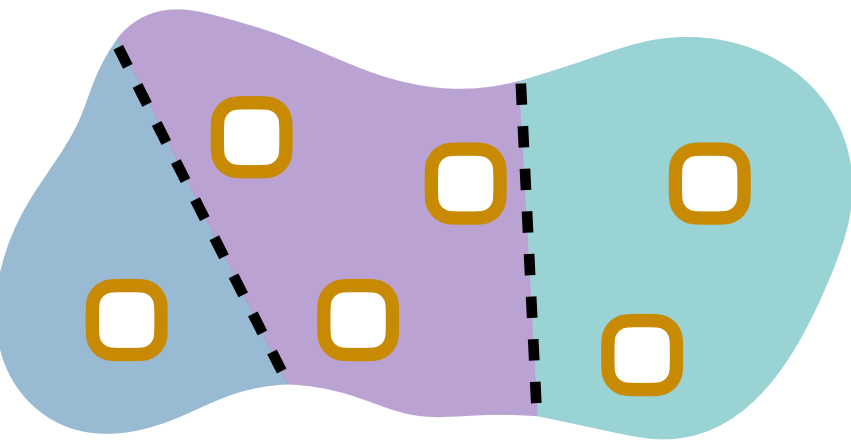
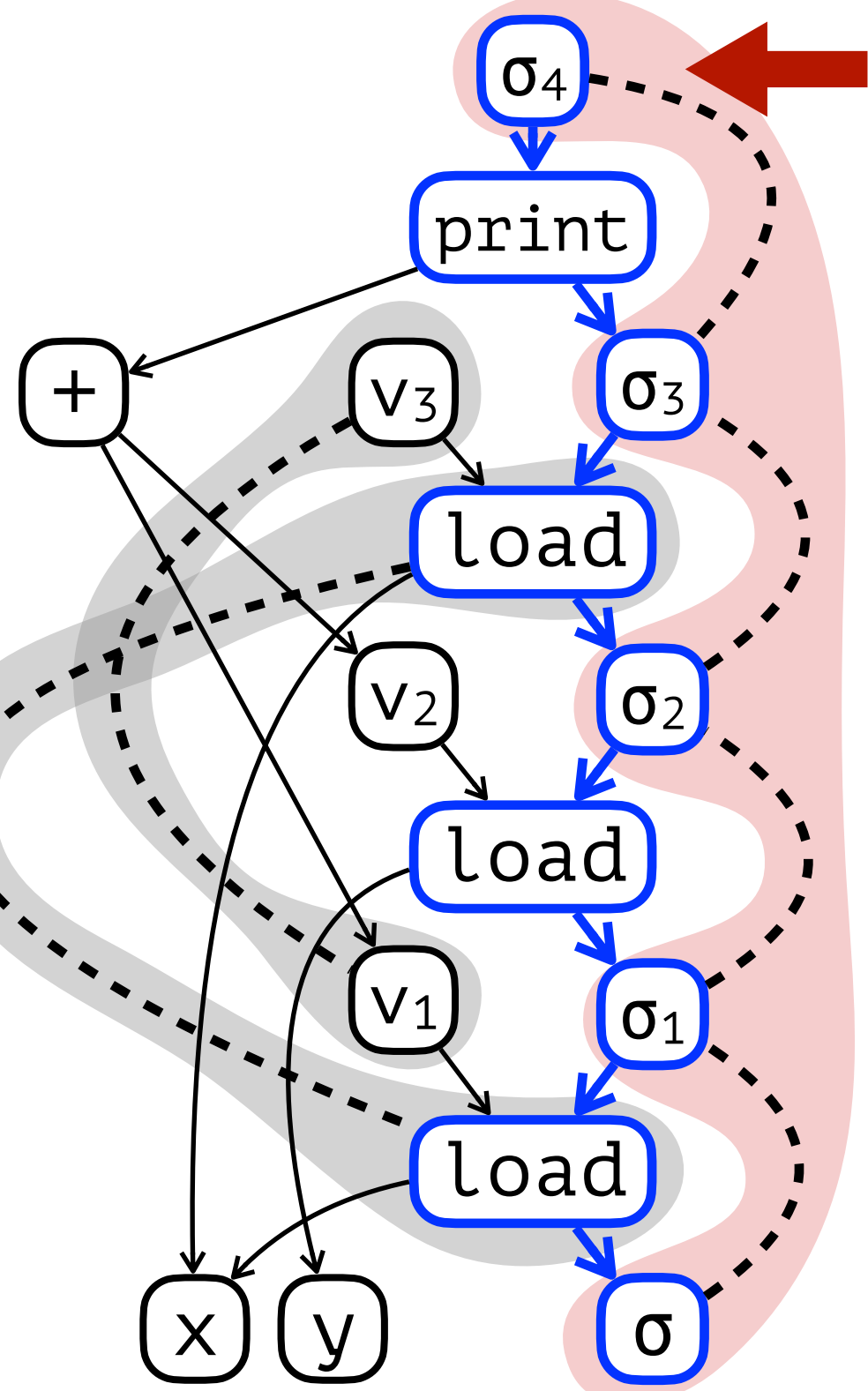


Group effectful terms by the values they compute

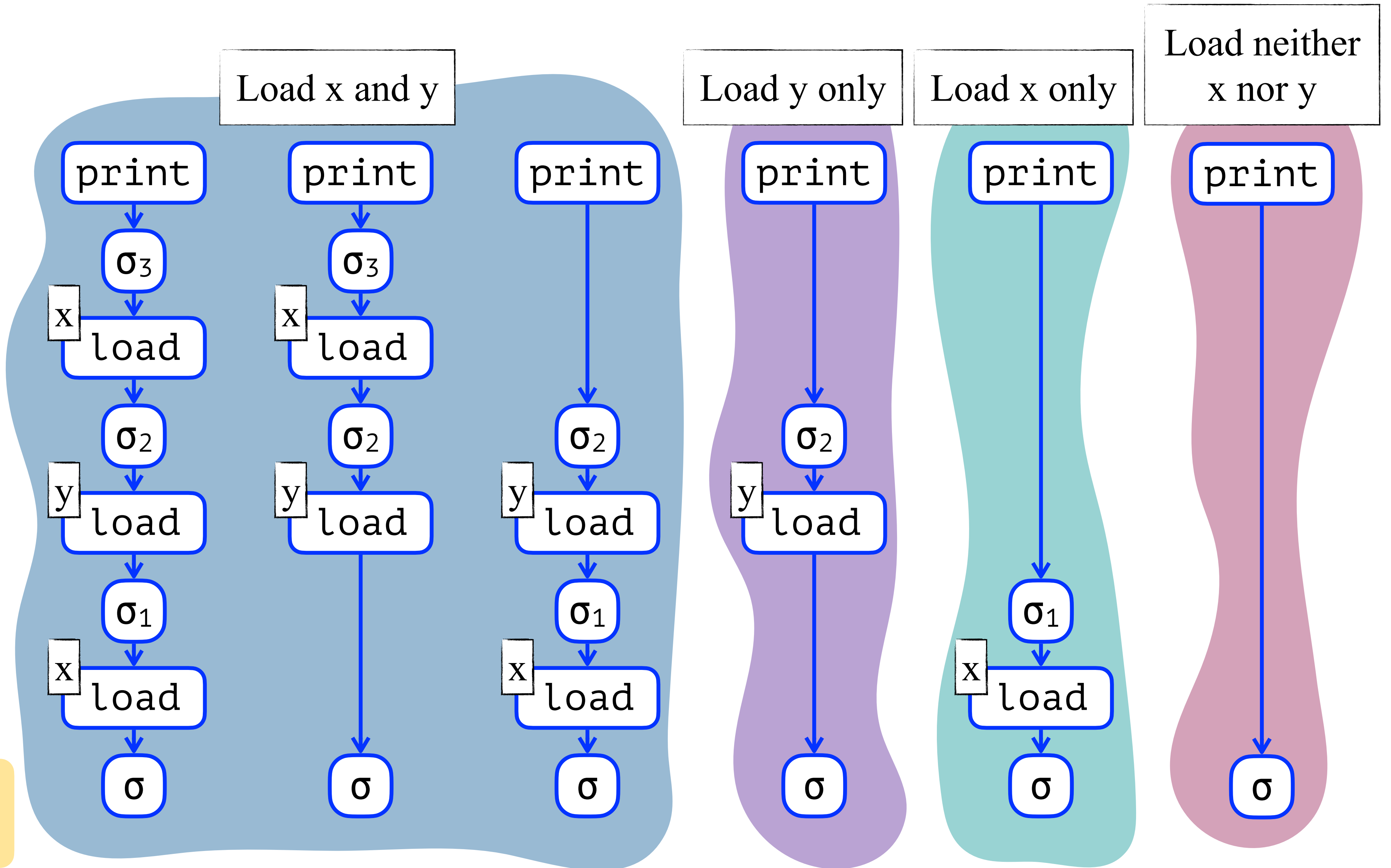


Group effectful terms by the values they compute

# Terms are interchangeable within each partition

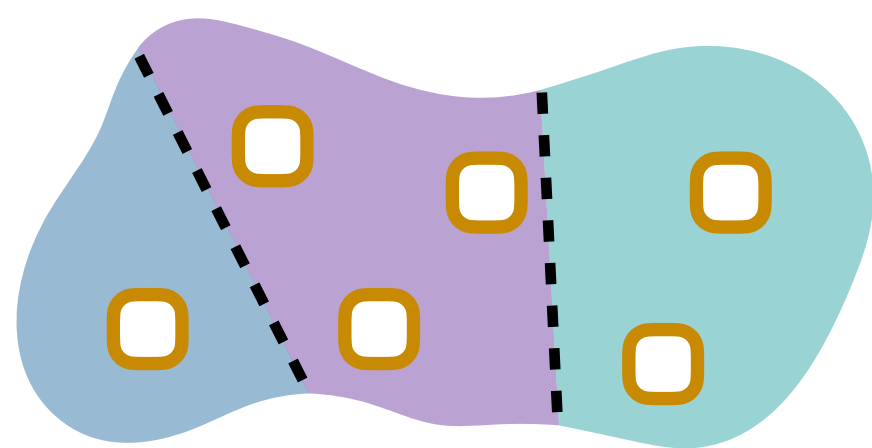
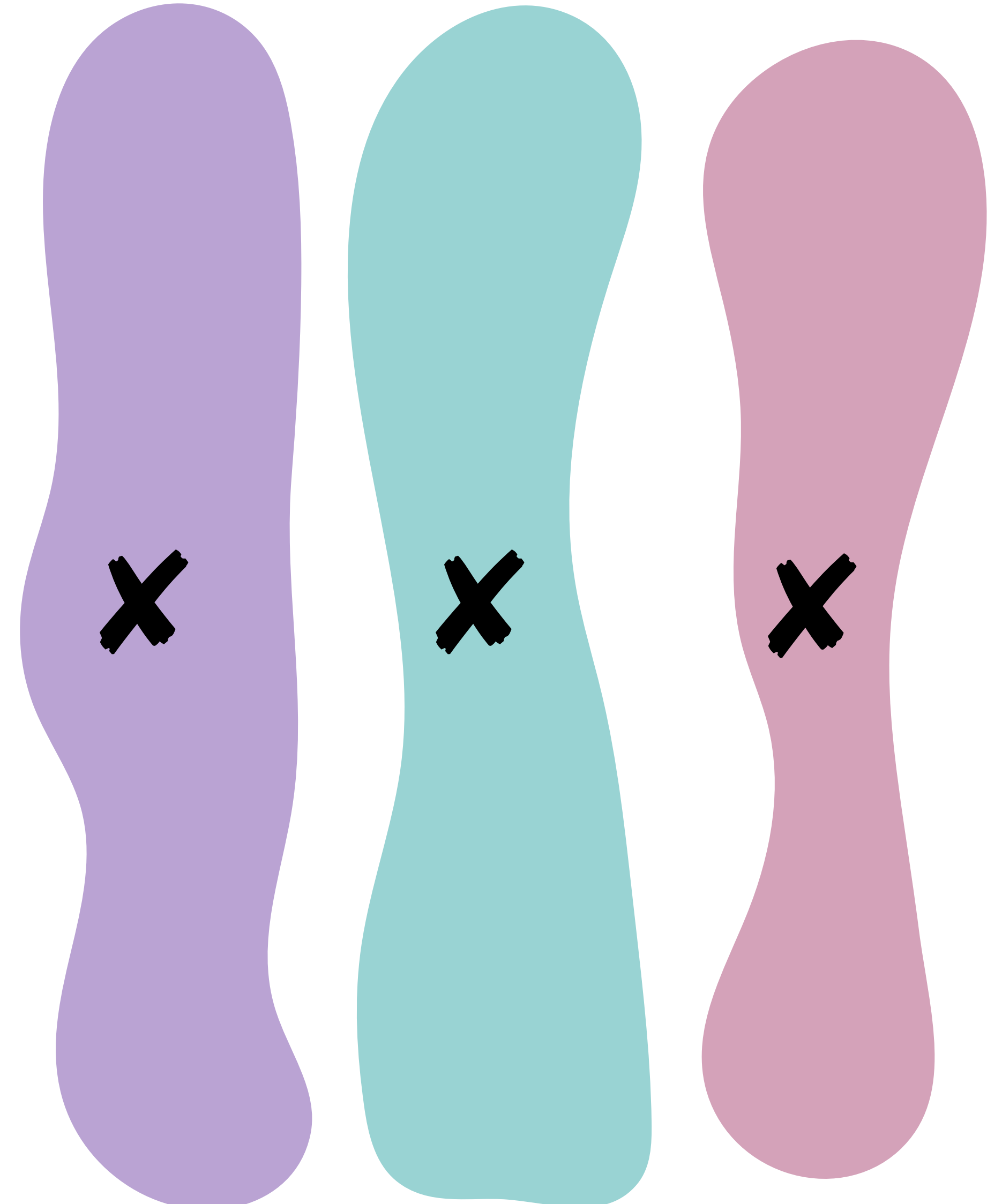
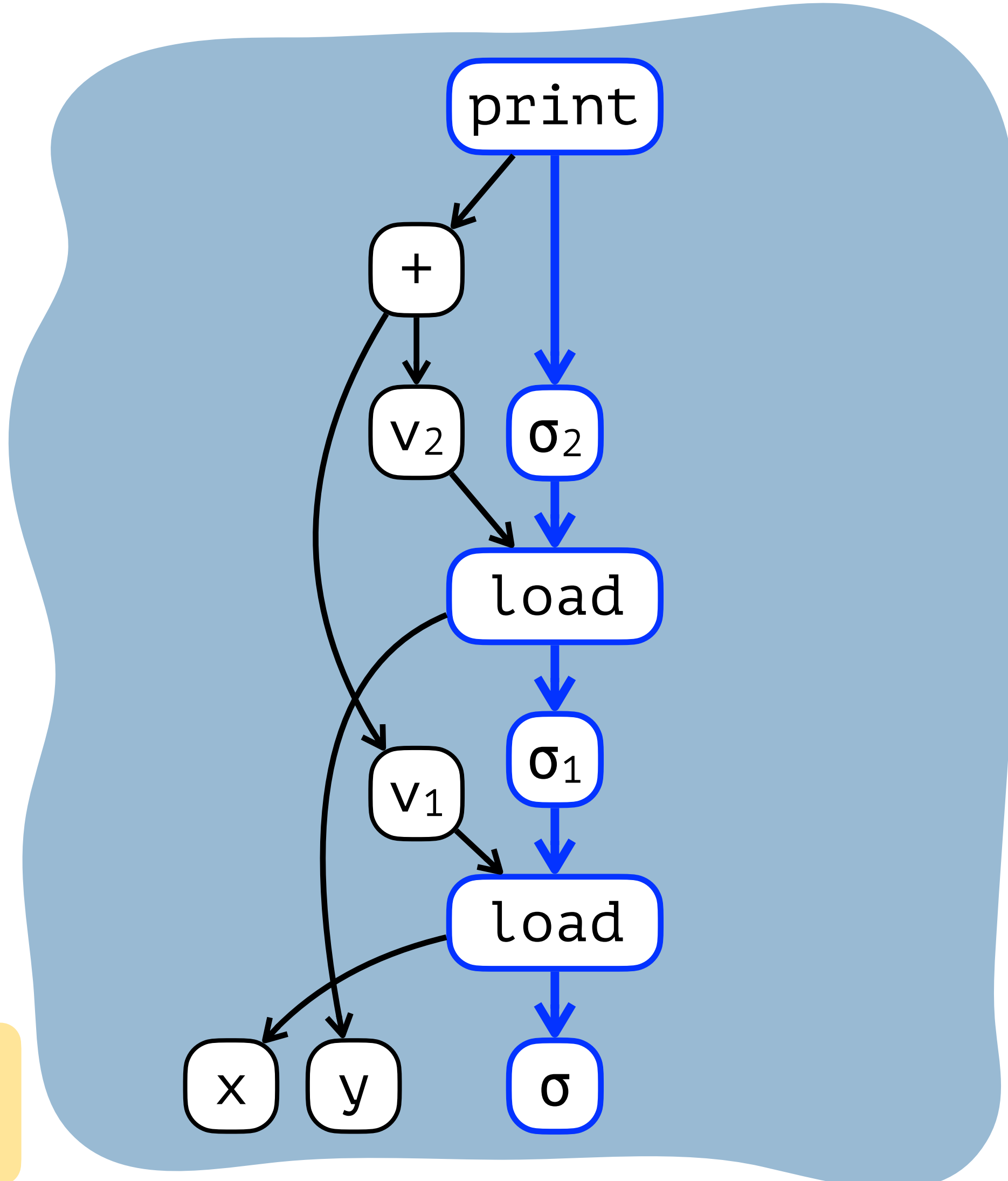
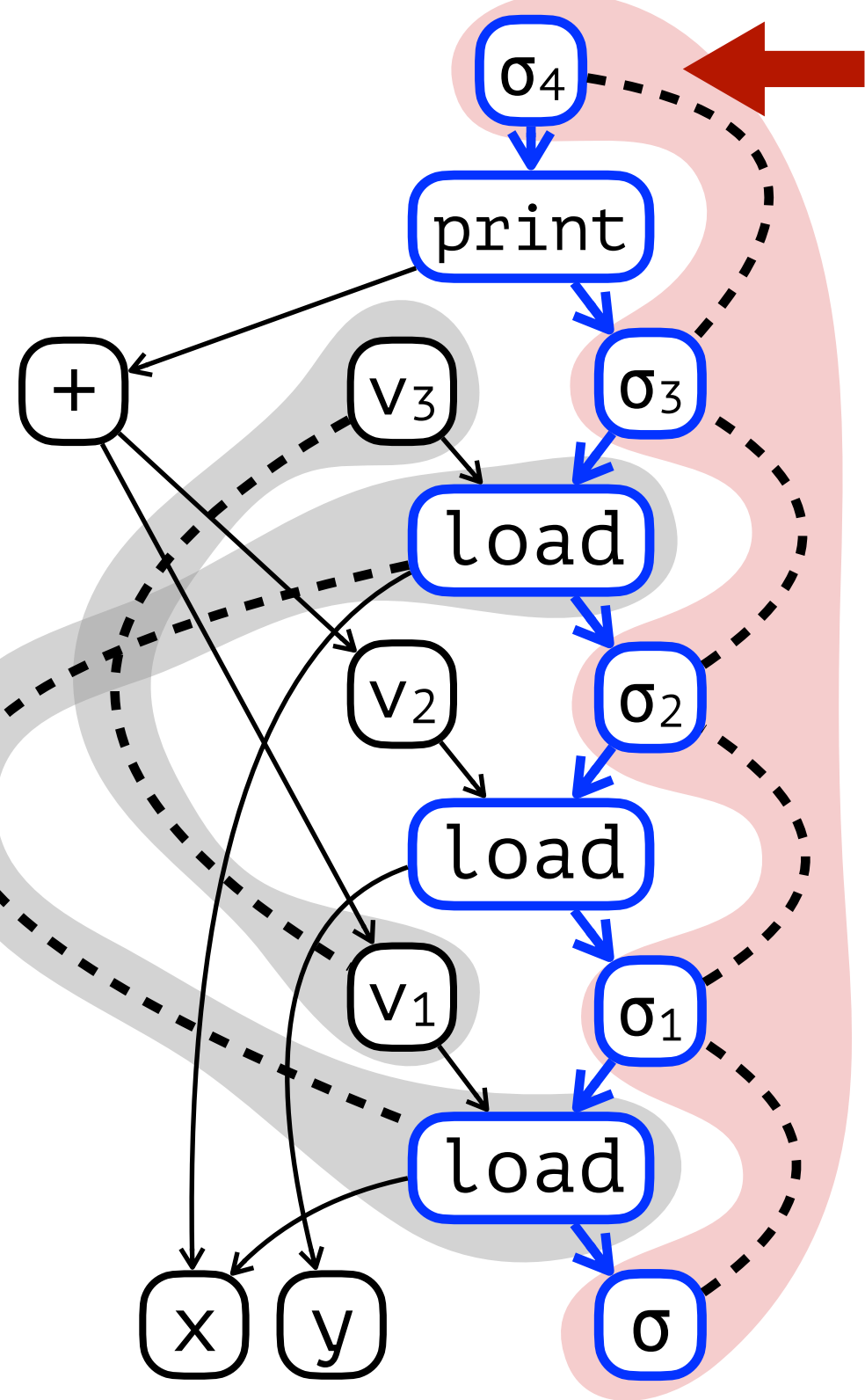


Group effectful terms by the values they compute



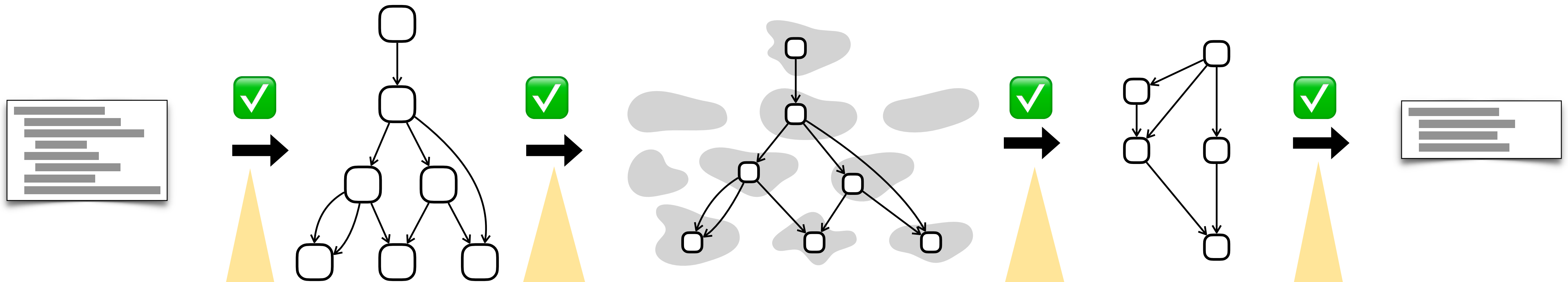
# Terms are interchangeable within each partition

Find one low-cost extraction for each



Group effectful terms by the values they compute

# Effectful Program Optimization with E-Graphs



Encode order of effects with explicit state values

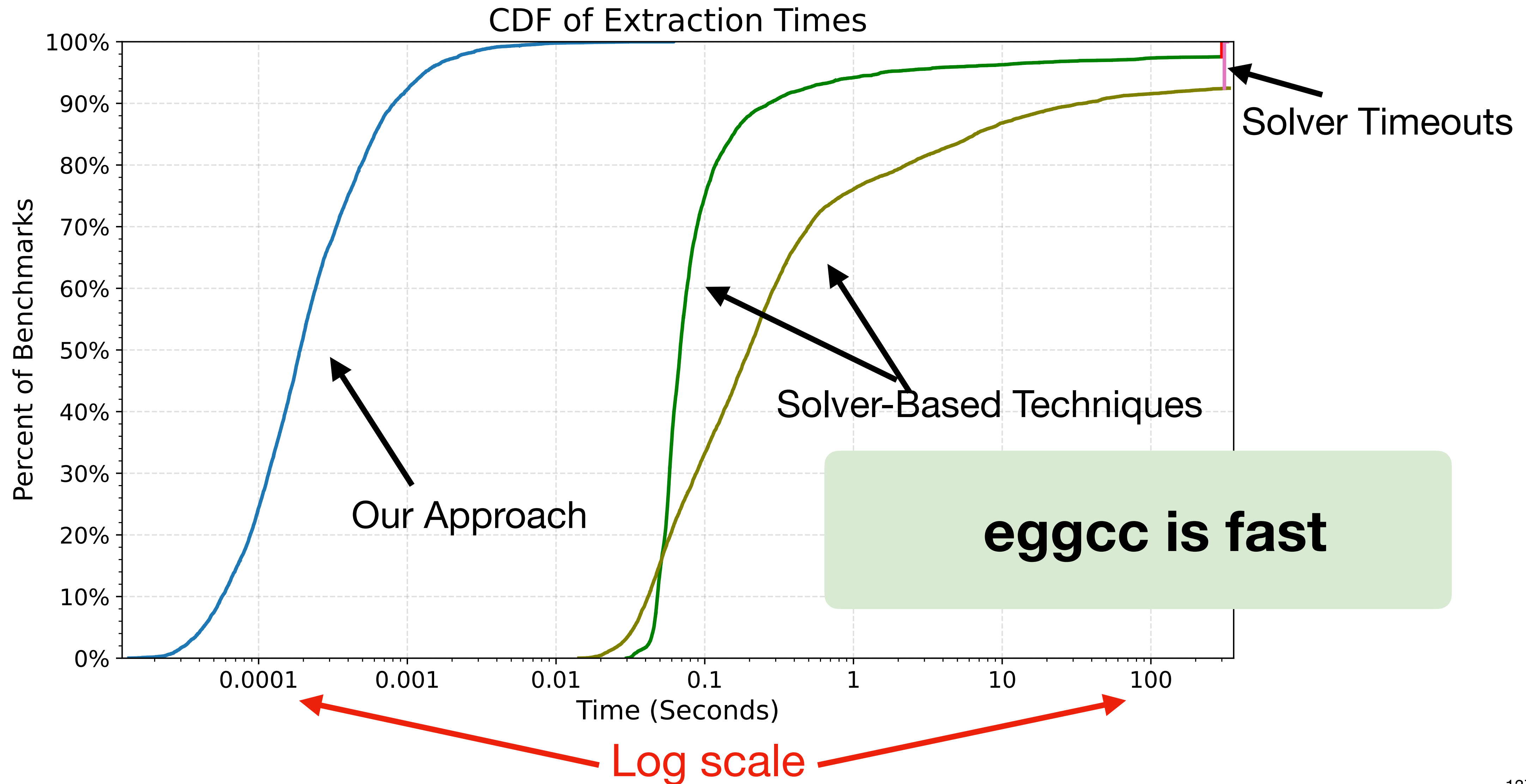
Relaxed equivalence relation for optimization

Effect-safe extraction under refined equivalence relation

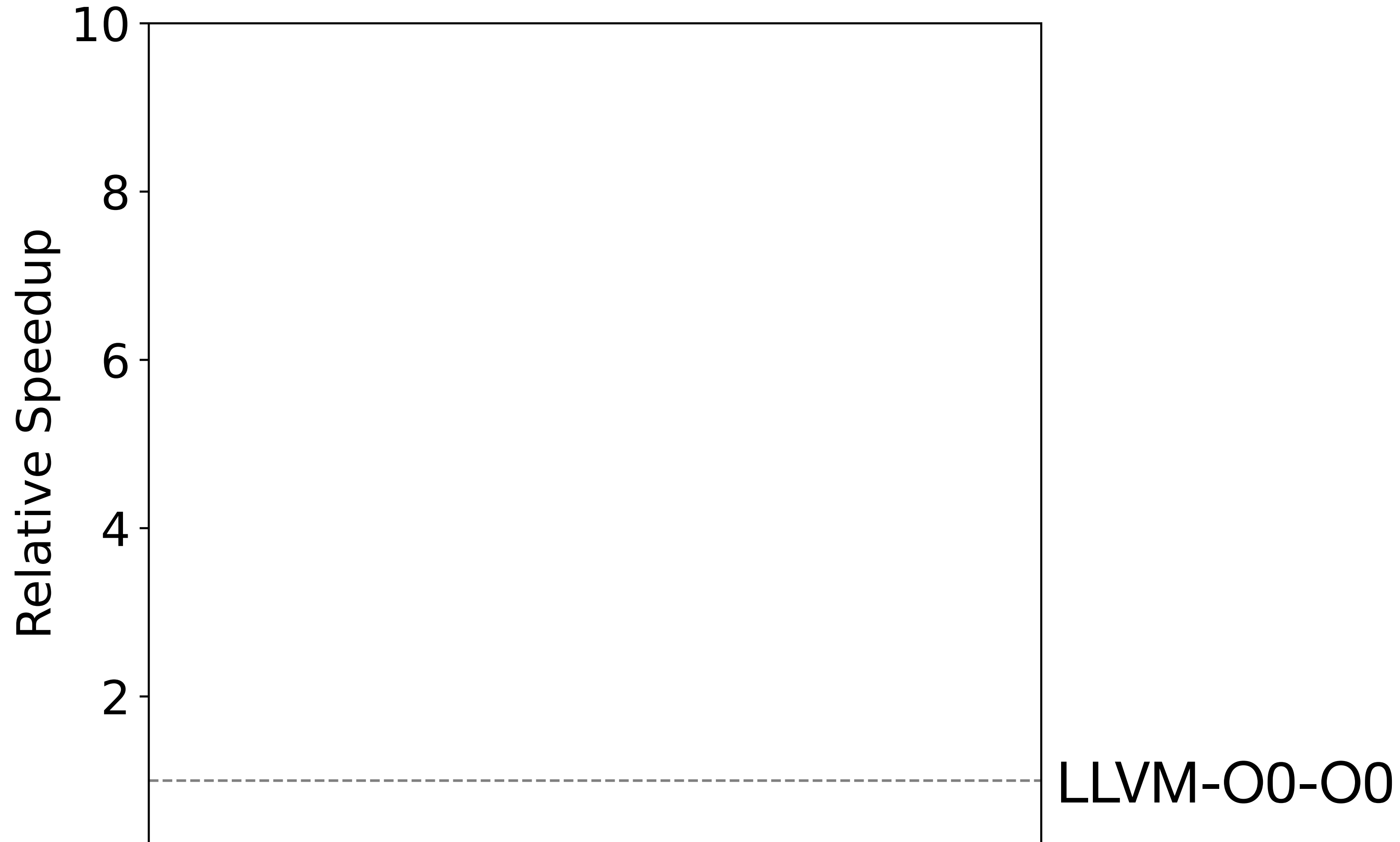
Reconstruction succeeds if effectful operations form a linear sequence

# The eggcc compiler

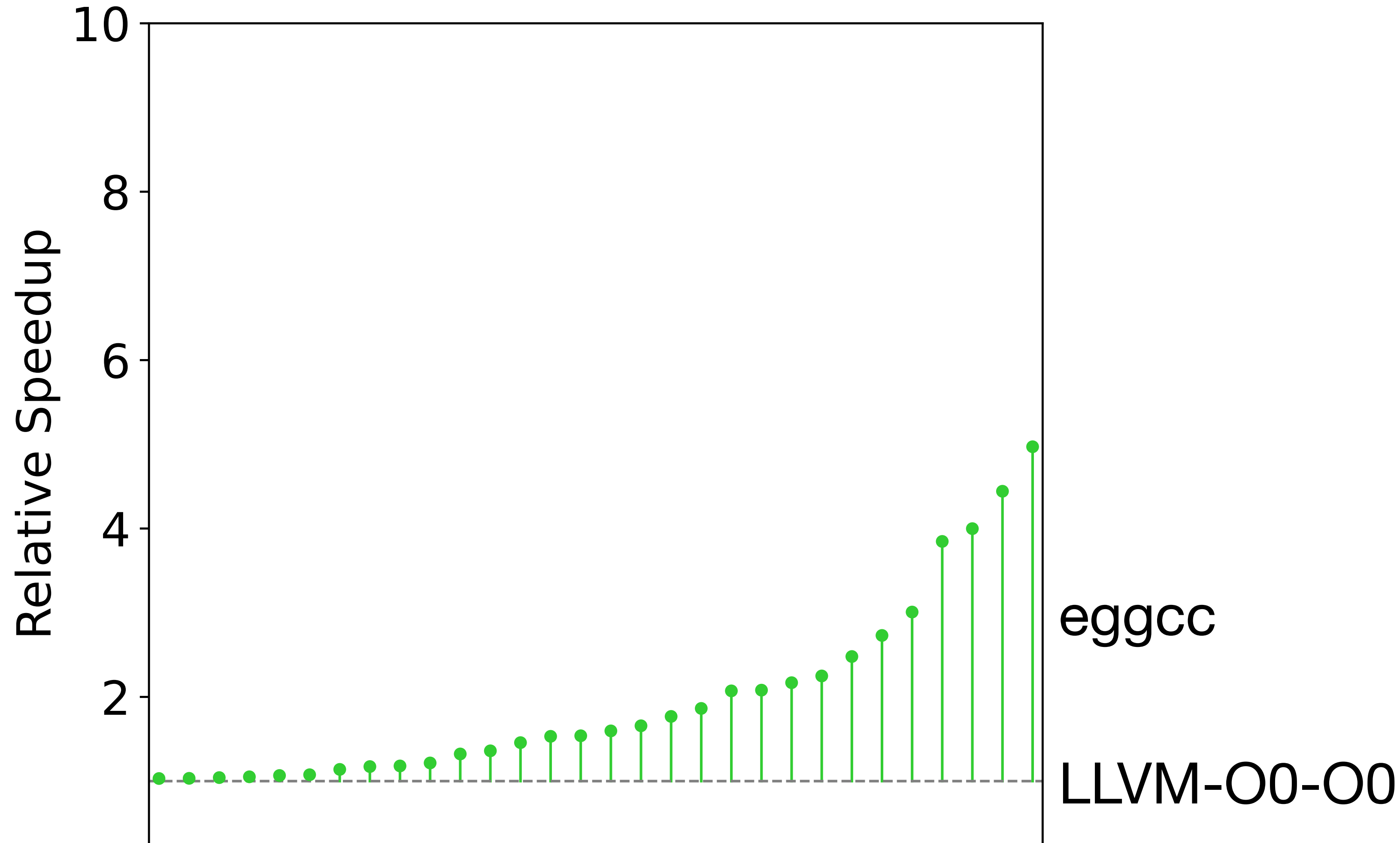
# Fast Effect-safe Extraction in Practice



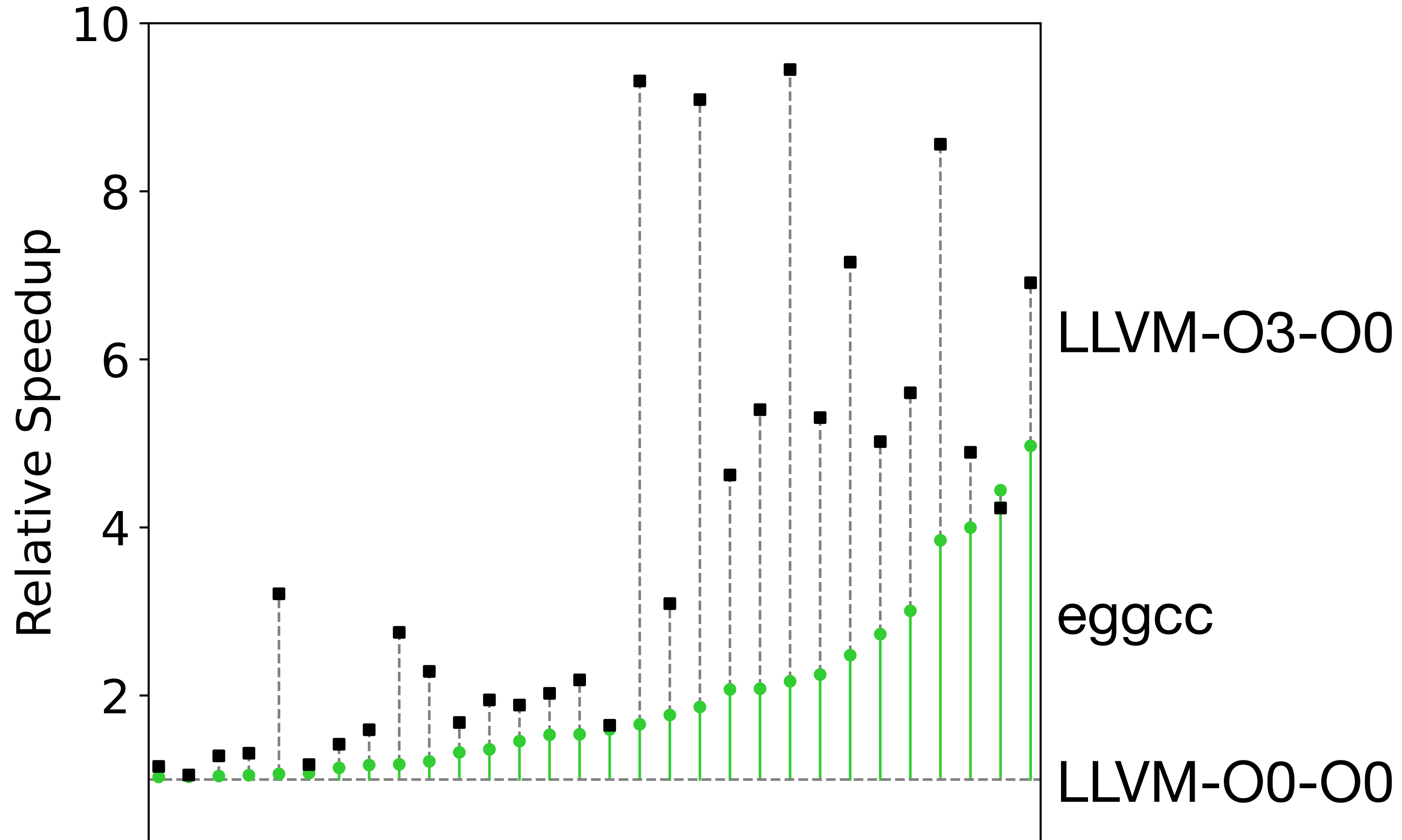
# Fast Effect-safe Extraction in Practice



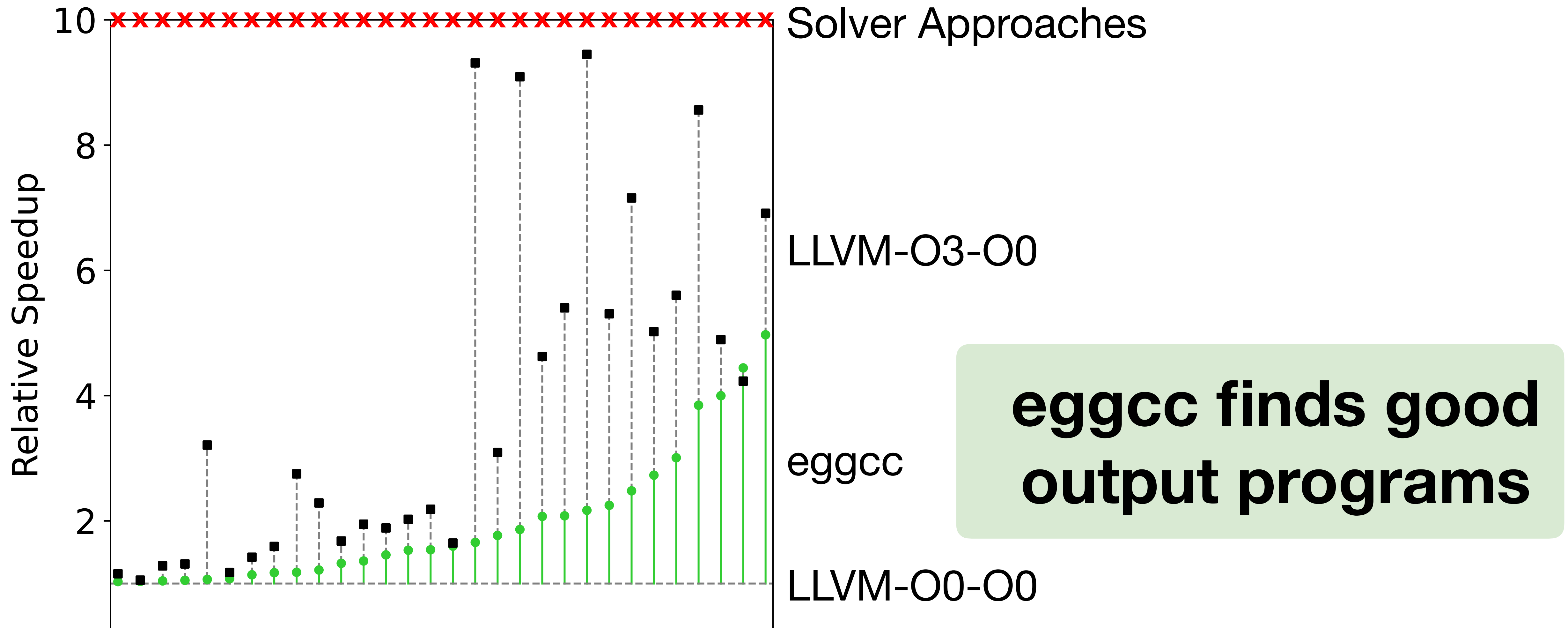
# Fast Effect-safe Extraction in Practice



# Fast Effect-safe Extraction in Practice

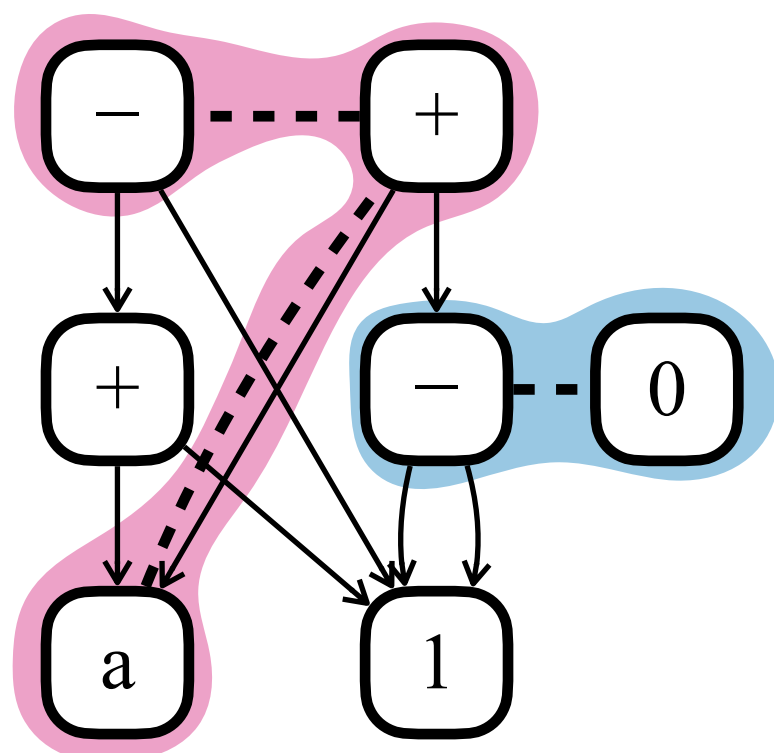


# Fast Effect-safe Extraction in Practice

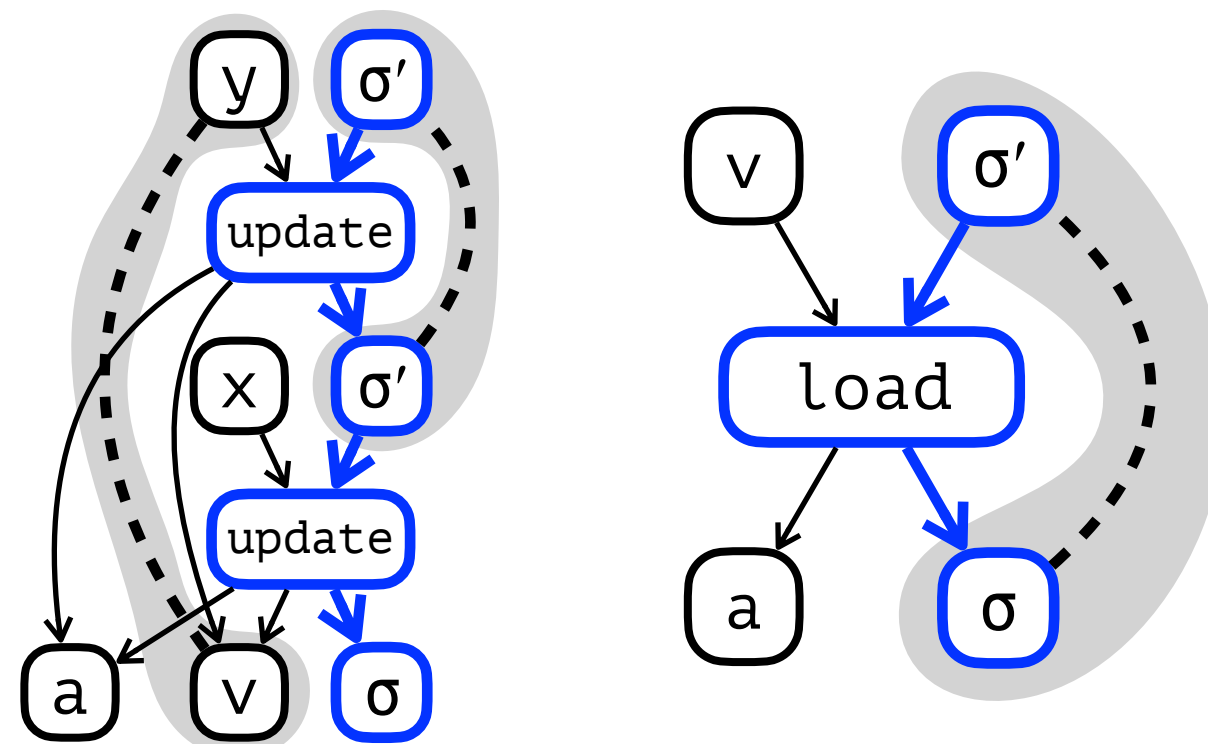


# Fast Effect-safe Extraction in Practice

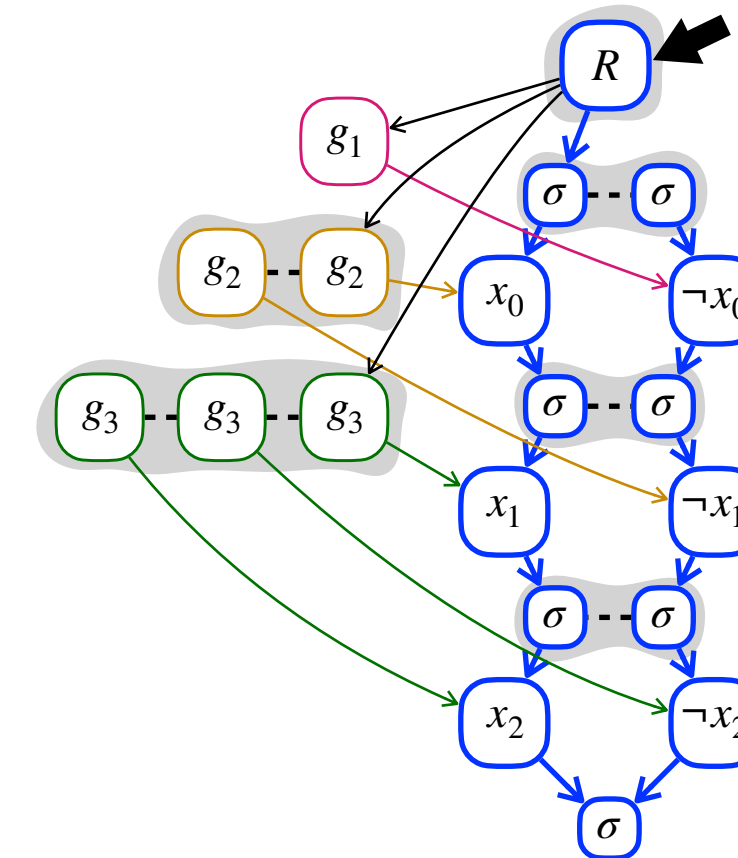
Rewrite non-destructively with e-graphs



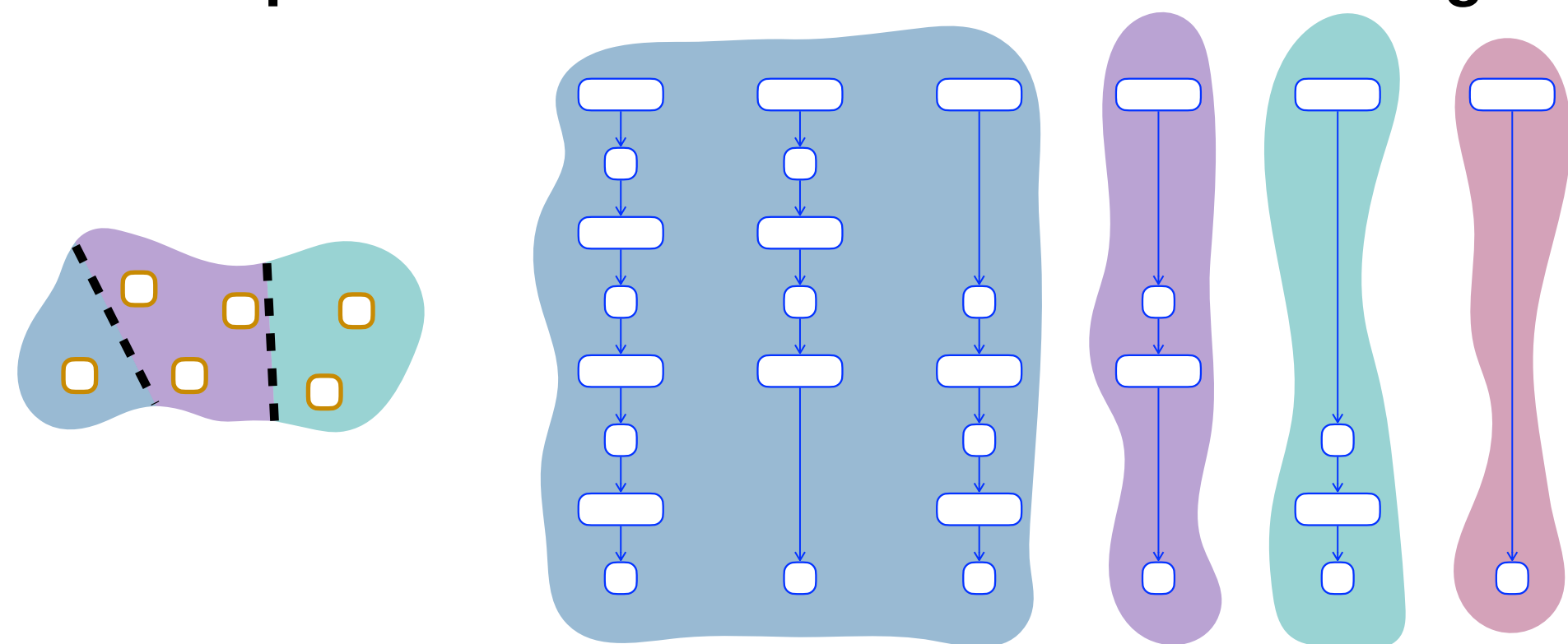
Relax equivalence relation to enable optimizations



Effect-safe extraction is NP-Complete



Refine equivalence relation to recover interchangeability



Empirically fast, high-quality extraction

